

Lecture 5:

Texture Mapping

Computer Graphics and Imaging
UC Berkeley CS184/284A

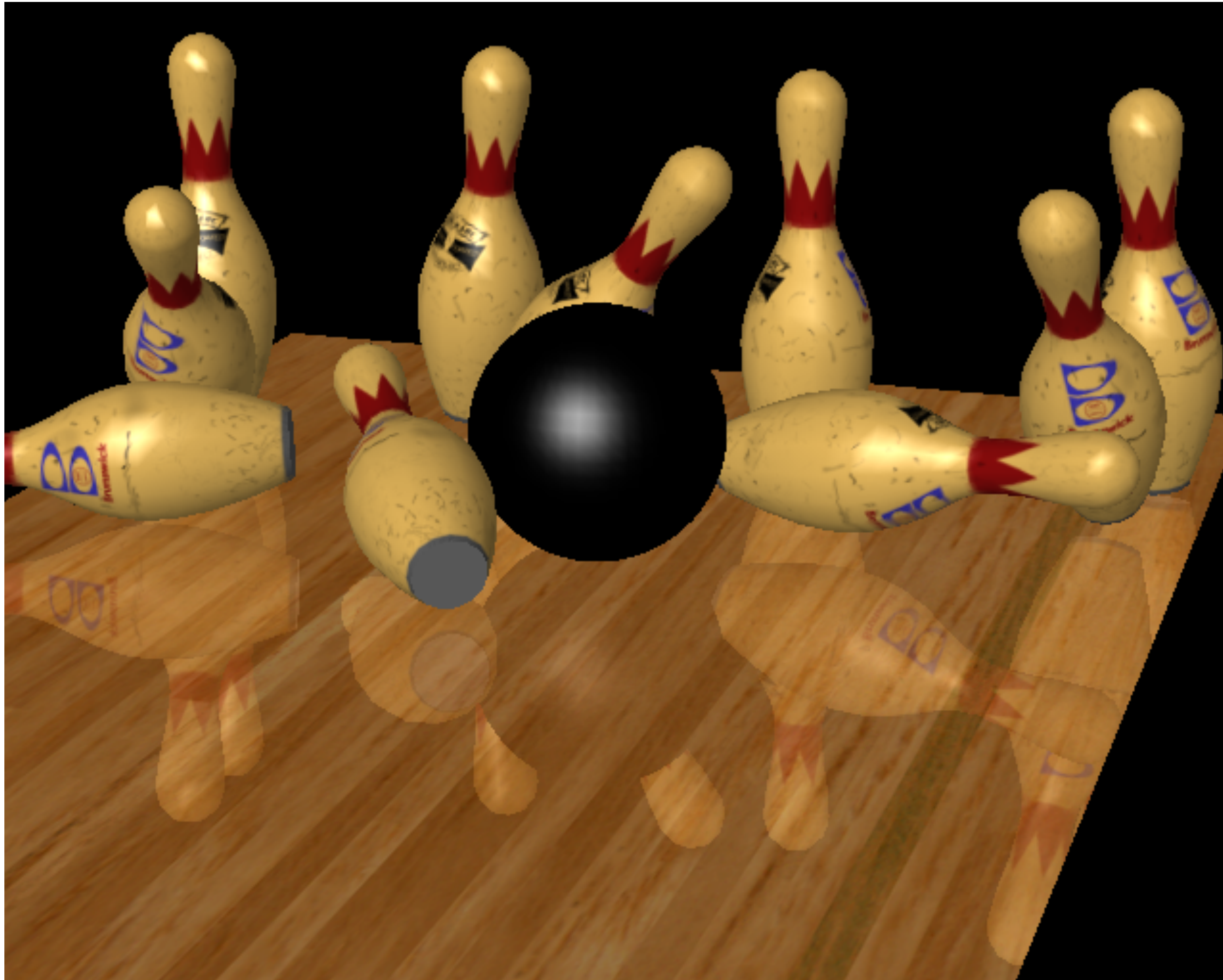
Texture Mapping Has Many Uses



Pattern on ball

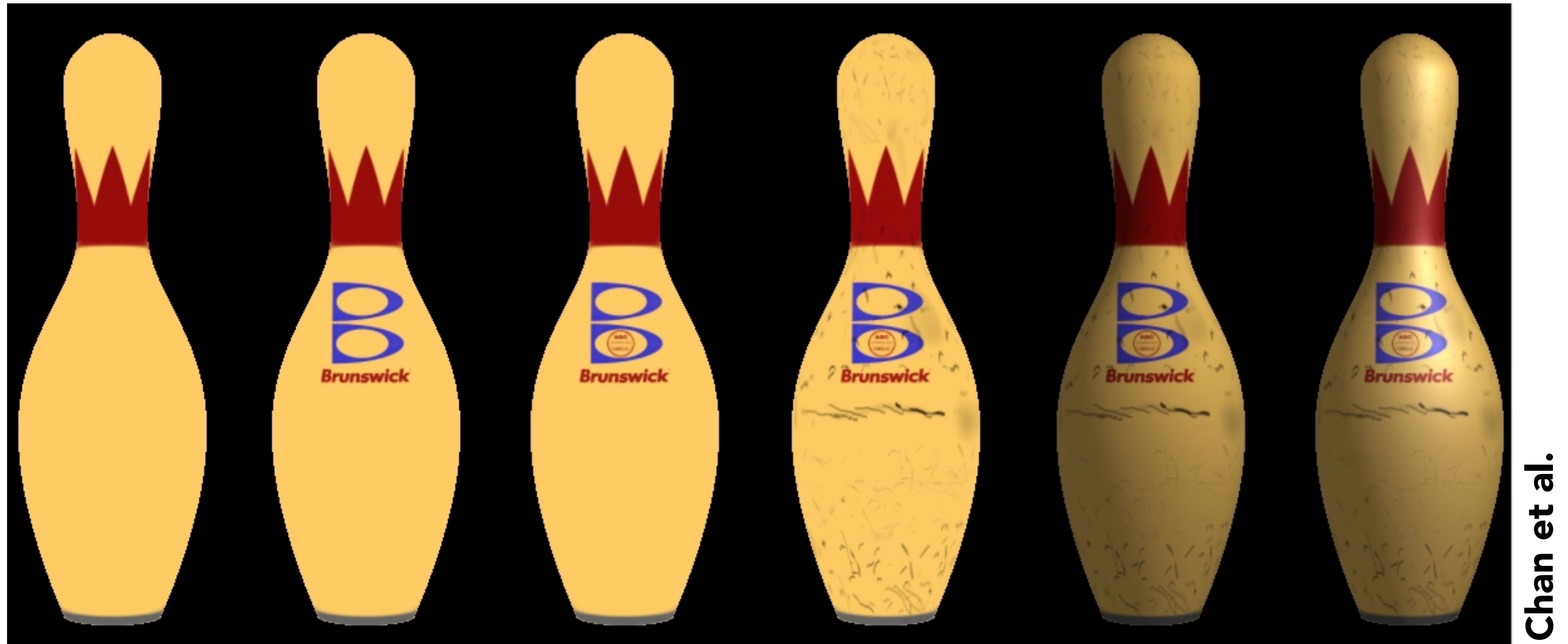
Wood grain on floor

Describe Surface Material Properties



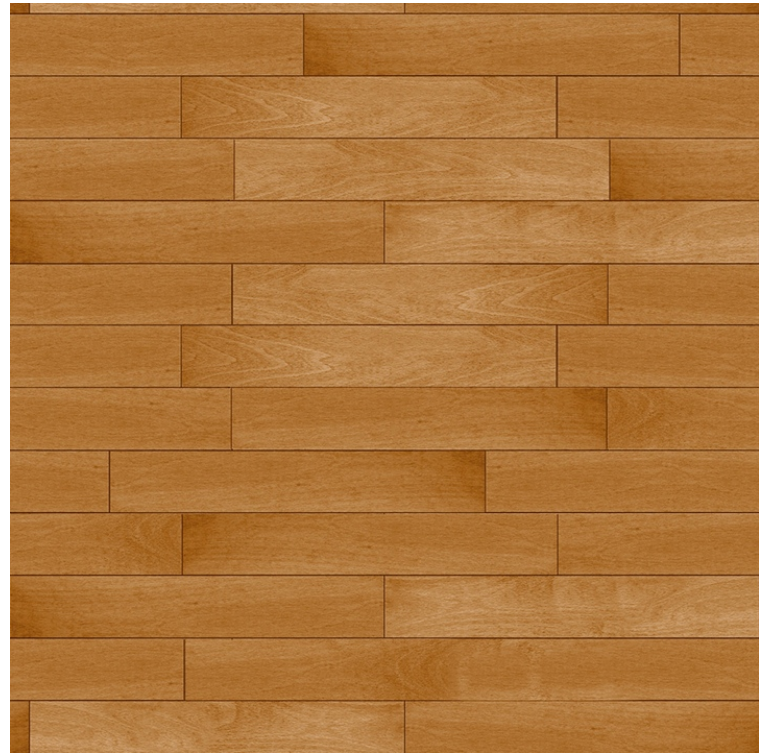
Proudfoot et al.

Describe Surface Material Properties



- Add details without raising geometric complexity
- Paste image onto geometry or define procedurally

2D Texture Mapping of Images

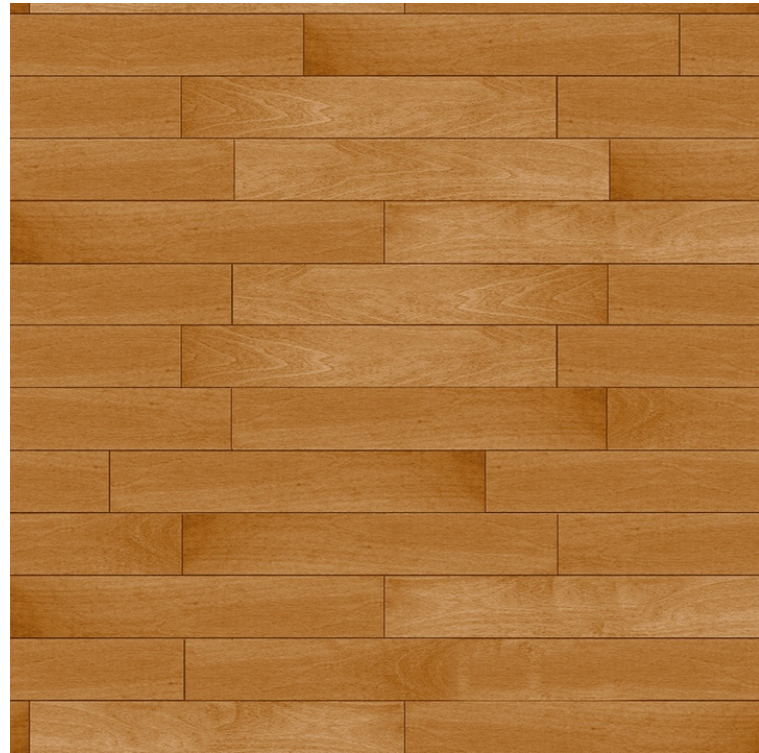


Map 2D image
onto object.



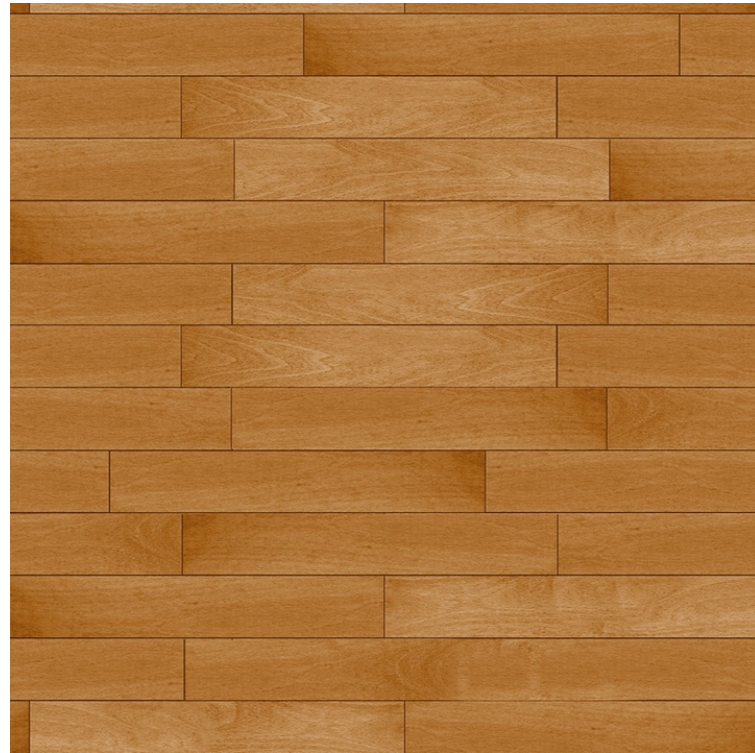
2D Texture Mapping of Images

Surface Color

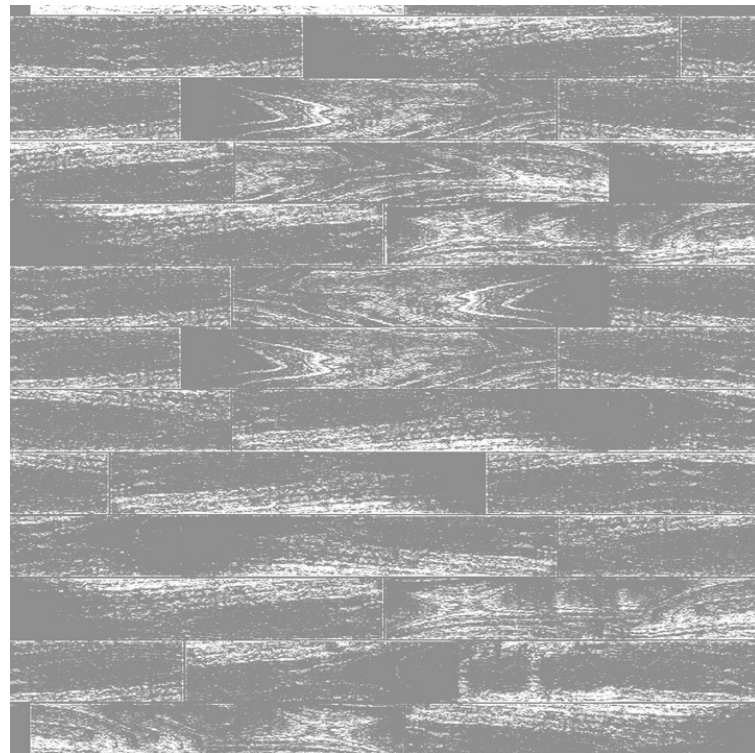


2D Texture Mapping of Images

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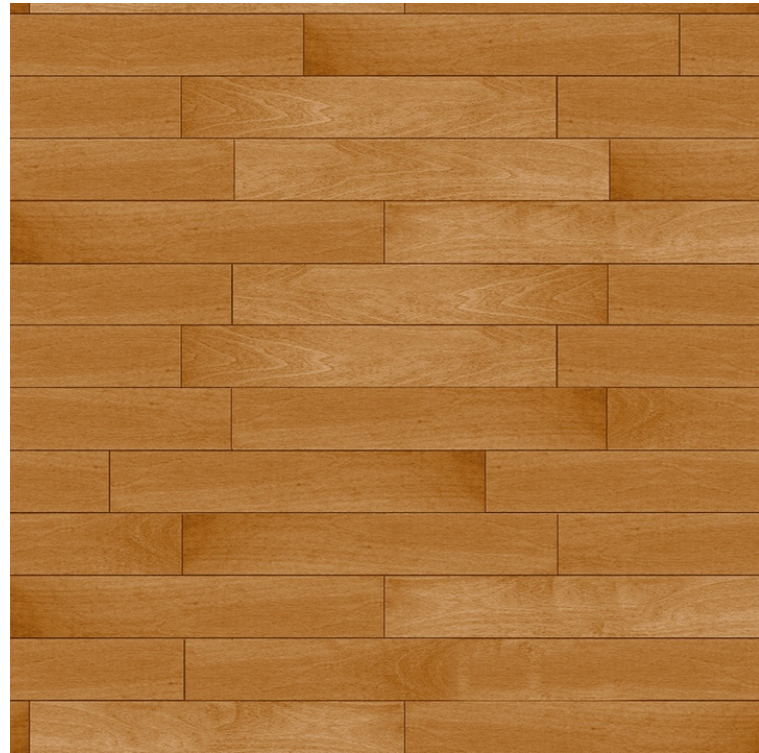


Surface Roughness

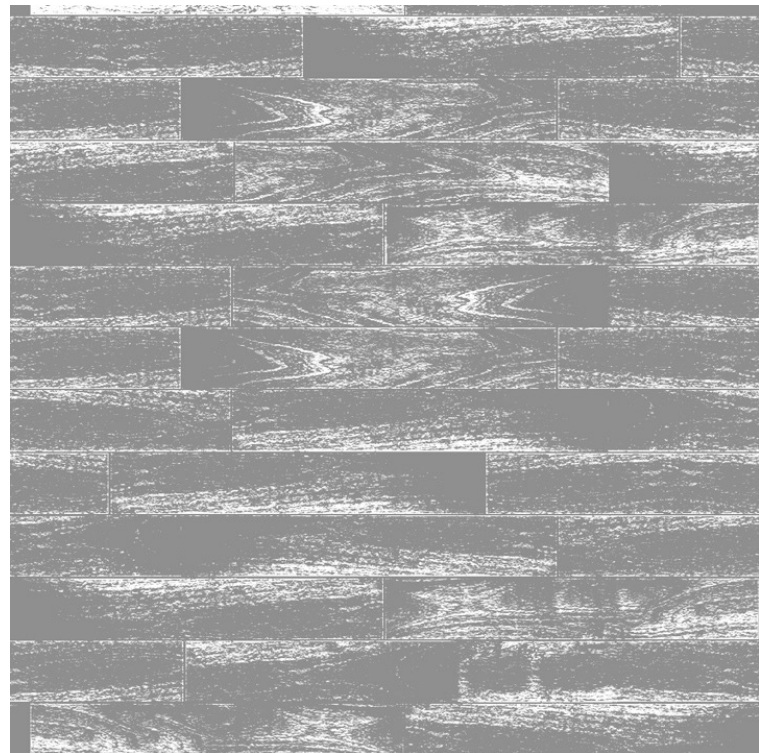


2D Texture Mapping of Images

Surface Color



Surface Roughness



Surface Geometry



Texture Coordinate Mappings

Think Chocolate Wrappers



Think Chocolate Wrappers

Texture image



Three Spaces

Surface lives in 3D world space

Every 3D surface point also has a place where it goes in the 2D image and in the 2D texture.

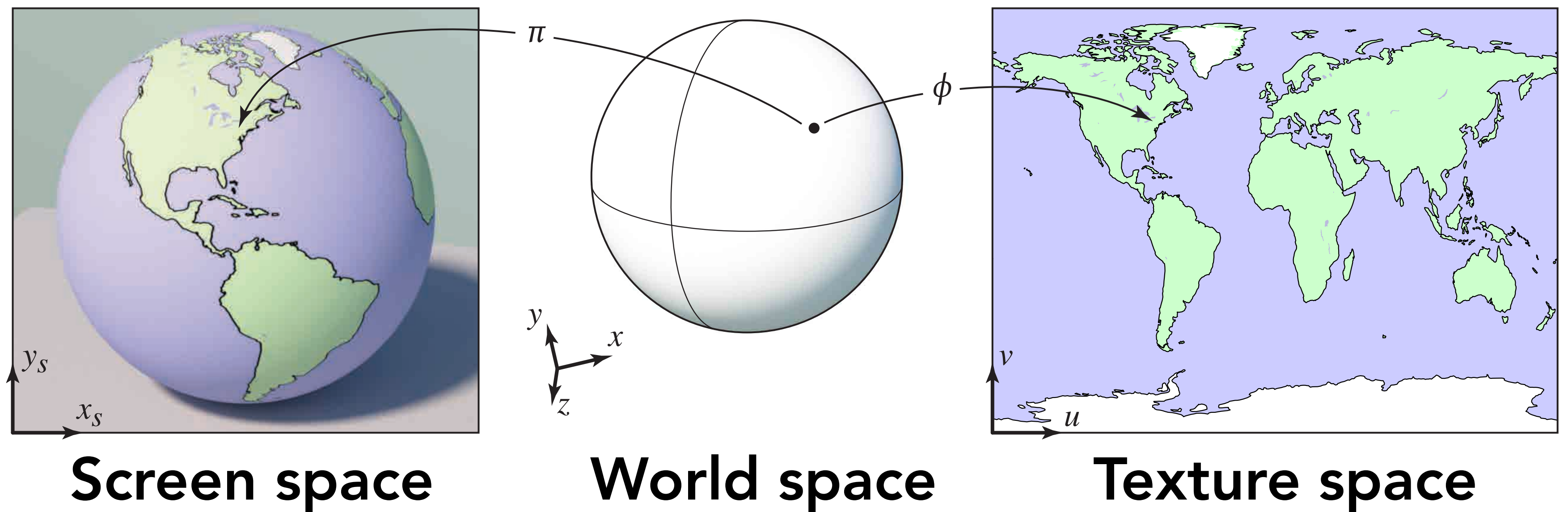
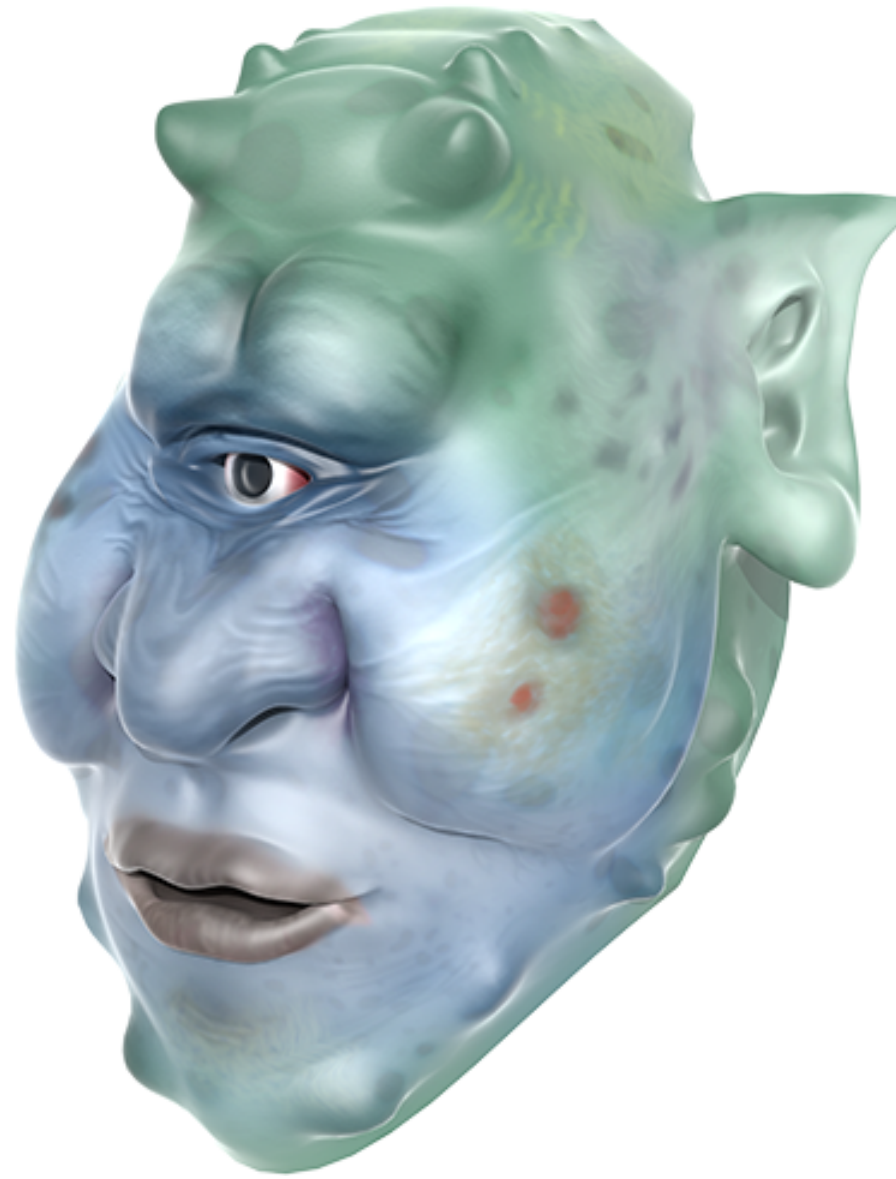


Image Texture Applied to Surface

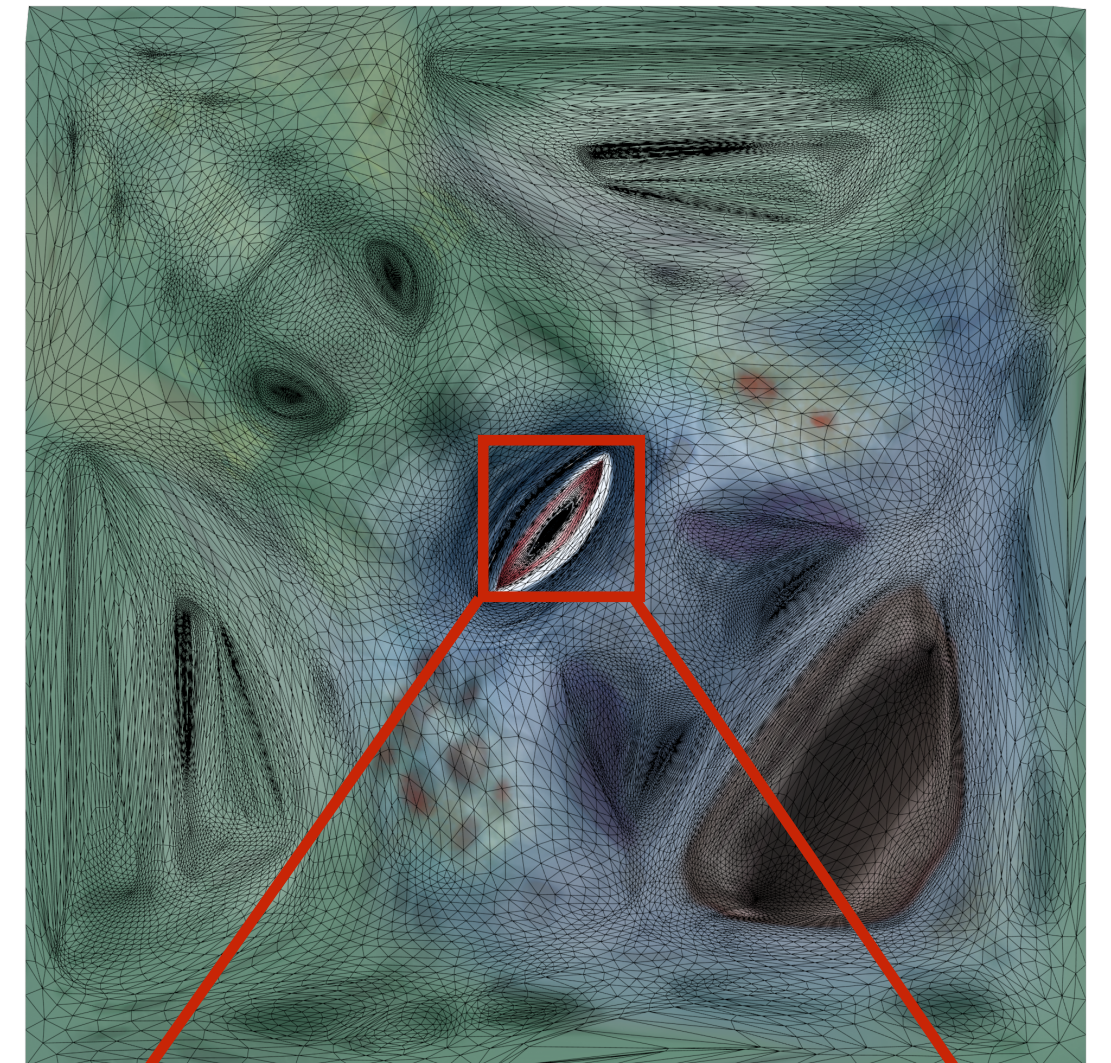
Rendering without texture



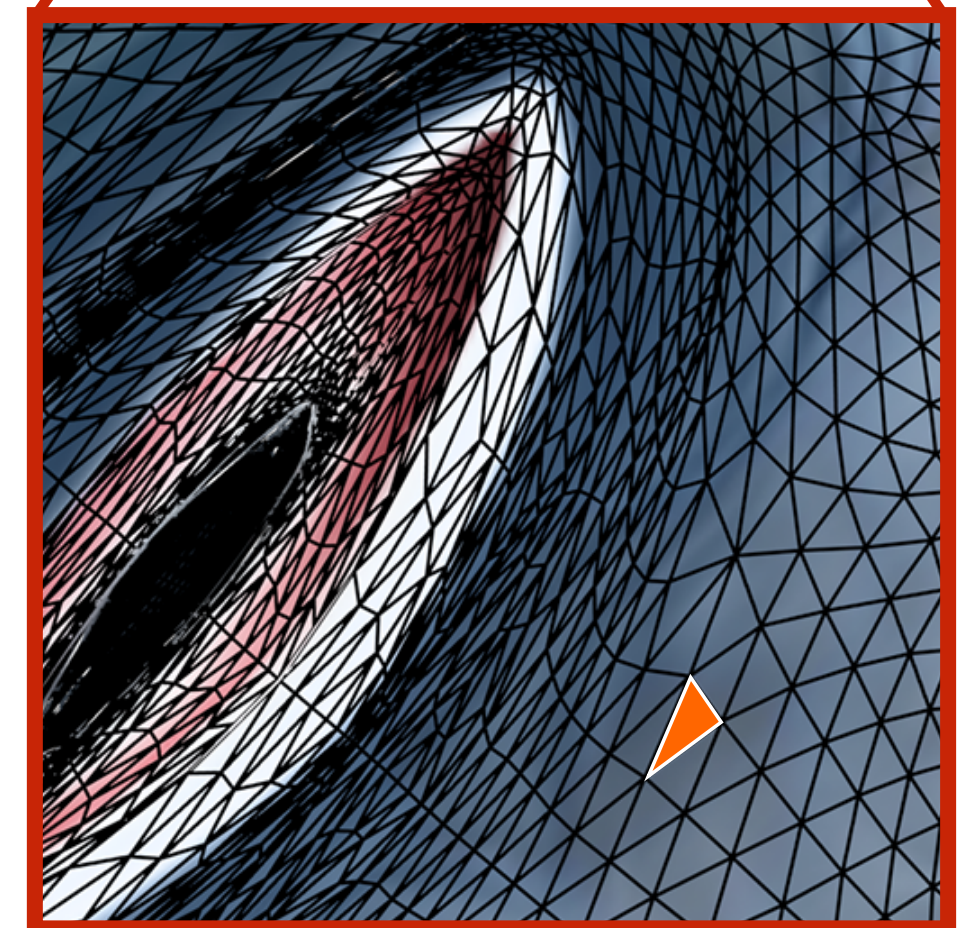
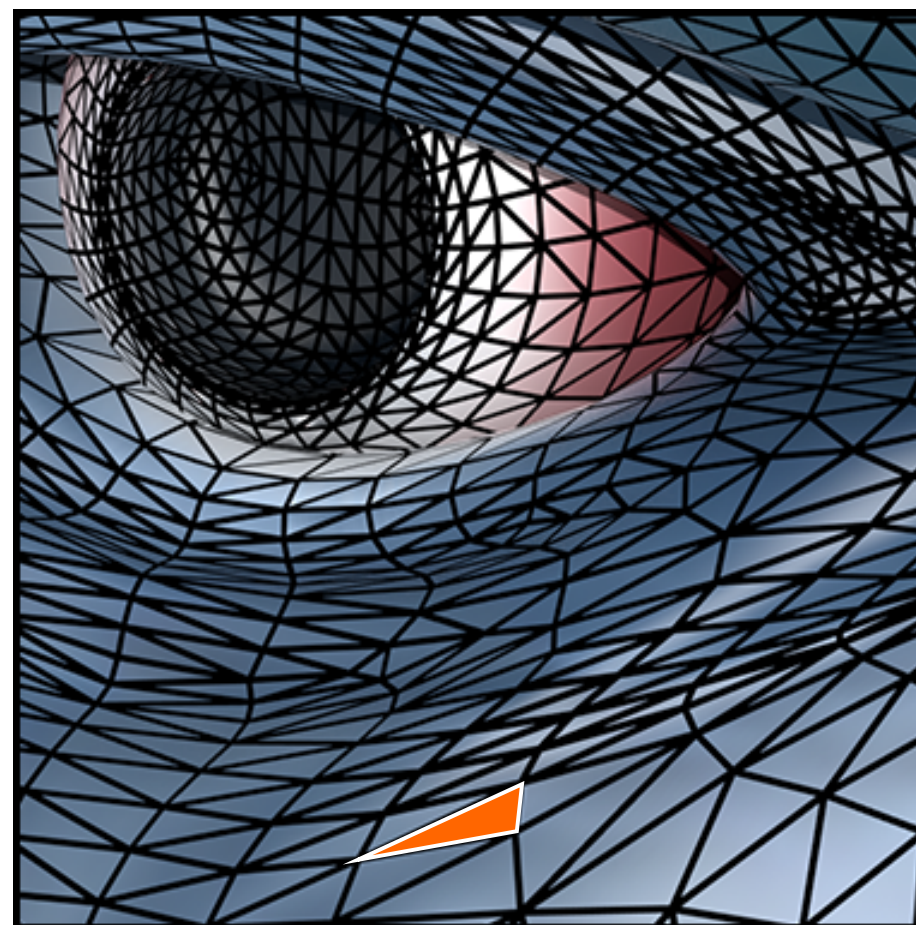
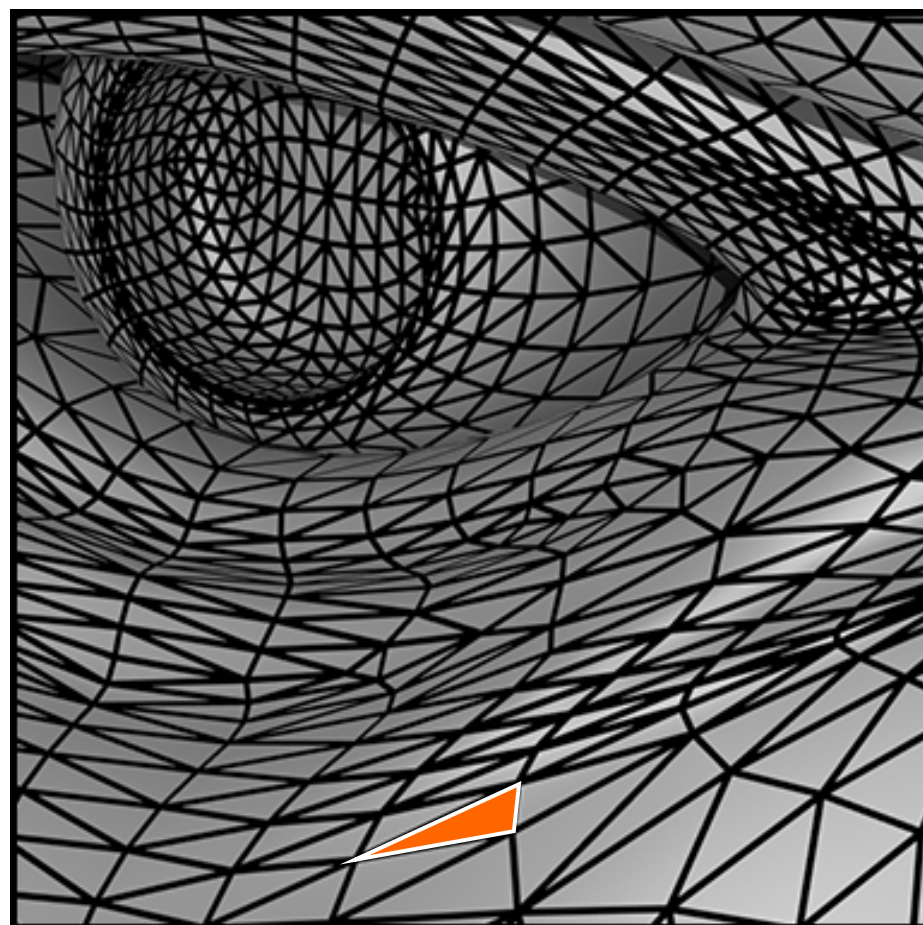
Rendering with texture



Texture image



Zoom

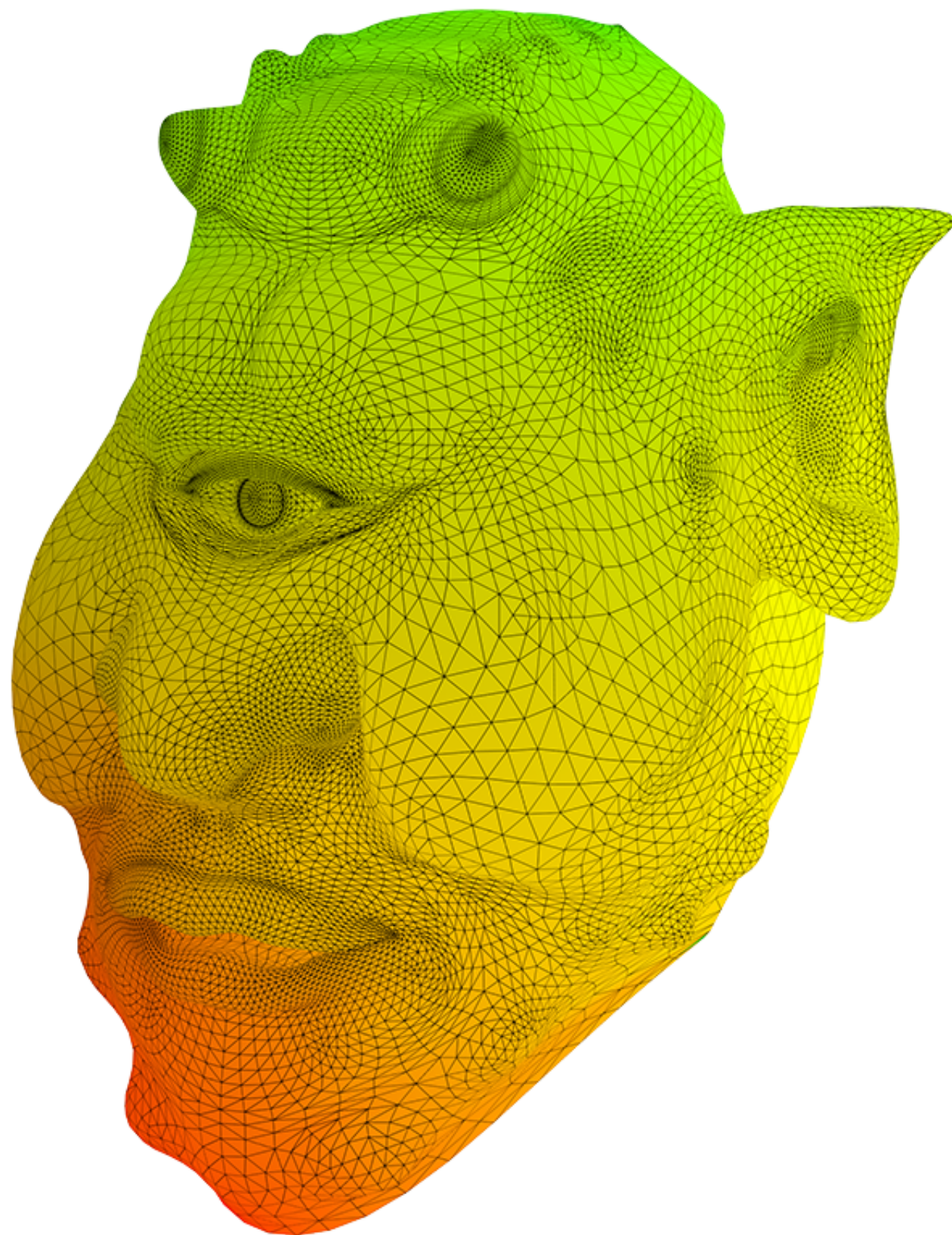


Each triangle "copies" a piece of the texture image back to the surface.

Visualization of Texture Coordinates

Each surface point is assigned a texture coordinate (u,v)

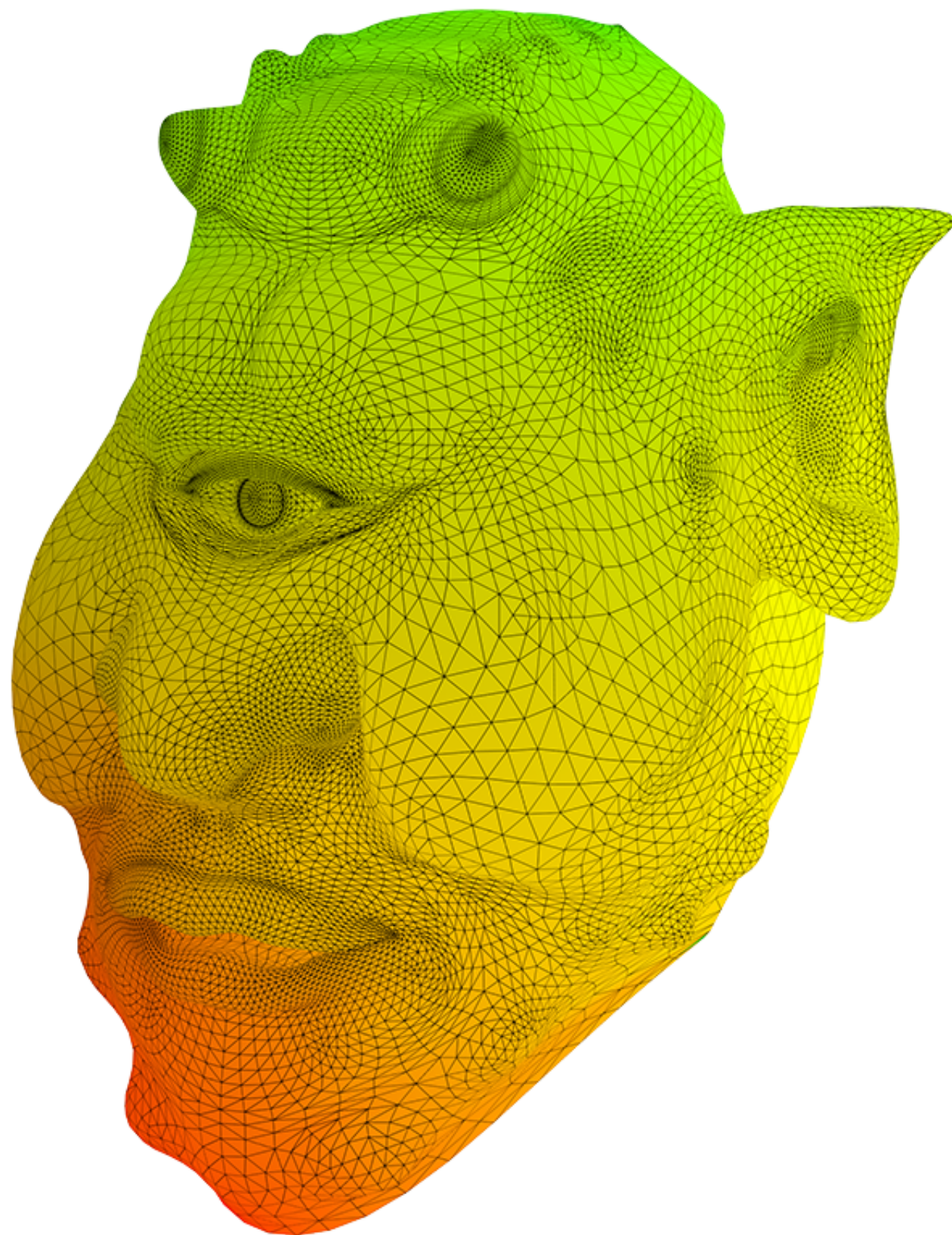
Visualization of texture coordinates



Visualization of Texture Coordinates

Each surface point is assigned a texture coordinate (u,v)

Visualization of texture coordinates



Triangle vertices in texture space

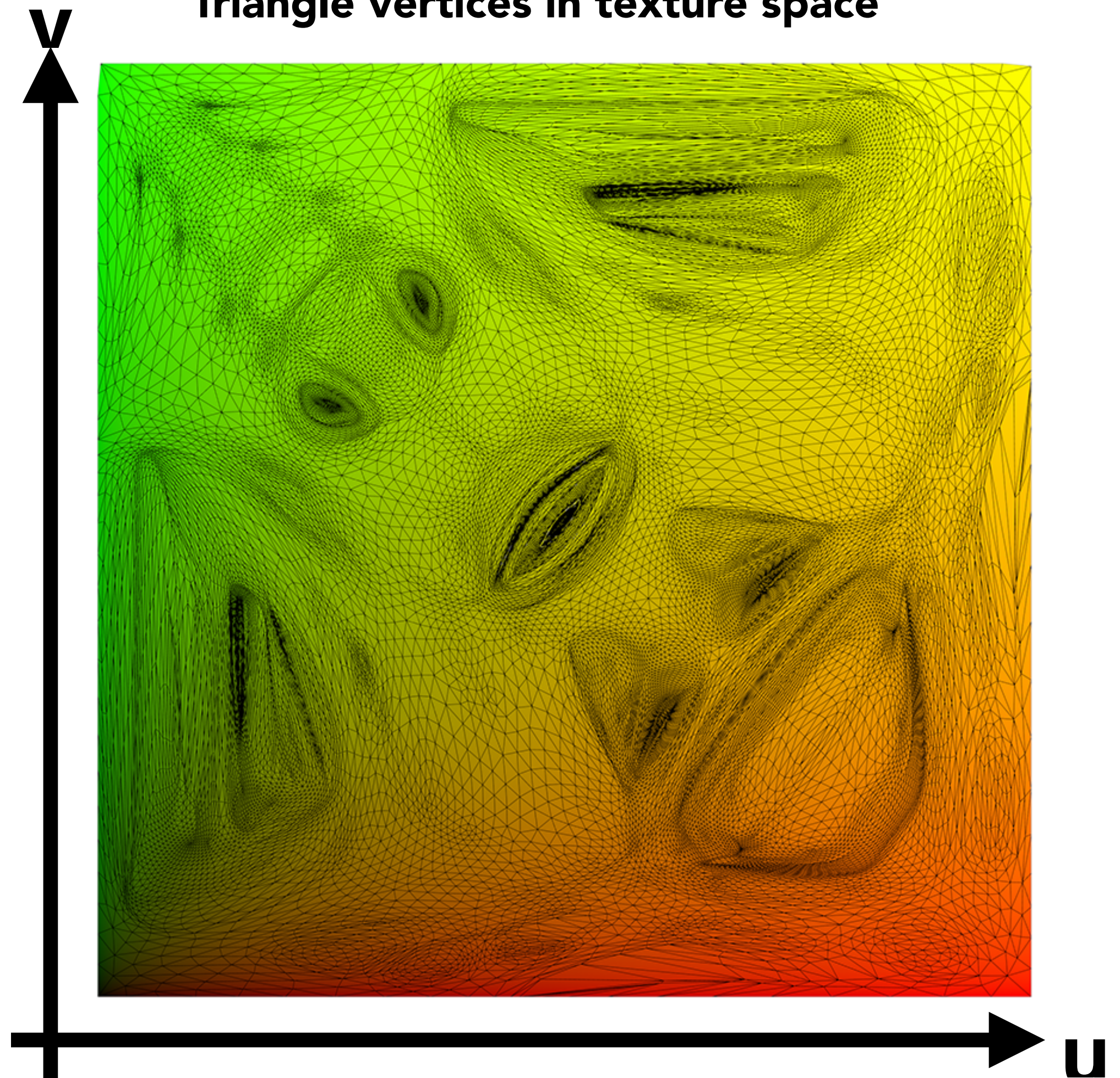
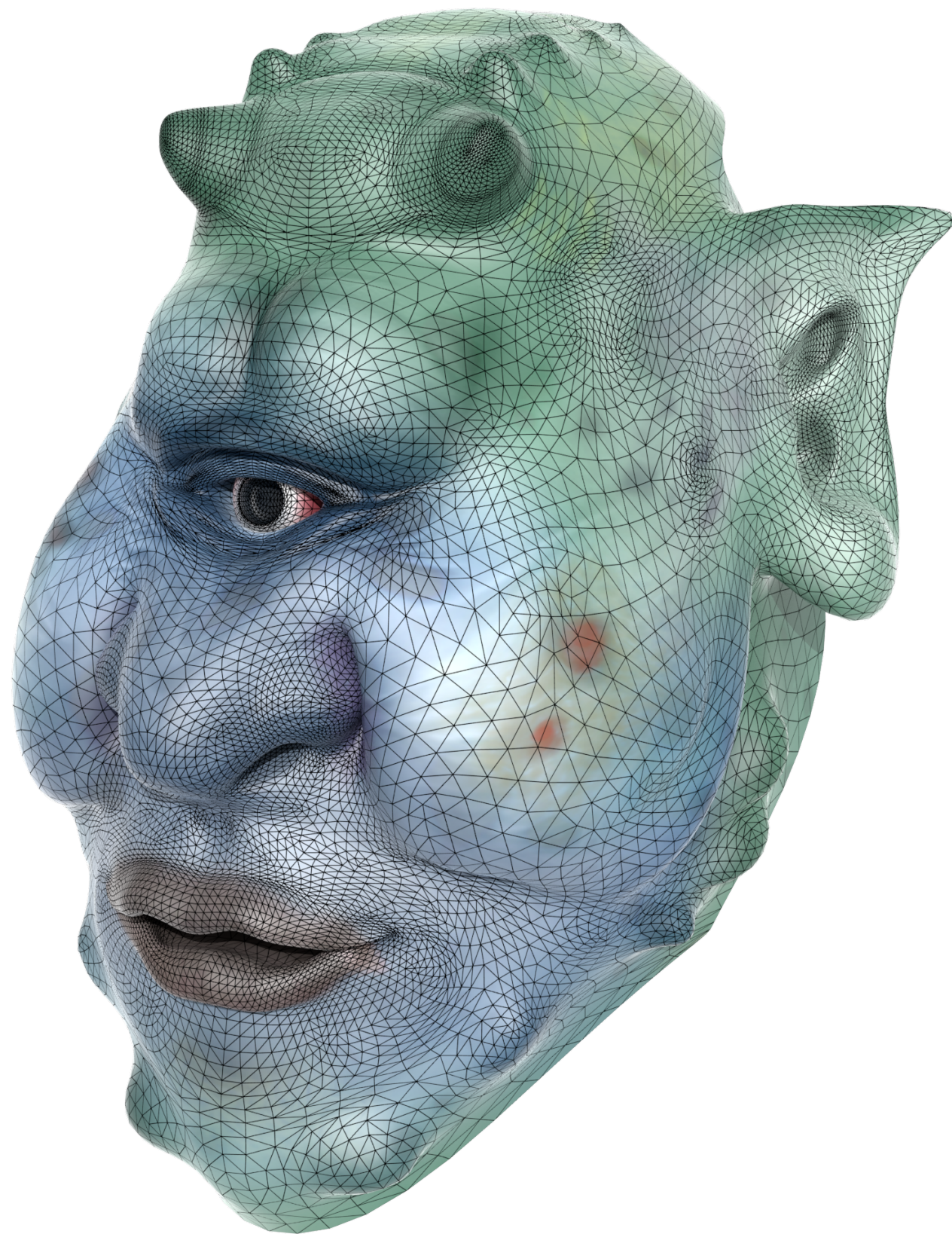


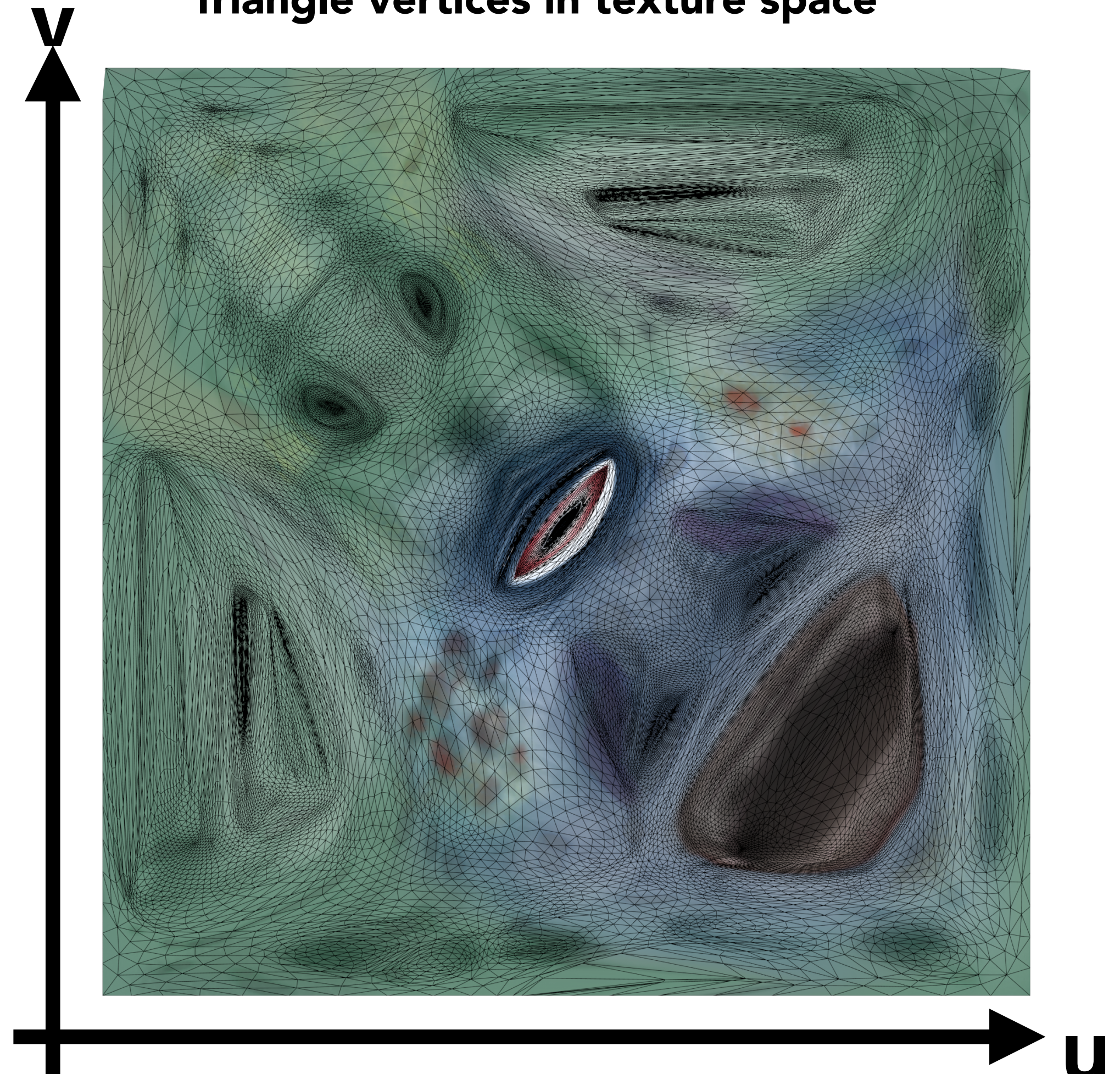
Image Texture Applied to Surface

Each surface point is assigned a texture coordinate (u,v)

Rendered result



Triangle vertices in texture space

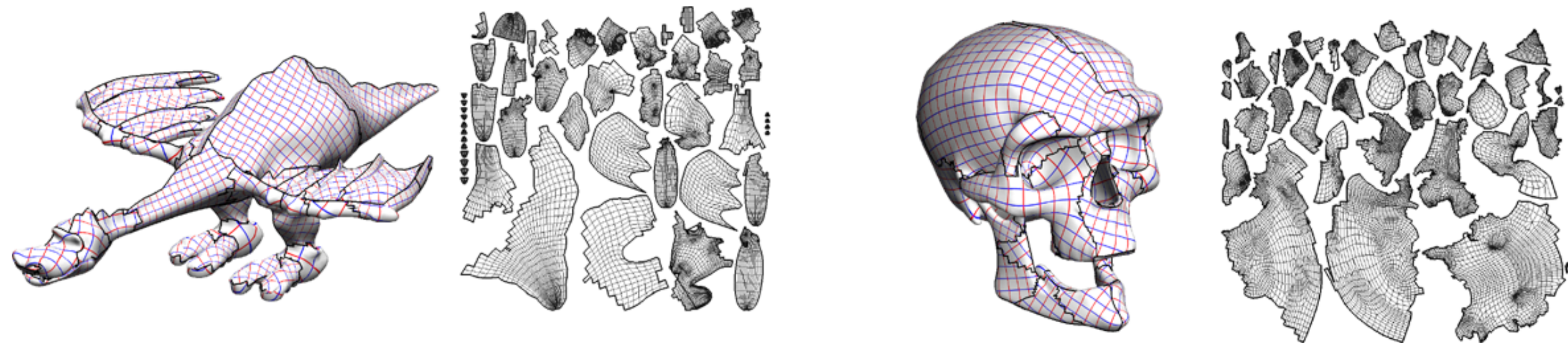


Creating Good Surface Coordinates is Hard

Finding cuts

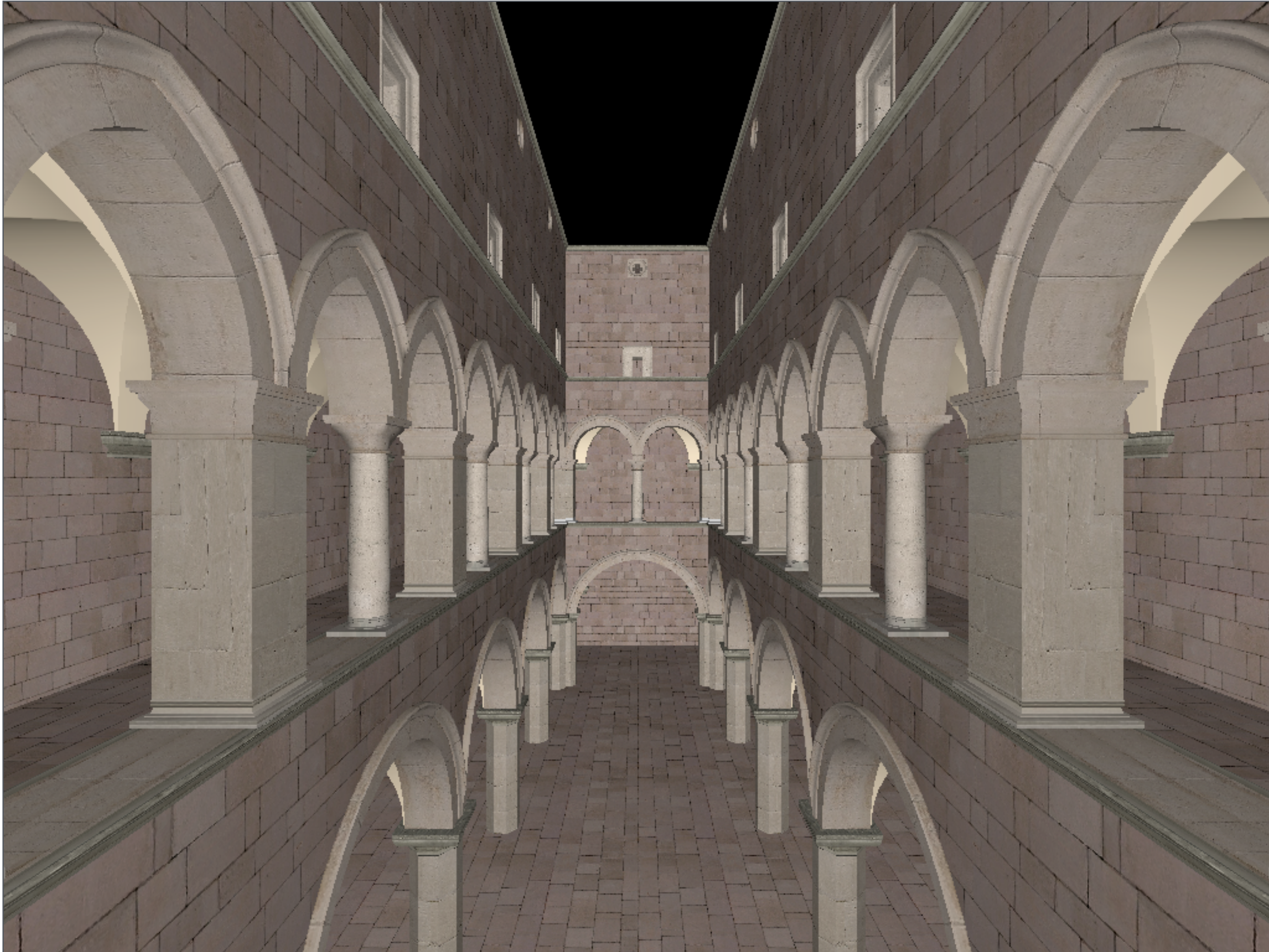


Texture atlases



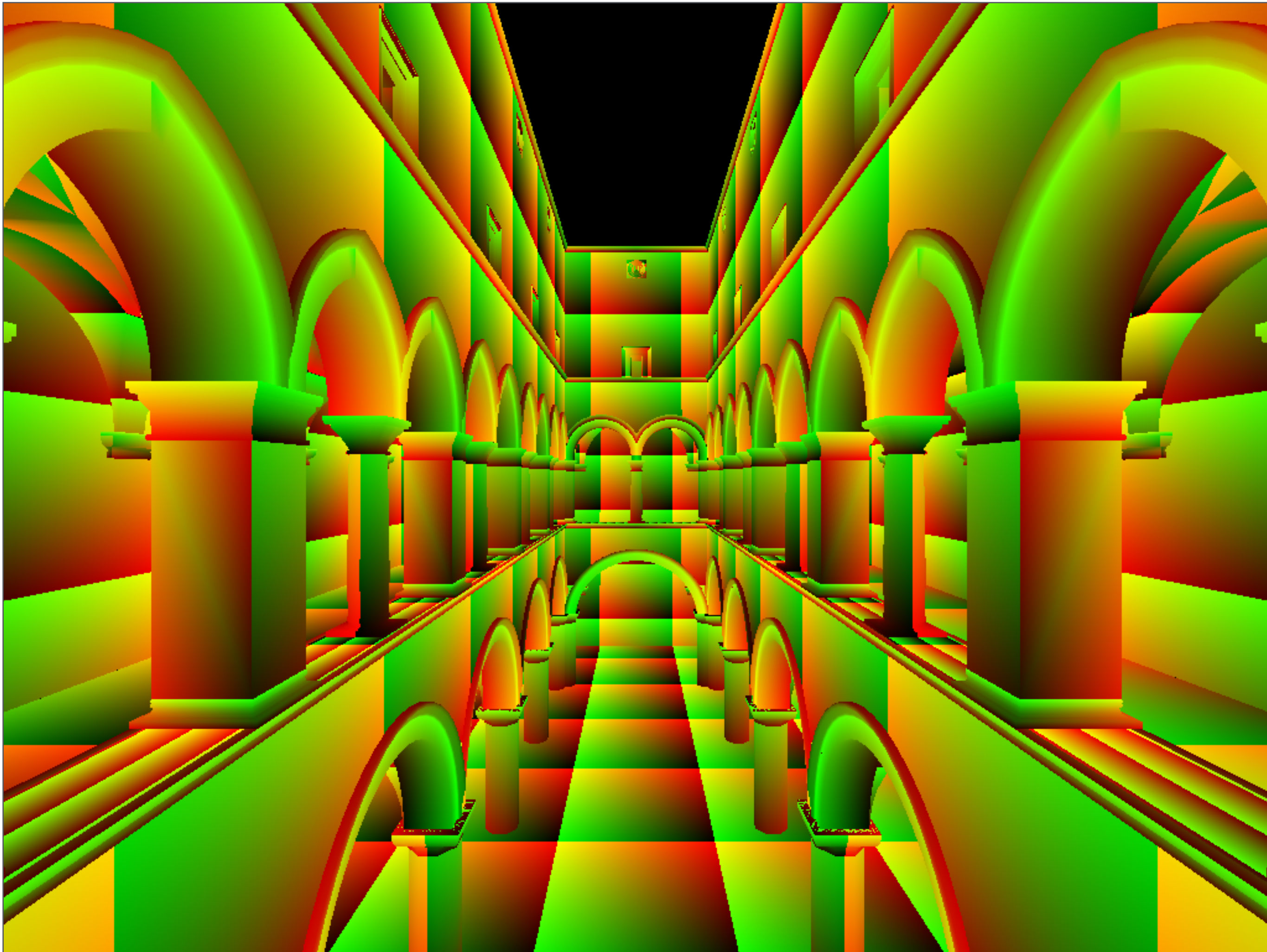
**Levy et al: Least Squares Conformal Maps
for Automatic Texture Atlas Generation, SIGGRAPH, 2002**

Sponza Palace Model



Textures applied to surfaces

Sponza Palace Model



Visualization of texture coordinates

Sponza Palace Model

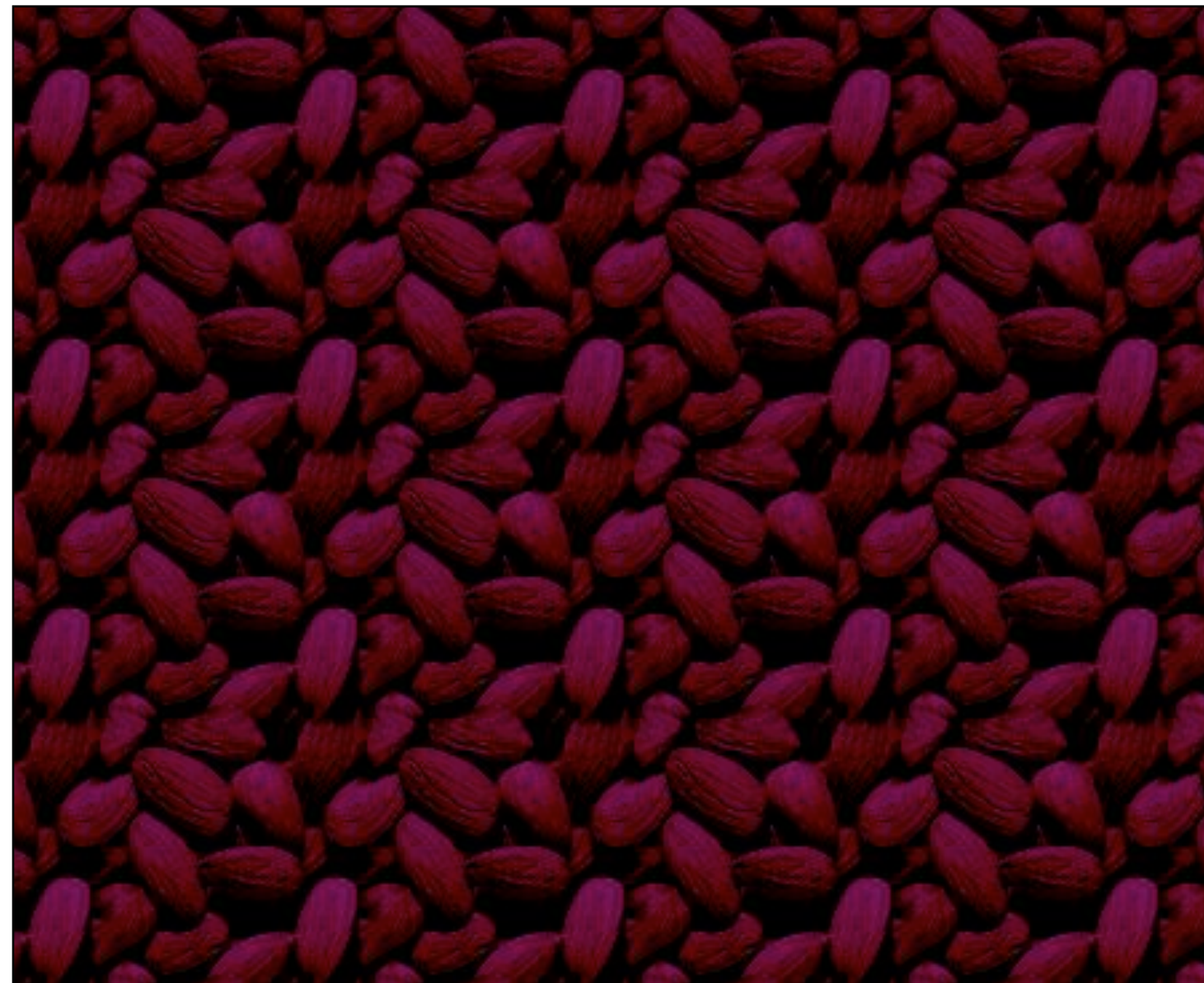


Example textures used

Repeating Textures

Image Tiles allow repeating textures

- Images must be manipulated to allow tiling
- Often result in visible artifacts
 - There are methods to get around artifacts....



Interpolation Across Triangles: Barycentric Coordinates

Interpolation Across Triangles

Interpolation Across Triangles

Why do we want to interpolate?

- Specify values (e.g. texture coordinates) at vertices, and obtain smoothly varying values across surface

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What do we want to interpolate?

- Texture coordinates, colors, normal vectors, ...

Interpolation Across Triangles

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What do we want to interpolate?

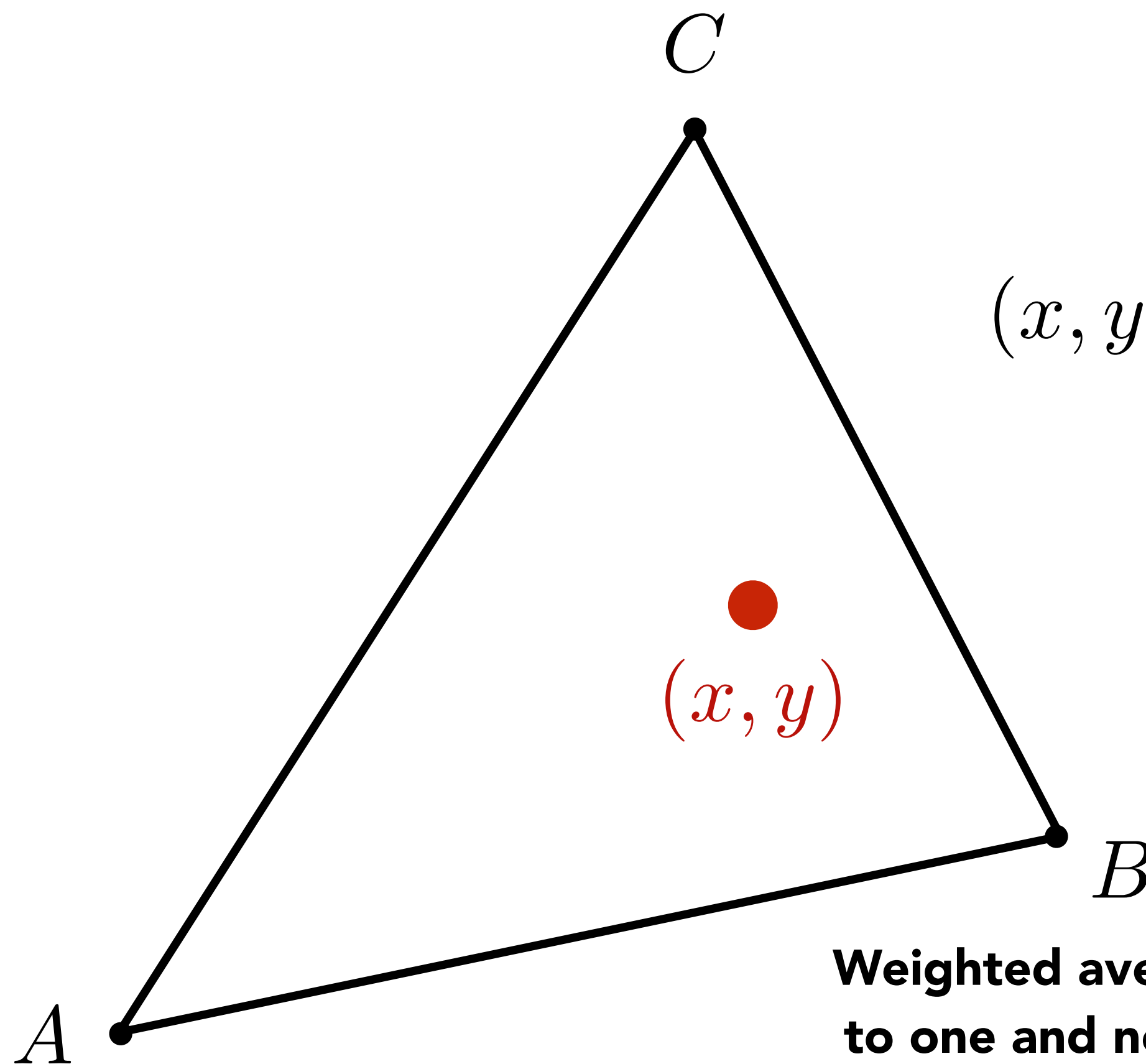
- Texture coordinates, colors, normal vectors, ...

How do we interpolate?

- Barycentric coordinates

Barycentric Coordinates

A coordinate system for triangles (α, β, γ)



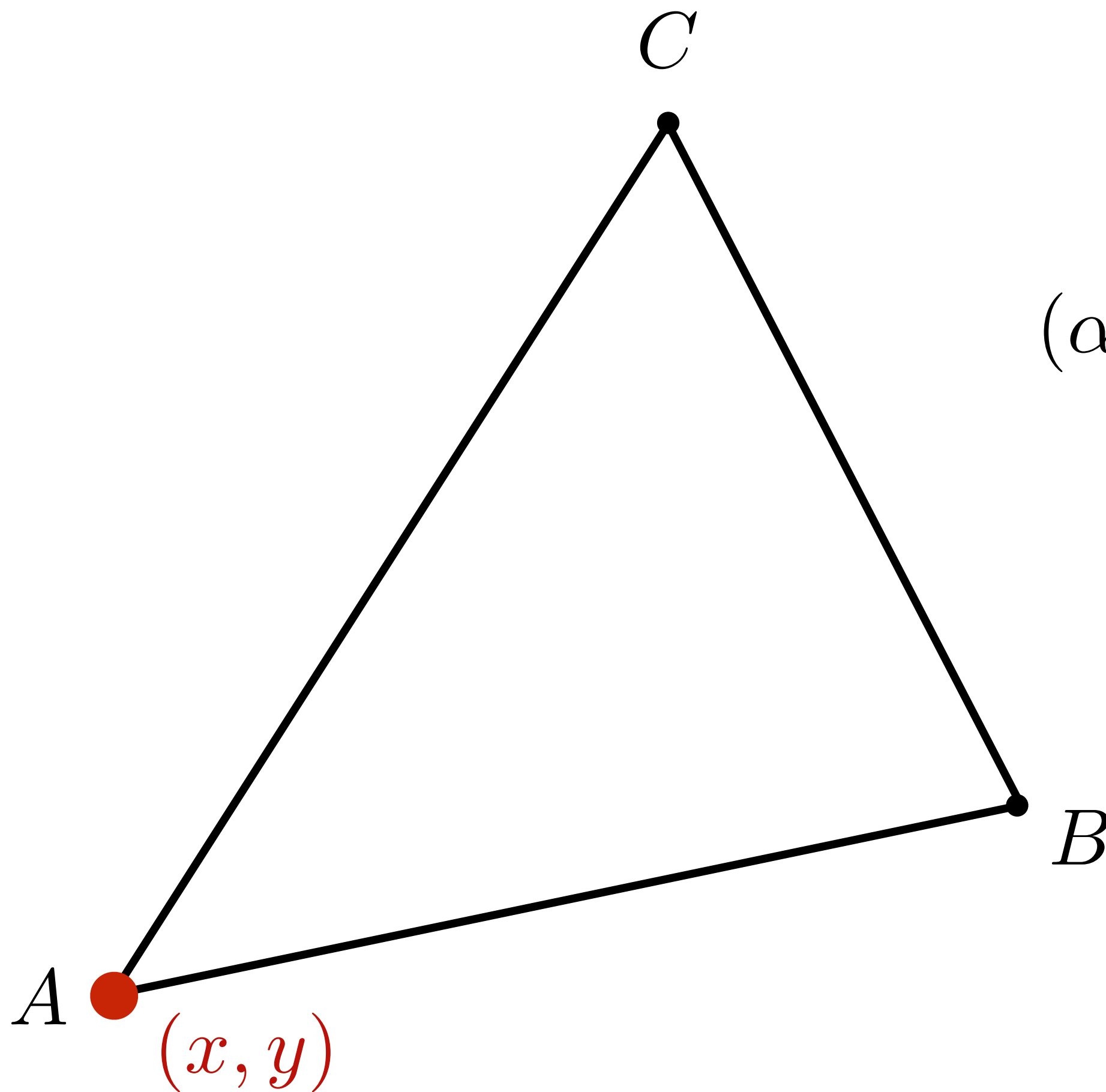
$$(x, y) = \alpha A + \beta B + \gamma C$$

$$\alpha + \beta + \gamma = 1$$

Inside the triangle if all three coordinates are non-negative

Weighted average of points with weights summing to one and non-negative has convex hull property.

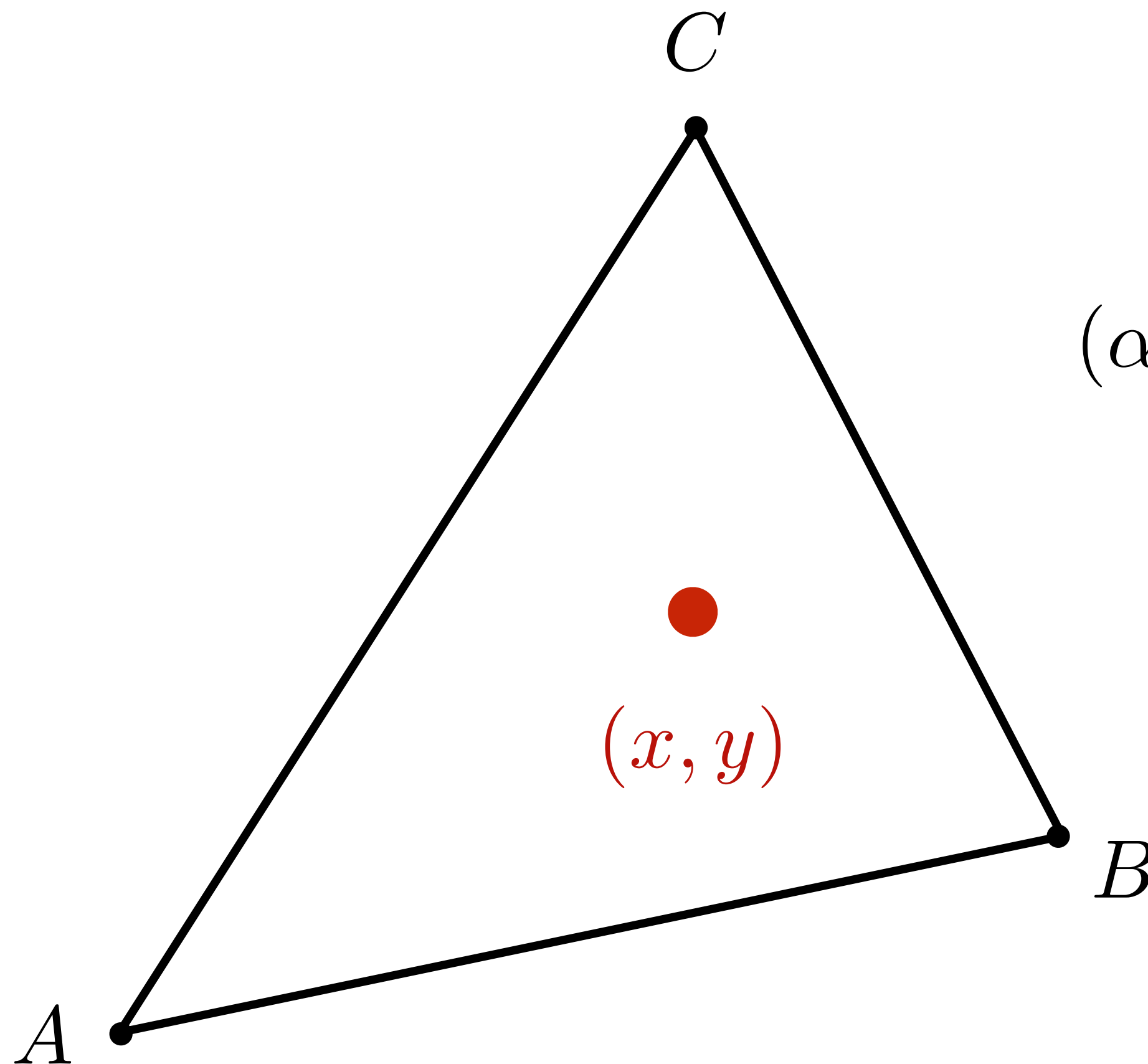
Barycentric Coordinates - Examples



$$(\alpha, \beta, \gamma) = (1, 0, 0)$$

$$(x, y) = \alpha A + \beta B + \gamma C$$
$$= A$$

Barycentric Coordinates - Examples

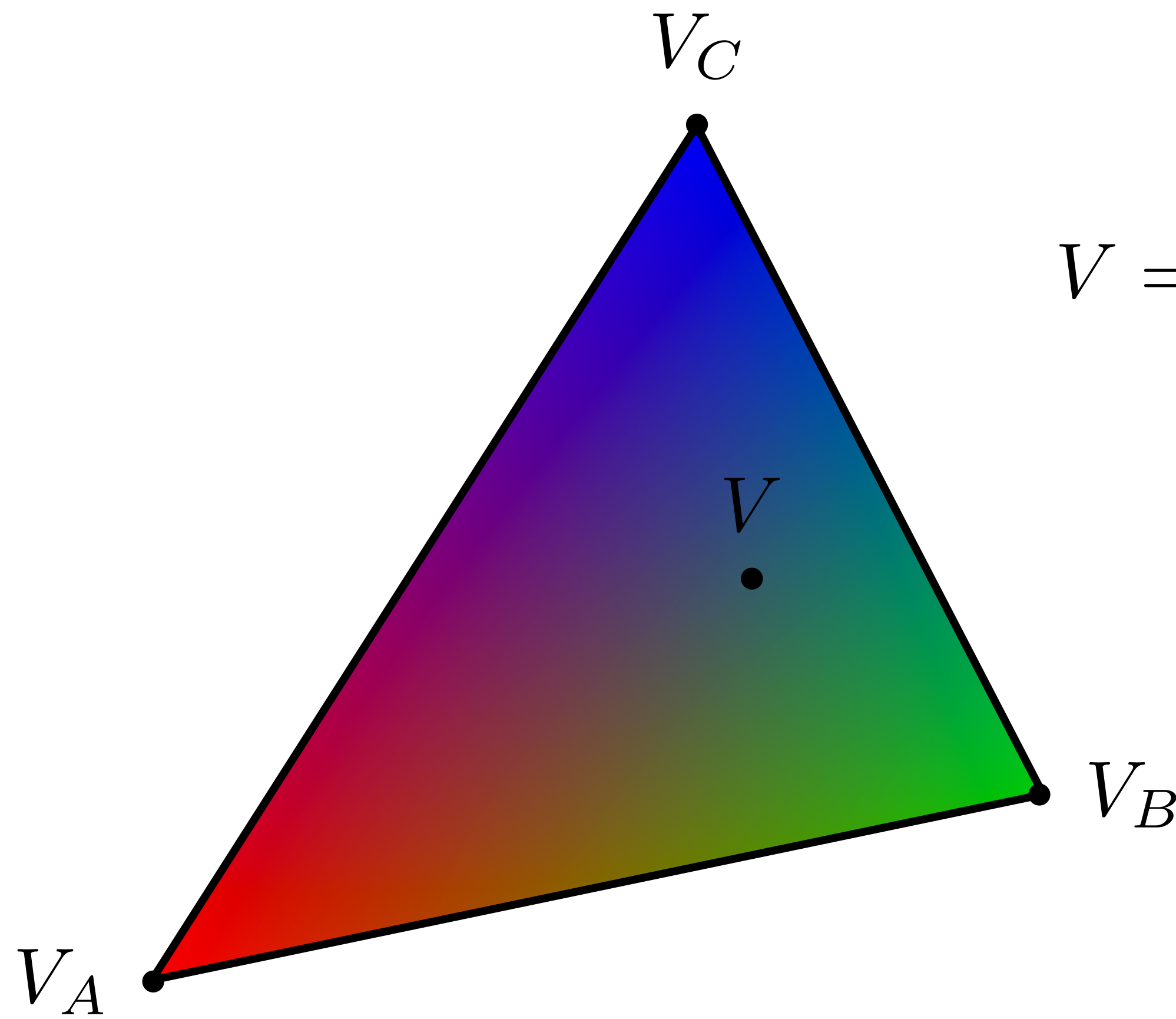


$$(\alpha, \beta, \gamma) = \left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$$

$$(x, y) = \frac{1}{3} A + \frac{1}{3} B + \frac{1}{3} C$$

Linear Interpolation Across Triangle

Barycentric coords linearly interpolate values at vertices

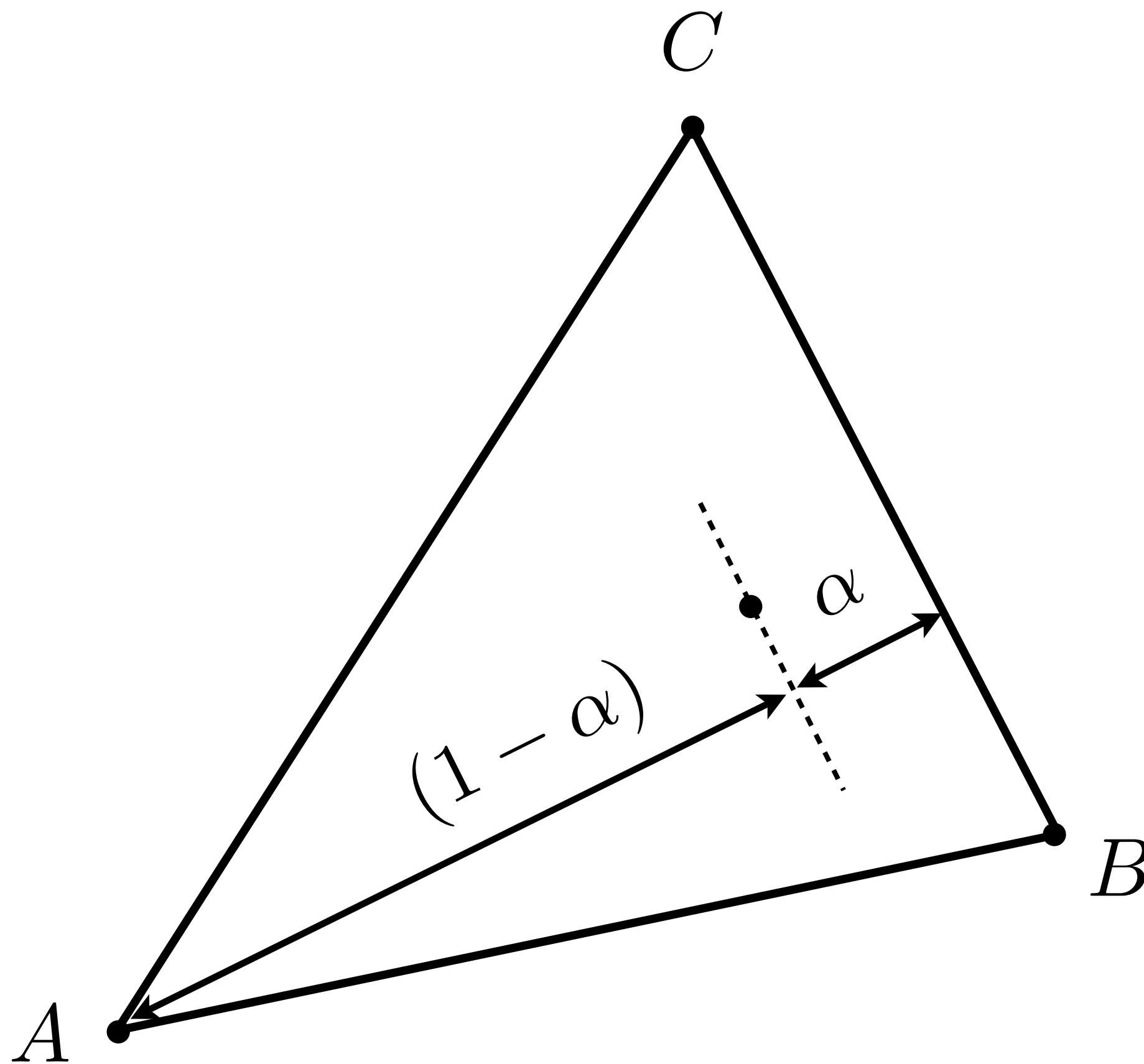


$$V = \alpha V_A + \beta V_B + \gamma V_C$$

V_A , V_B , V_C can be
positions, texture
coordinates, color,
normal vectors,
material attributes...

Barycentric Coordinates

Geometric viewpoint — proportional distances



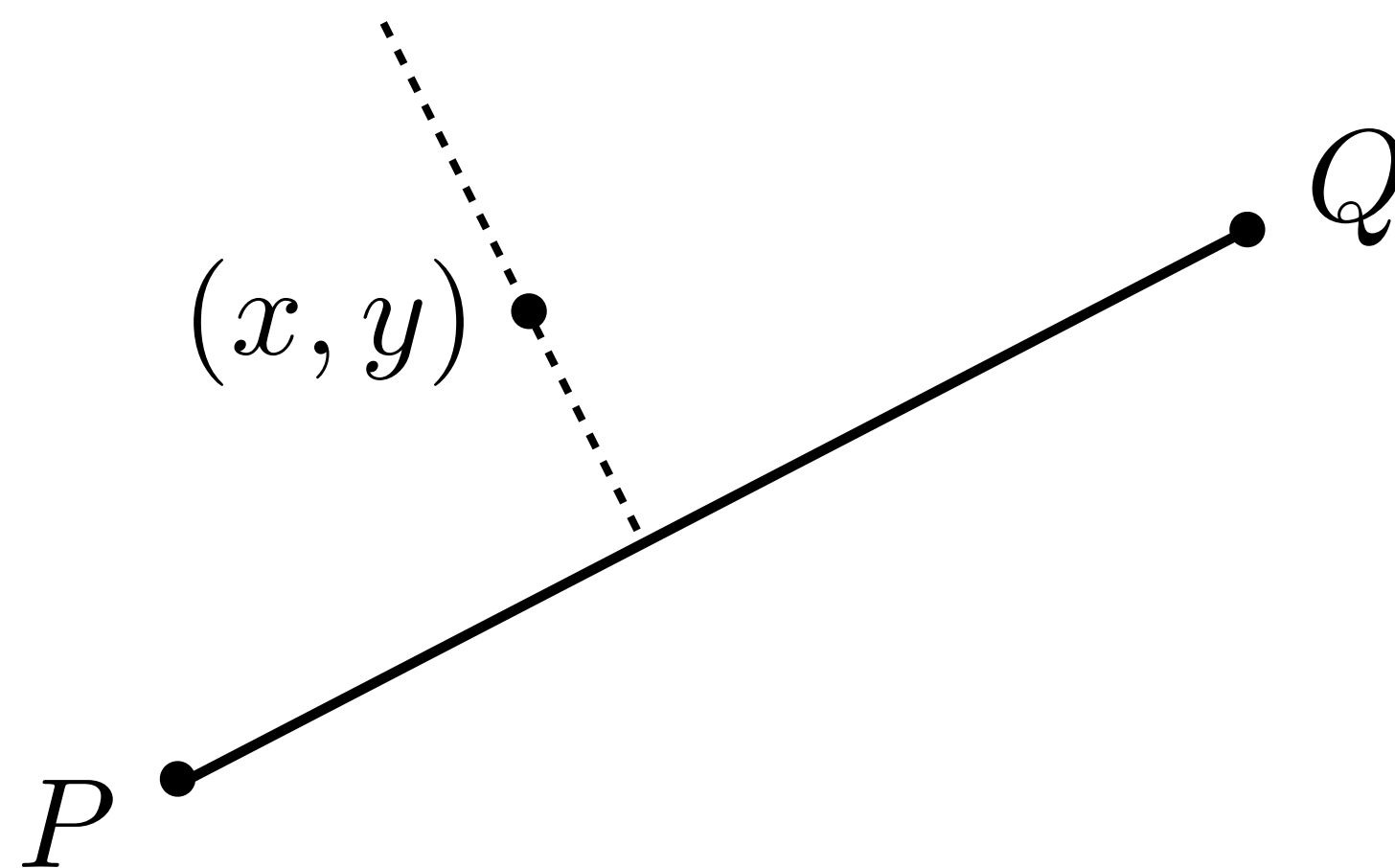
Similar construction
for other coordinates

Computing Barycentric Coordinates

Recall the line equation we derived in Lecture 2.

$L_{PQ}(x,y)$ is proportional to the distance from line PQ.

$$L_{PQ}(x, y) = -(x - x_P)(y_Q - y_P) + (y - y_P)(x_Q - x_P)$$

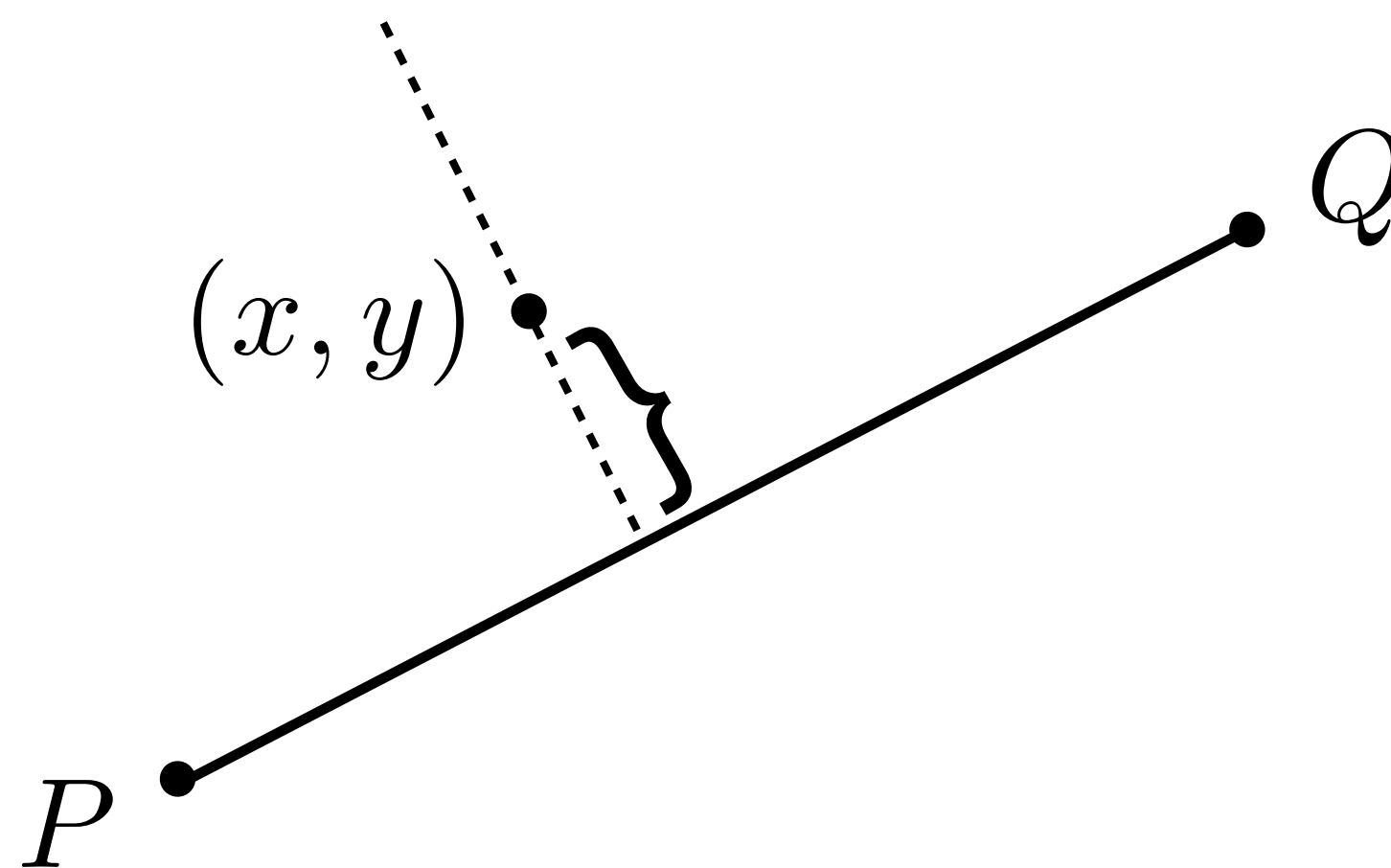


Computing Barycentric Coordinates

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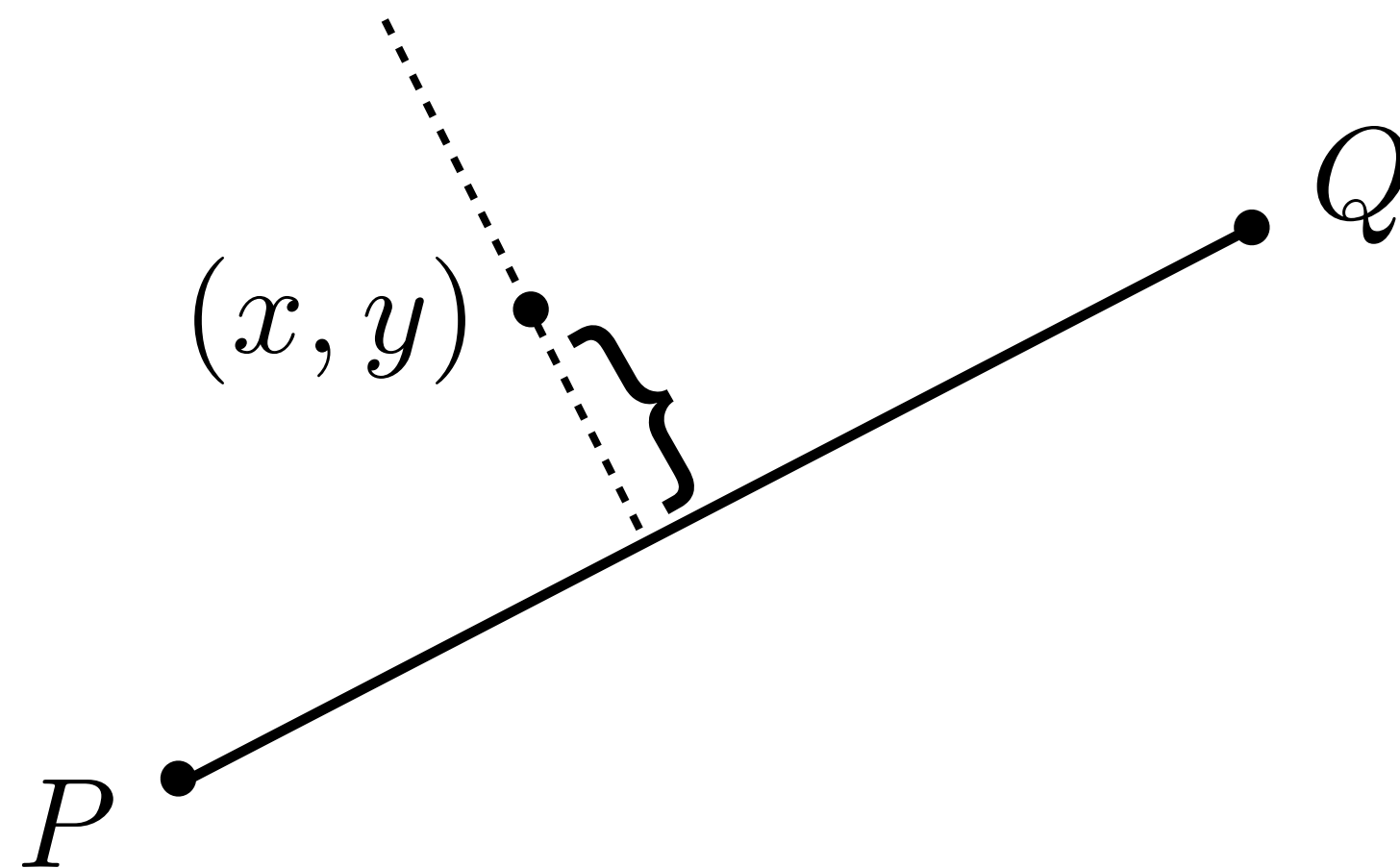


Computing Barycentric Coordinates

Recall the line equation we derived in Lecture 2.

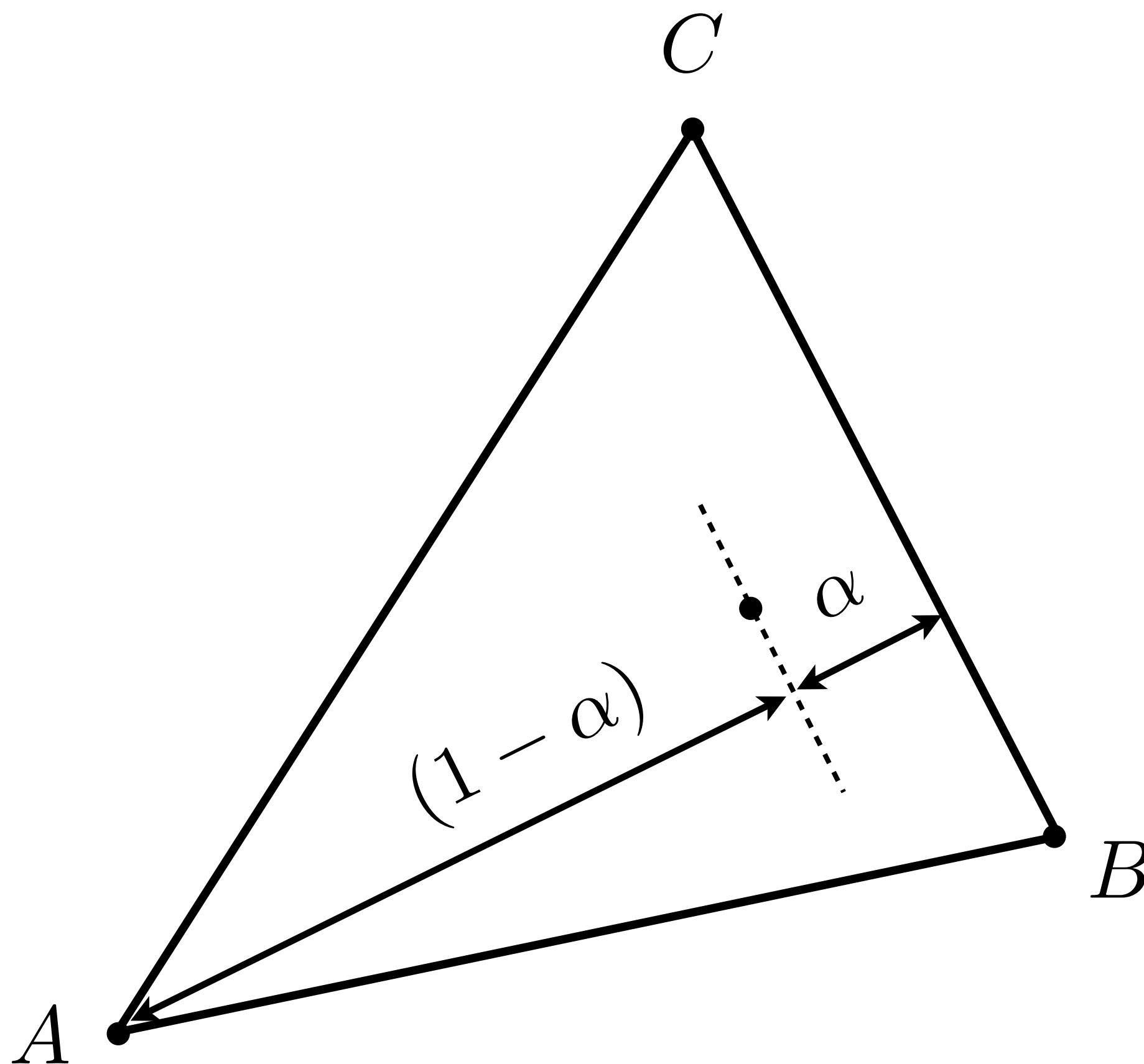
$L_{PQ}(x,y)$ is proportional to the distance from line PQ .

$$\begin{aligned} L_{PQ}(x,y) &= -(x - x_P)(y_Q - y_P) + (y - y_P)(x_Q - x_P) \\ &= (\mathbf{Q} - \mathbf{P}) \times \left(\begin{bmatrix} x \\ y \end{bmatrix} - \mathbf{P} \right) \end{aligned}$$



Computing Barycentric Coordinates

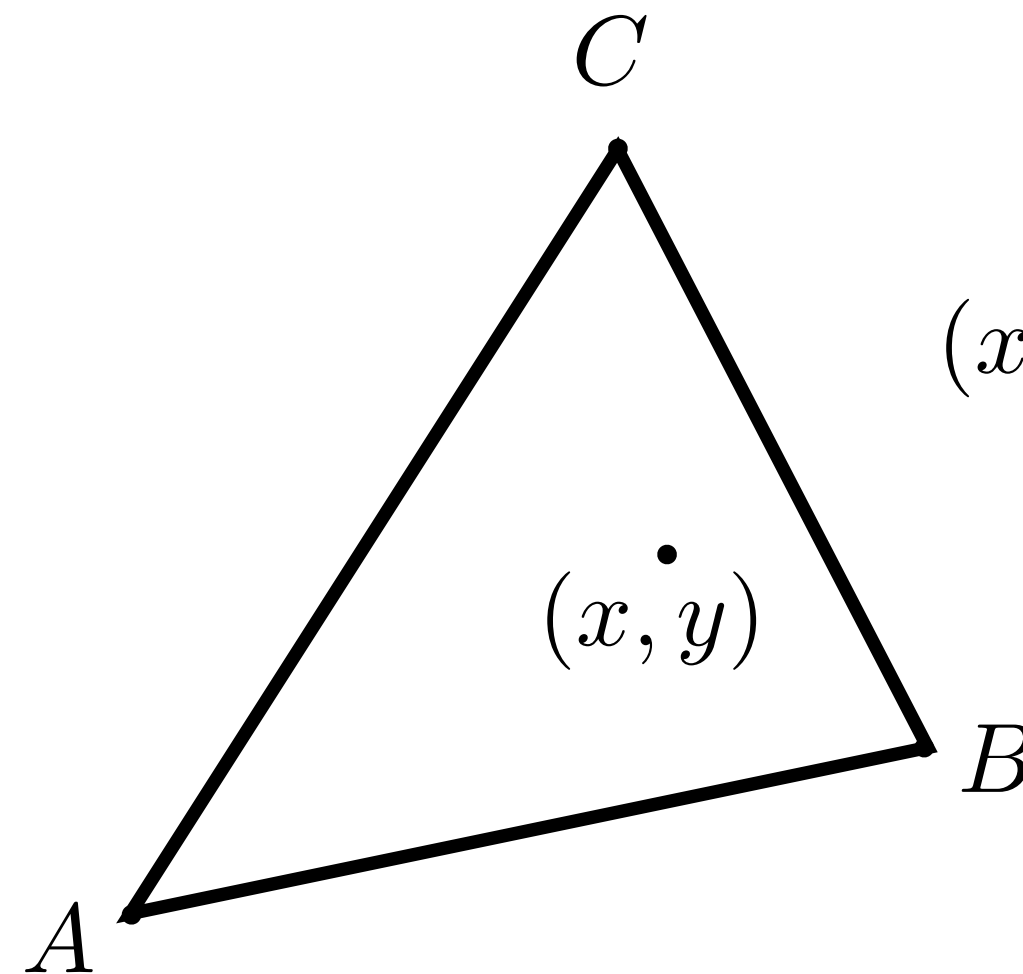
Geometric viewpoint — proportional distances



$$\alpha = \frac{L_{BC}(x, y)}{L_{BC}(x_A, y_A)}$$

**Similar construction
for other coordinates**

Barycentric Coordinate Formulas



$$(x, y) = \alpha A + \beta B + \gamma C$$

$$\alpha + \beta + \gamma = 1$$

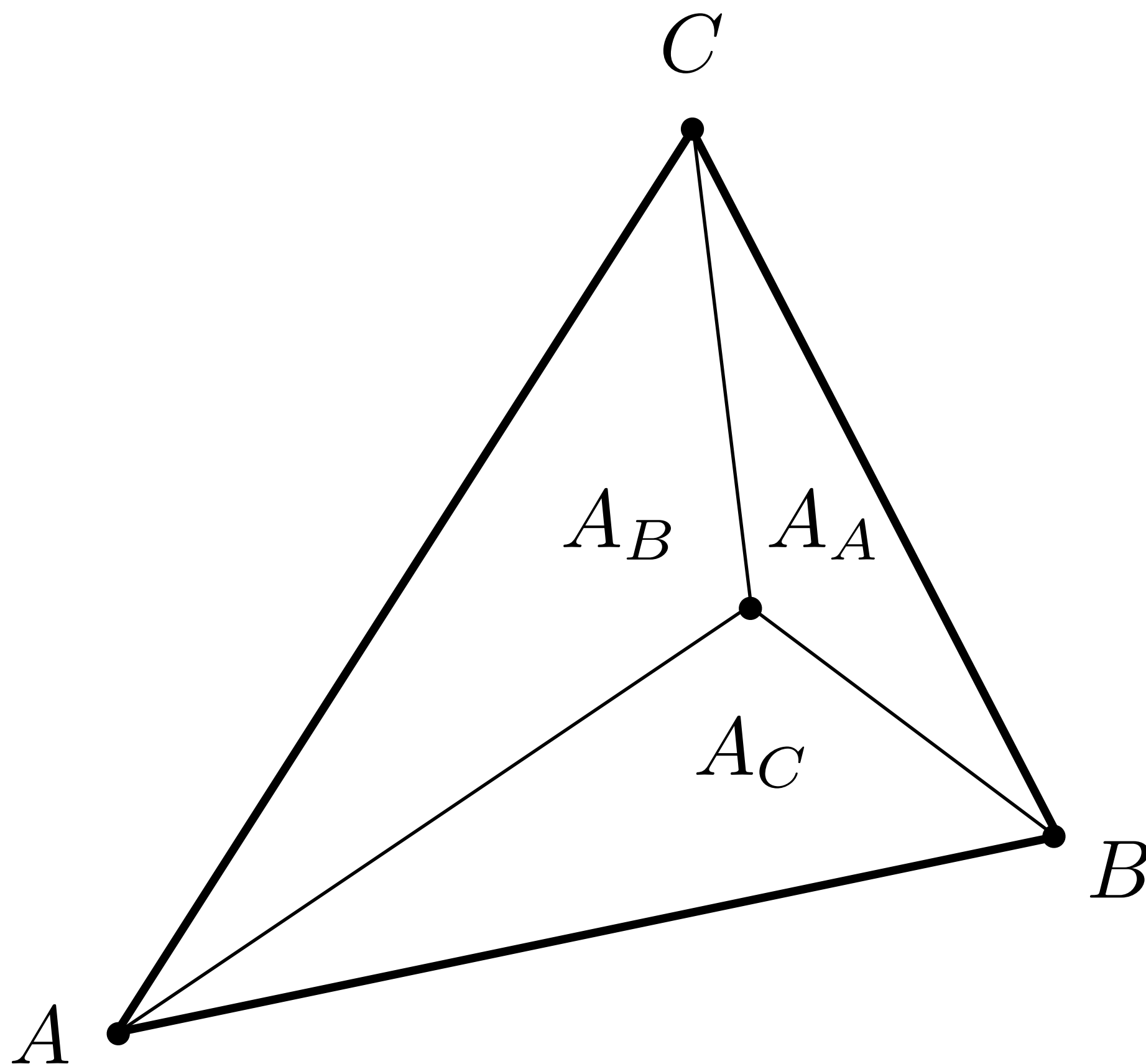
$$\alpha = \frac{-(x - x_B)(y_C - y_B) + (y - y_B)(x_C - x_B)}{-(x_A - x_B)(y_C - y_B) + (y_A - y_B)(x_C - x_B)}$$

$$\beta = \frac{-(x - x_C)(y_A - y_C) + (y - y_C)(x_A - x_C)}{-(x_B - x_C)(y_A - y_C) + (y_B - y_C)(x_A - x_C)}$$

$$\gamma = 1 - \alpha - \beta$$

Barycentric Coordinates

Alternative geometric viewpoint — proportional areas



$$\alpha = \frac{A_A}{A_A + A_B + A_C}$$

$$\beta = \frac{A_B}{A_A + A_B + A_C}$$

$$\gamma = \frac{A_C}{A_A + A_B + A_C}$$

Barycentric Coordinates

Linear Algebra View

$$(x, y) = \alpha A + \beta B + \gamma C$$

Barycentric Coordinates

Linear Algebra View

$$(x, y) = \alpha A + \beta B + \gamma C$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \alpha \begin{bmatrix} A_x \\ A_y \end{bmatrix} + \beta \begin{bmatrix} B_x \\ B_y \end{bmatrix} + \gamma \begin{bmatrix} C_x \\ C_y \end{bmatrix}$$

Barycentric Coordinates

Linear Algebra View

$$(x, y) = \alpha A + \beta B + \gamma C$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \alpha \begin{bmatrix} A_x \\ A_y \end{bmatrix} + \beta \begin{bmatrix} B_x \\ B_y \end{bmatrix} + \gamma \begin{bmatrix} C_x \\ C_y \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \\ 1 \end{bmatrix} = \begin{bmatrix} A_x & B_x & C_x \\ A_y & B_y & C_y \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix}$$

Barycentric Coordinates

Linear Algebra View

$$(x, y) = \alpha A + \beta B + \gamma C$$

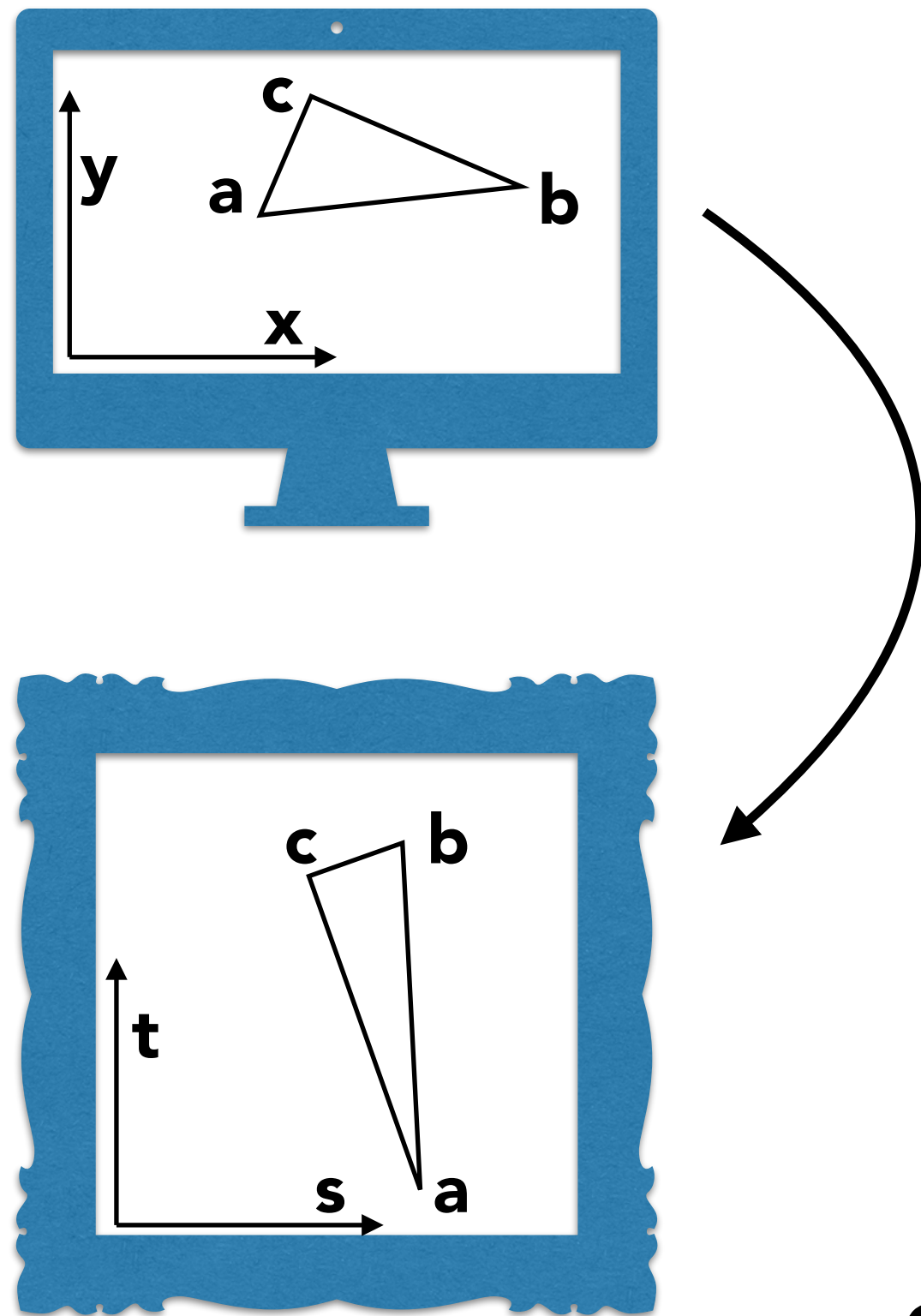
$$\begin{bmatrix} x \\ y \end{bmatrix} = \alpha \begin{bmatrix} A_x \\ A_y \end{bmatrix} + \beta \begin{bmatrix} B_x \\ B_y \end{bmatrix} + \gamma \begin{bmatrix} C_x \\ C_y \end{bmatrix}$$

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$$\begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = M^{-1} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Barycentric Coordinates

Linear Algebra View



$$\begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = M_{\text{screen}}^{-1} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

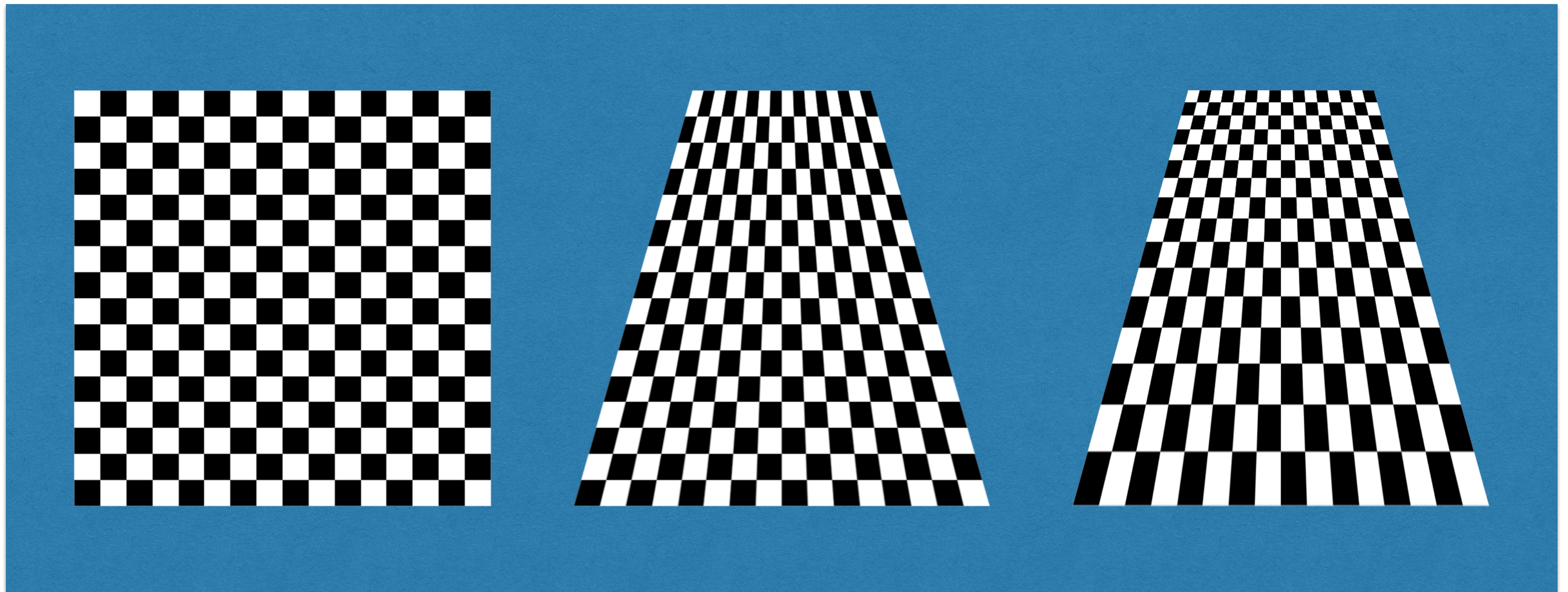
$$\begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = M_{\text{texture}}^{-1} \begin{bmatrix} s \\ t \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} s \\ t \\ 1 \end{bmatrix} = M_{\text{texture}} M_{\text{screen}}^{-1} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Consider SVD of

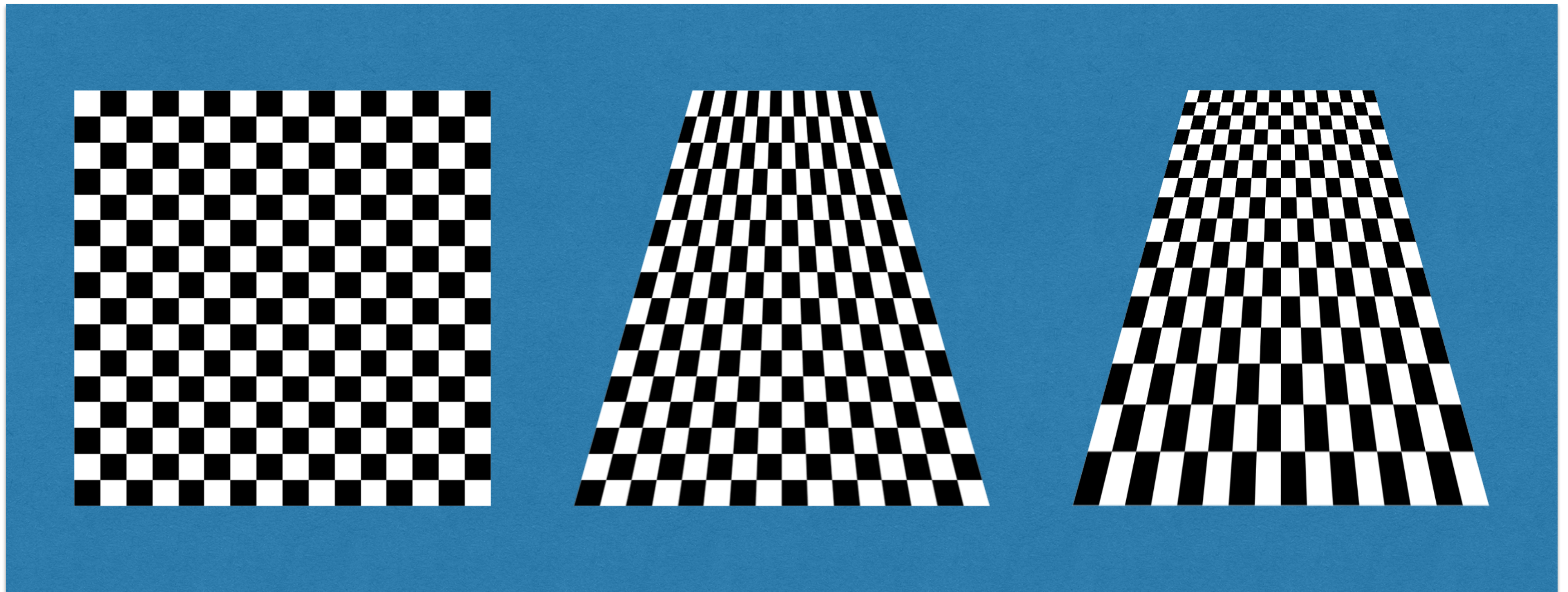
Perspective Projection and Interpolation

Perspective Projection and Interpolation



Original Texture

Perspective Projection and Interpolation

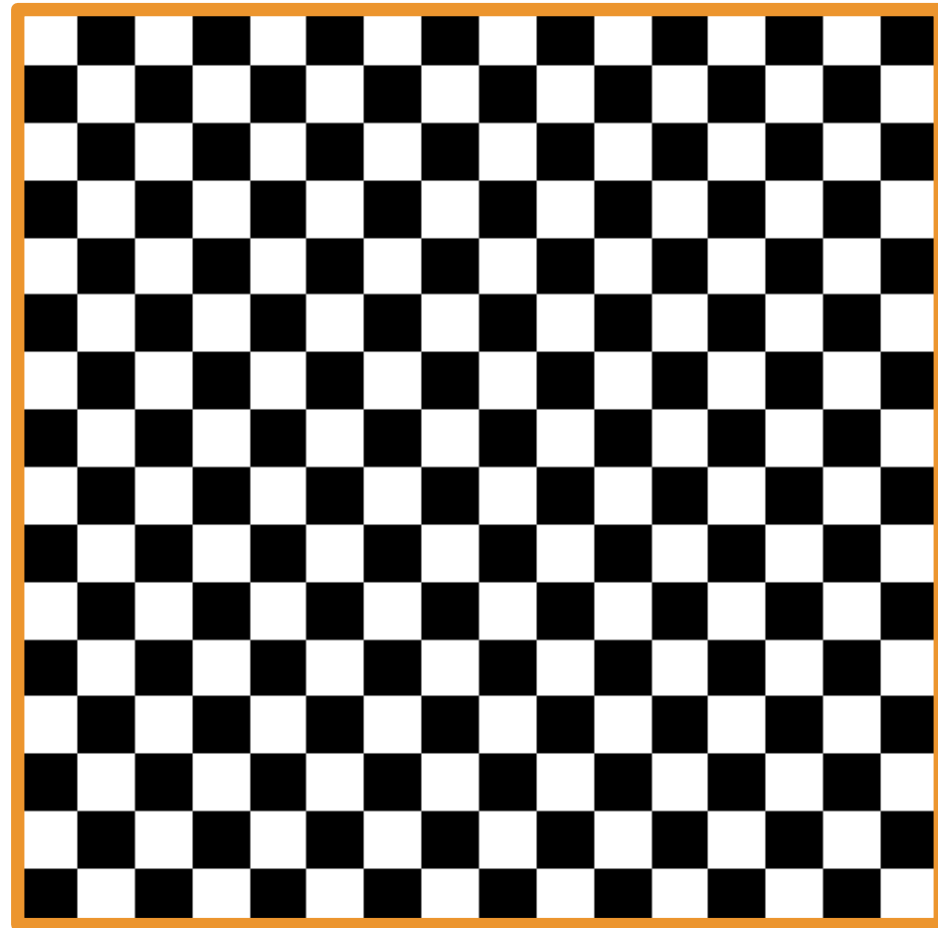


Original Texture

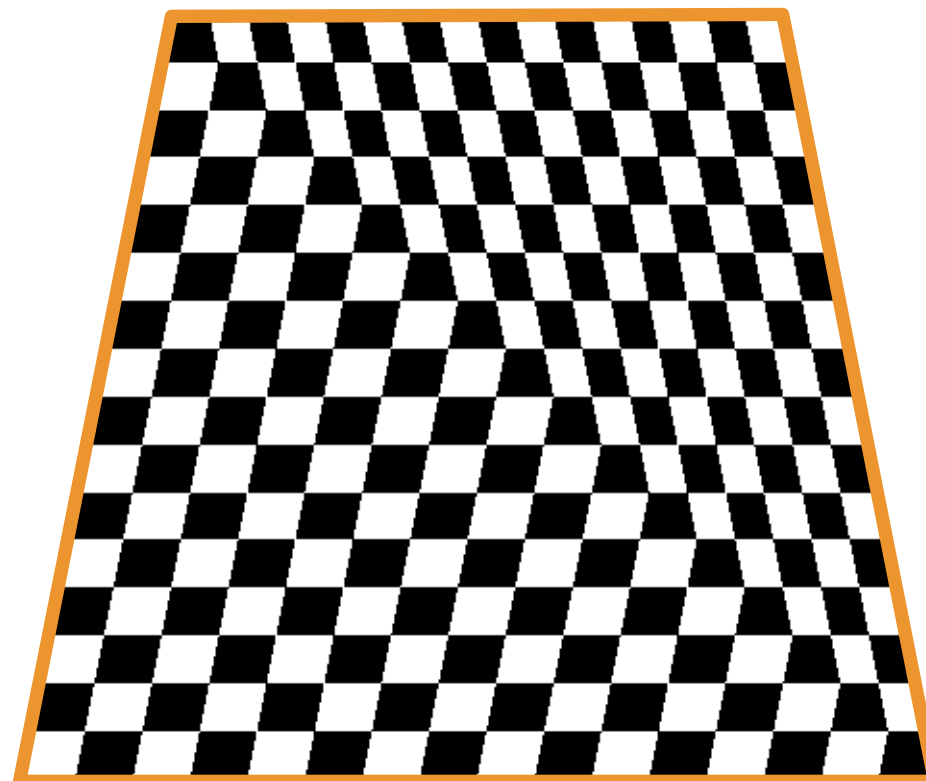
Linear/Affine Distortion
(Top is "squished")

Perspective Distortion
(Plane tilted away from viewer)

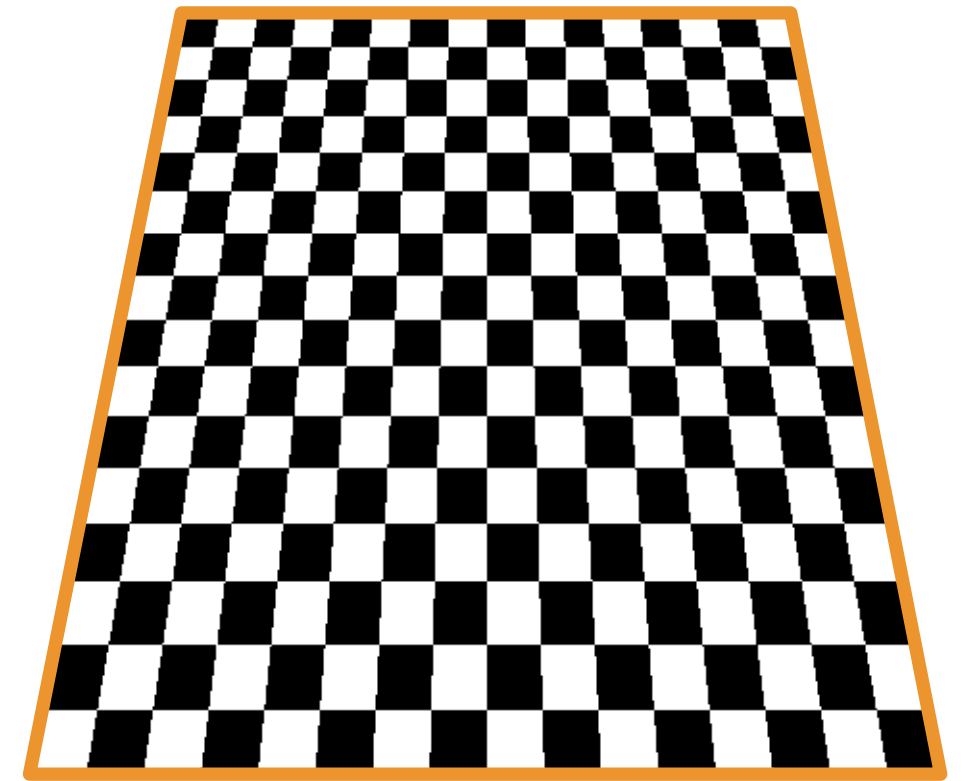
Perspective Projection and Interpolation



Texture



**Barycentric
interpolation of
texture
coordinates in
screen-space**

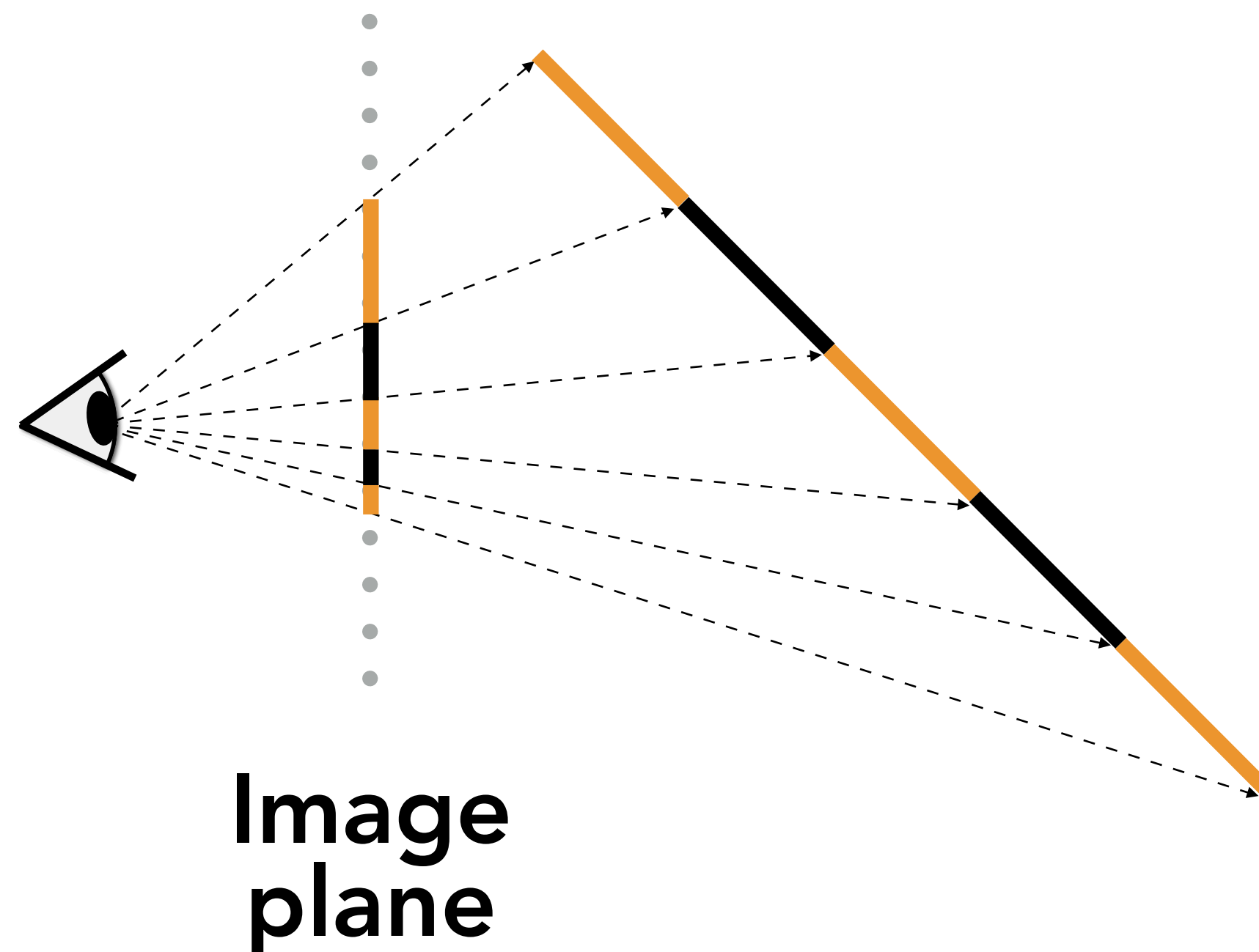


Correct image

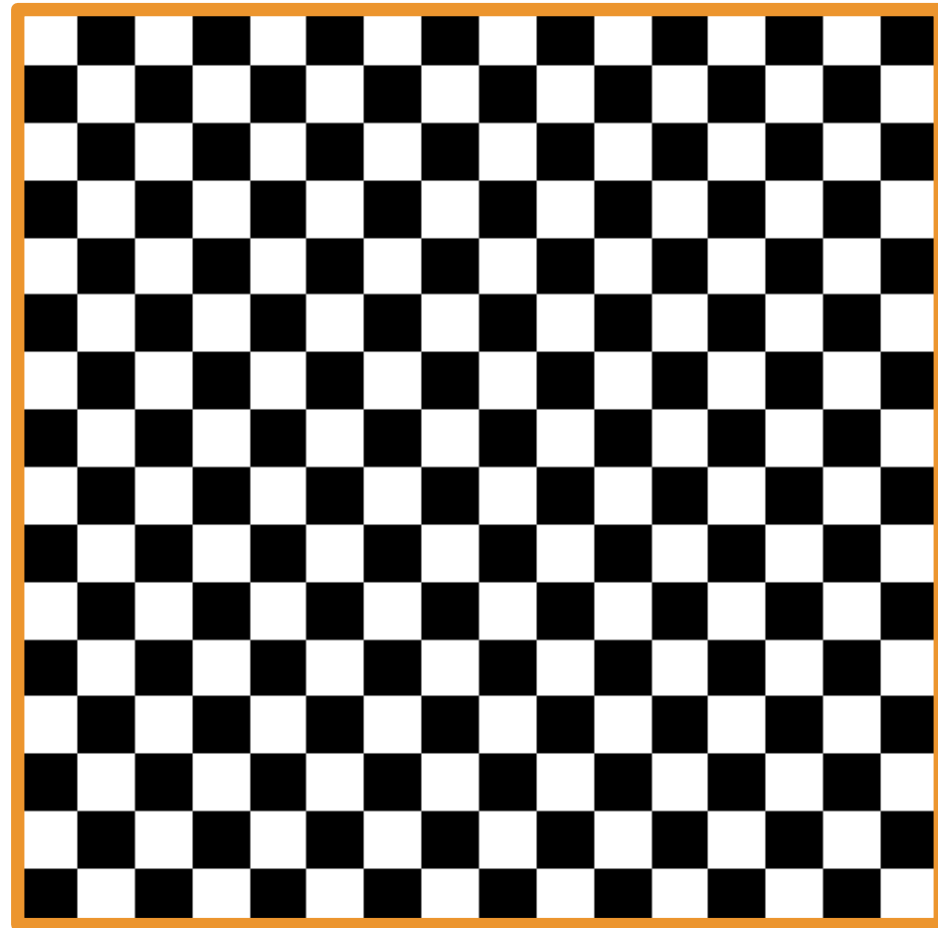
Perspective Projection Creates Non Linearity

Linear interpolation in world coordinates yields
nonlinear interpolation in screen coordinates!

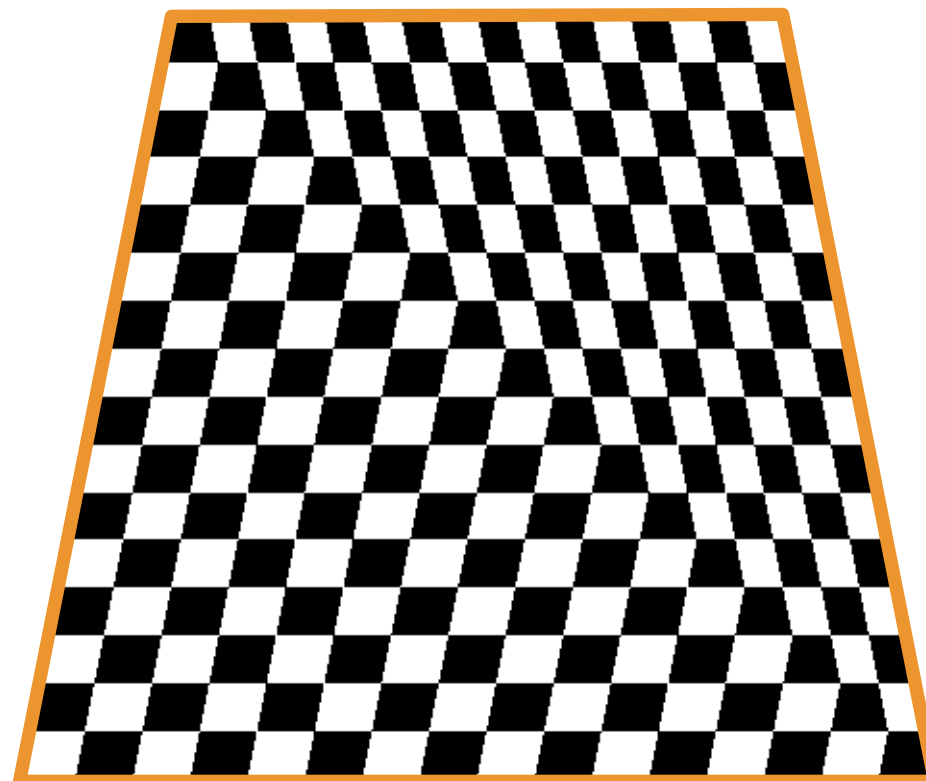
Perspective interpolation supported in GPU



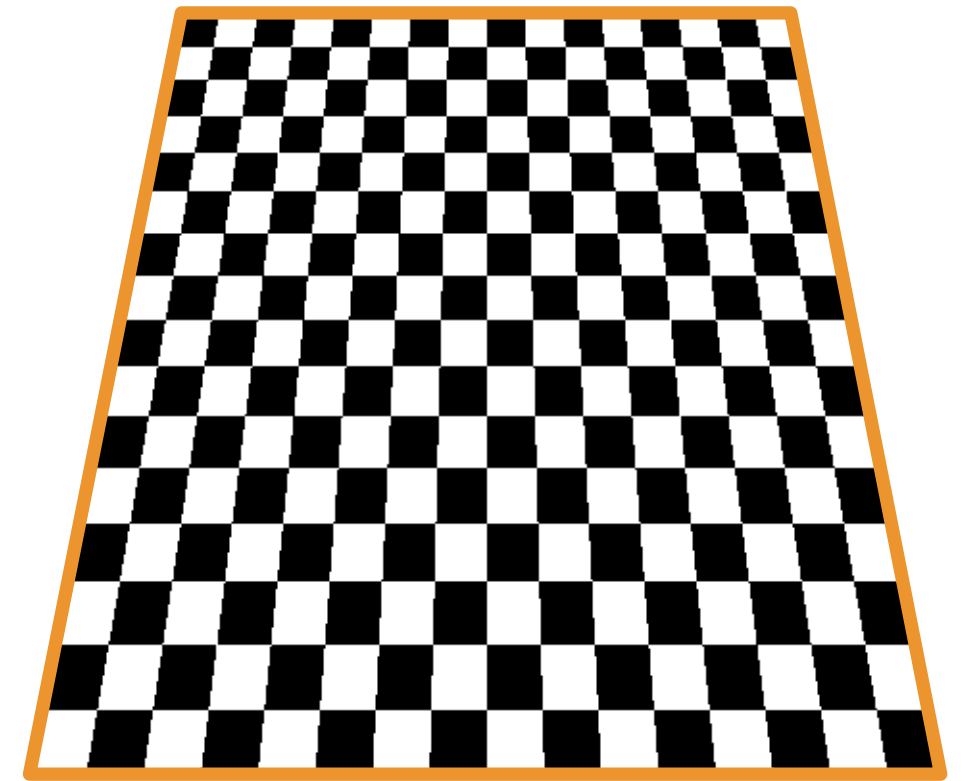
Perspective-Correct Interpolation



Texture



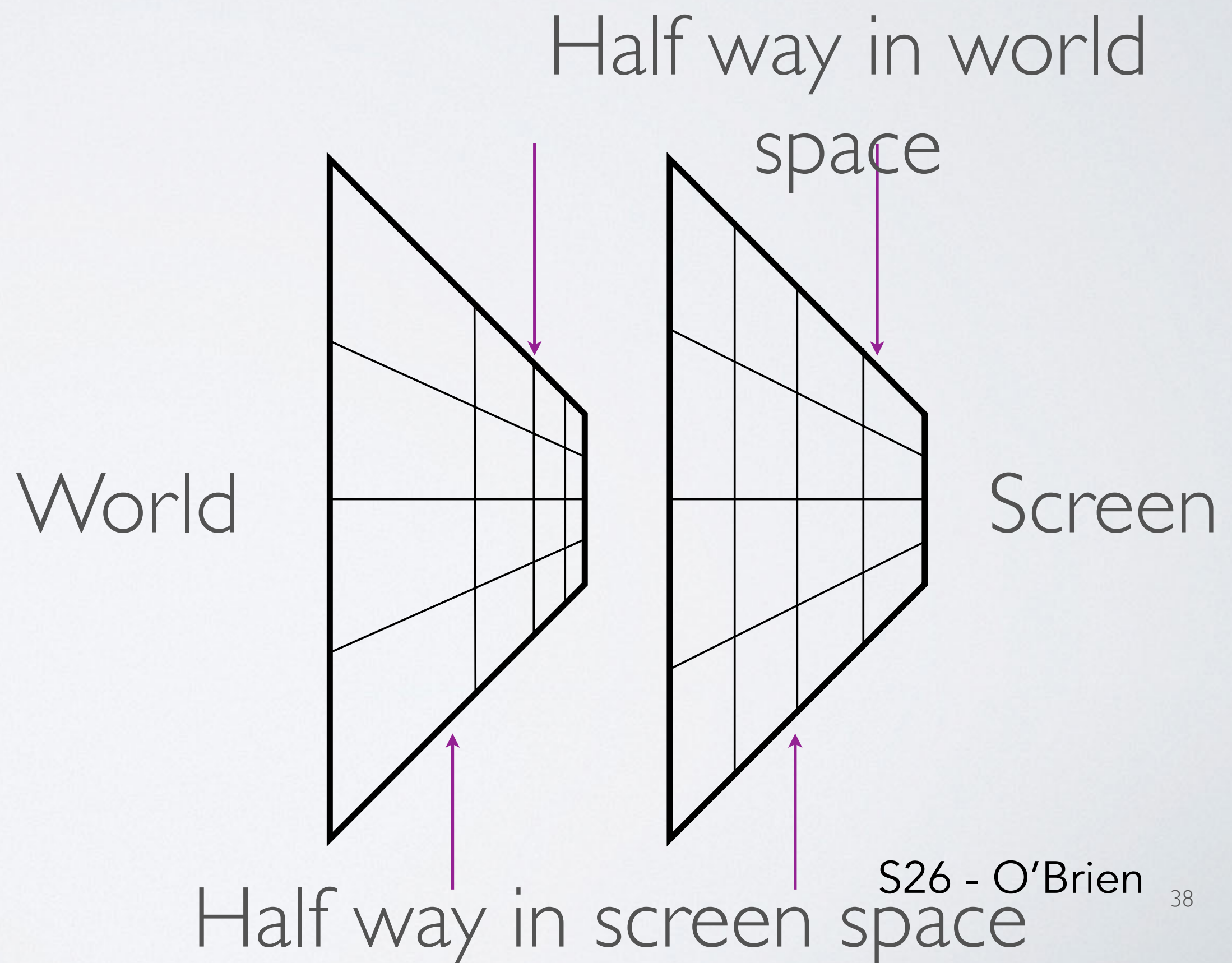
**Affine
screen-space
interpolation**



**Perspective
world-space
interpolation**

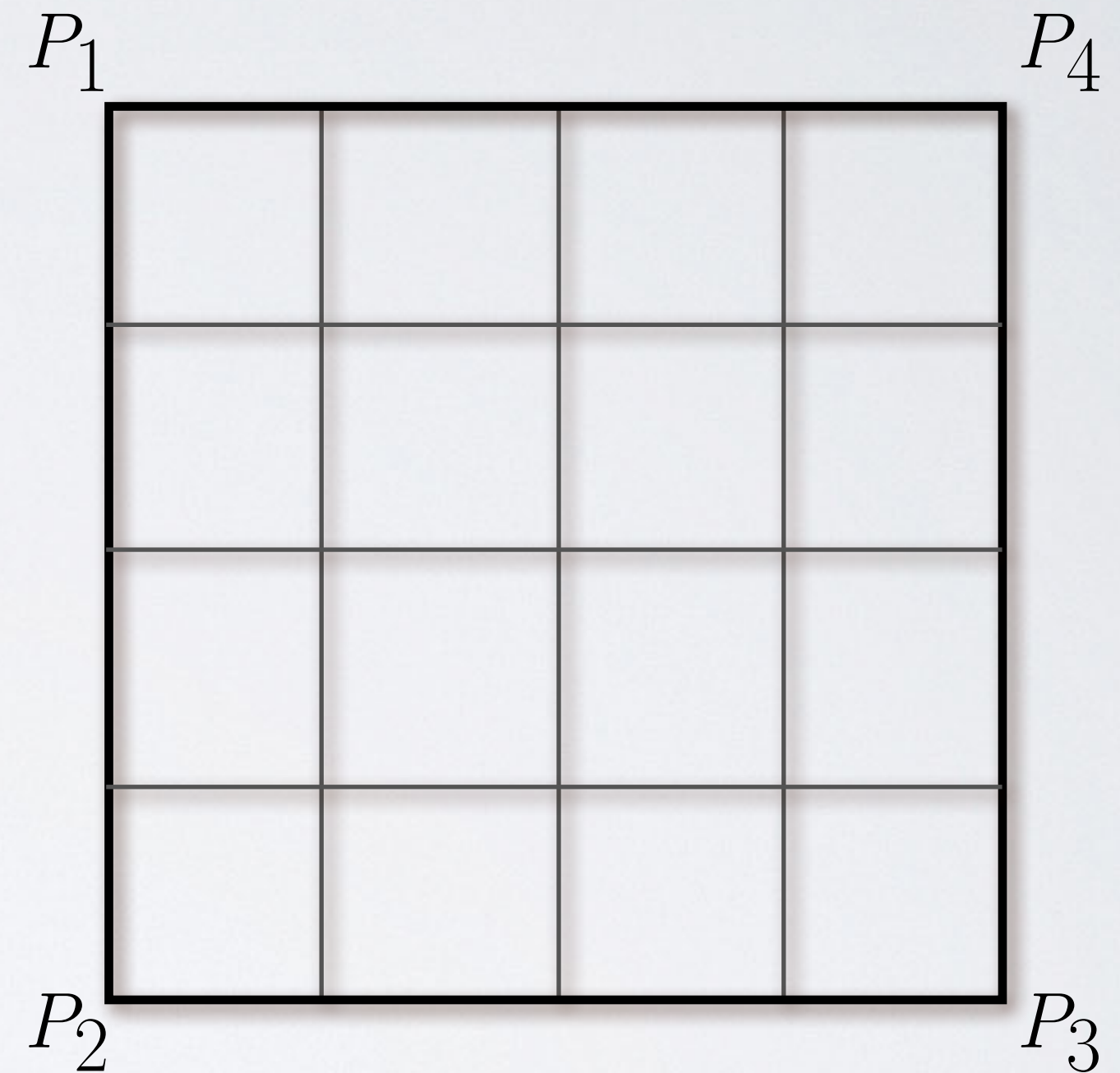
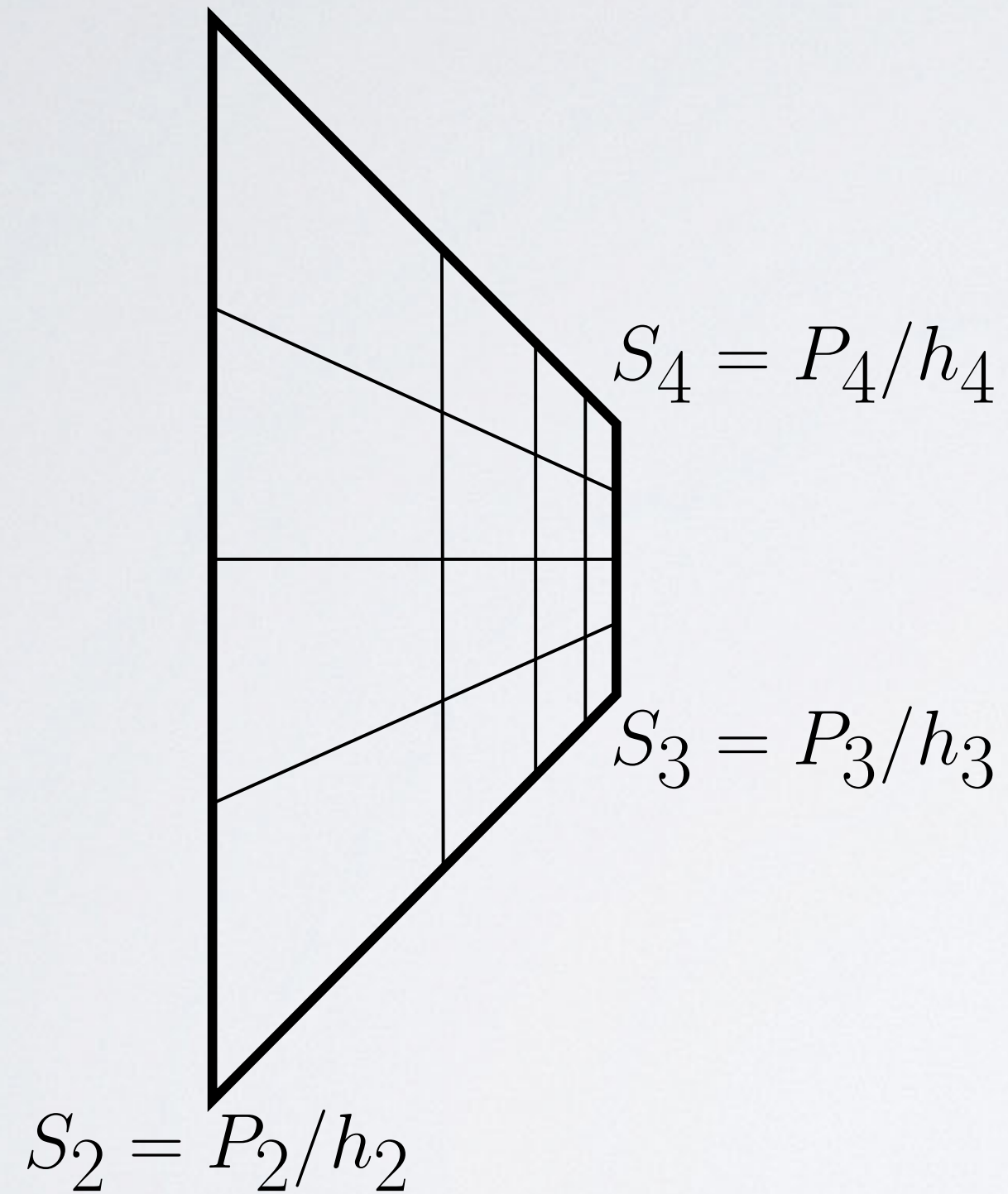
Depth Distortion

- Recall depth distortion from perspective
 - Interpolating in screen space different than in world
 - Ok, for shading (mostly)
 - Bad for texture

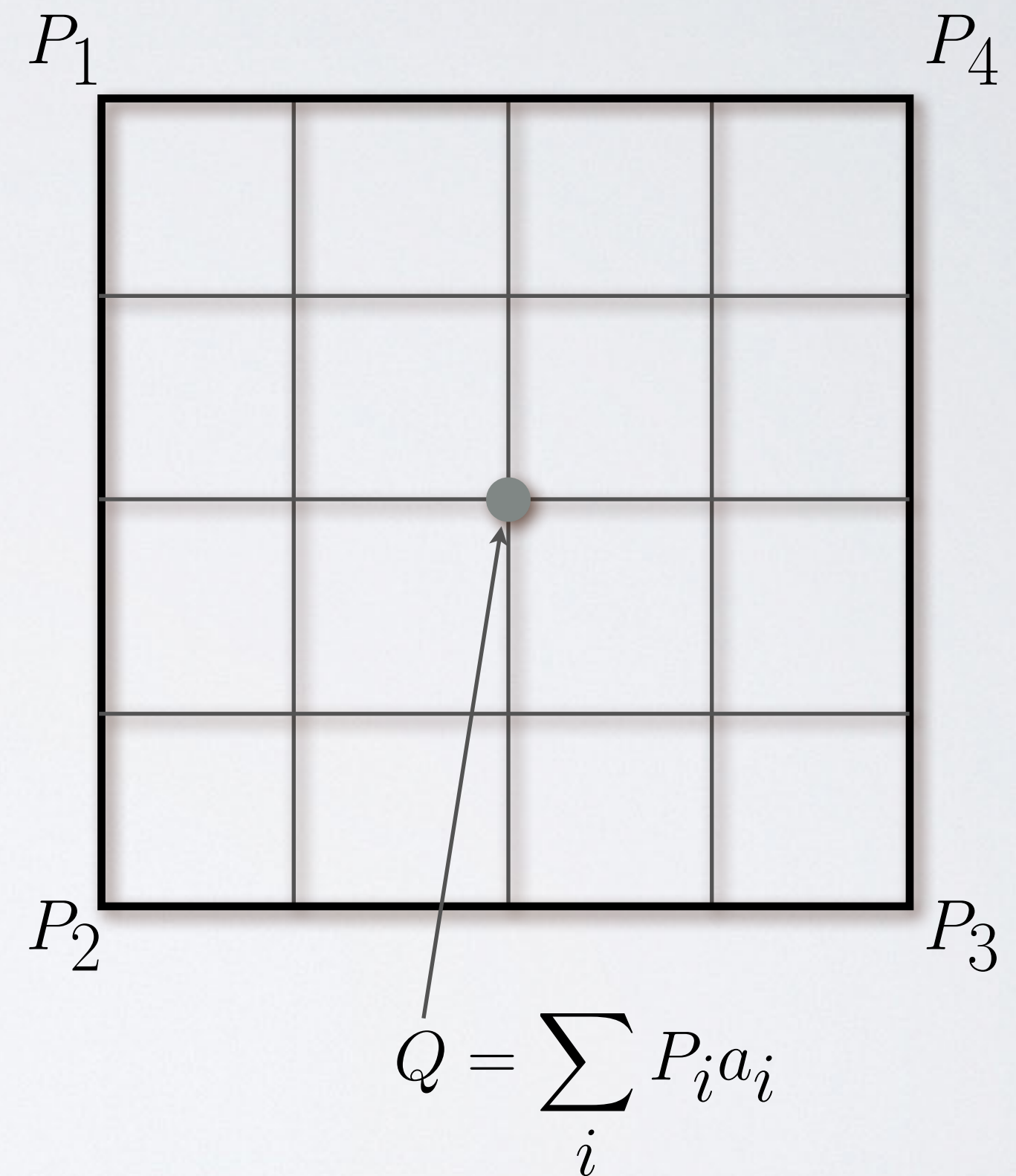
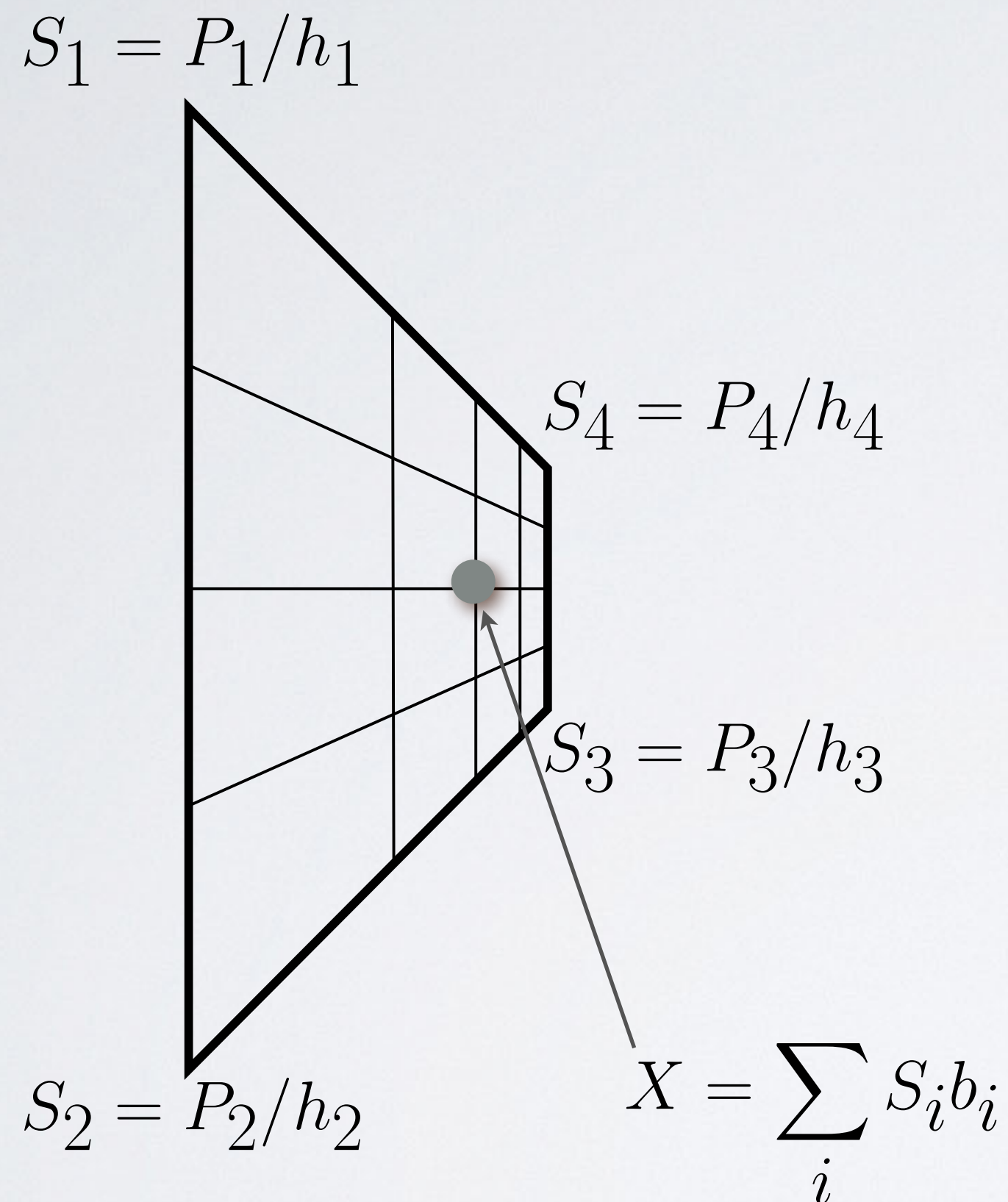


Depth Distortion

$$S_1 = P_1/h_1$$



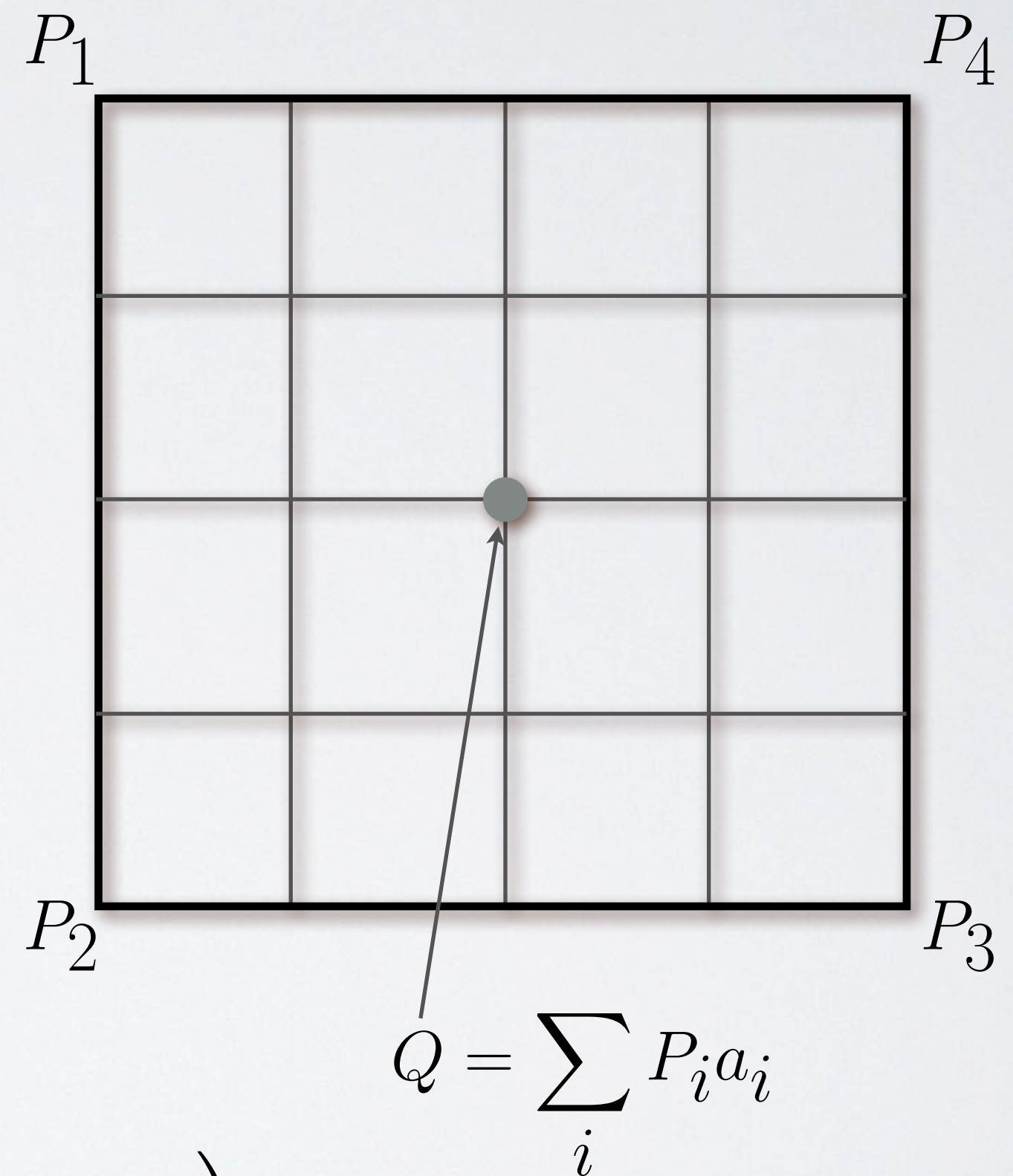
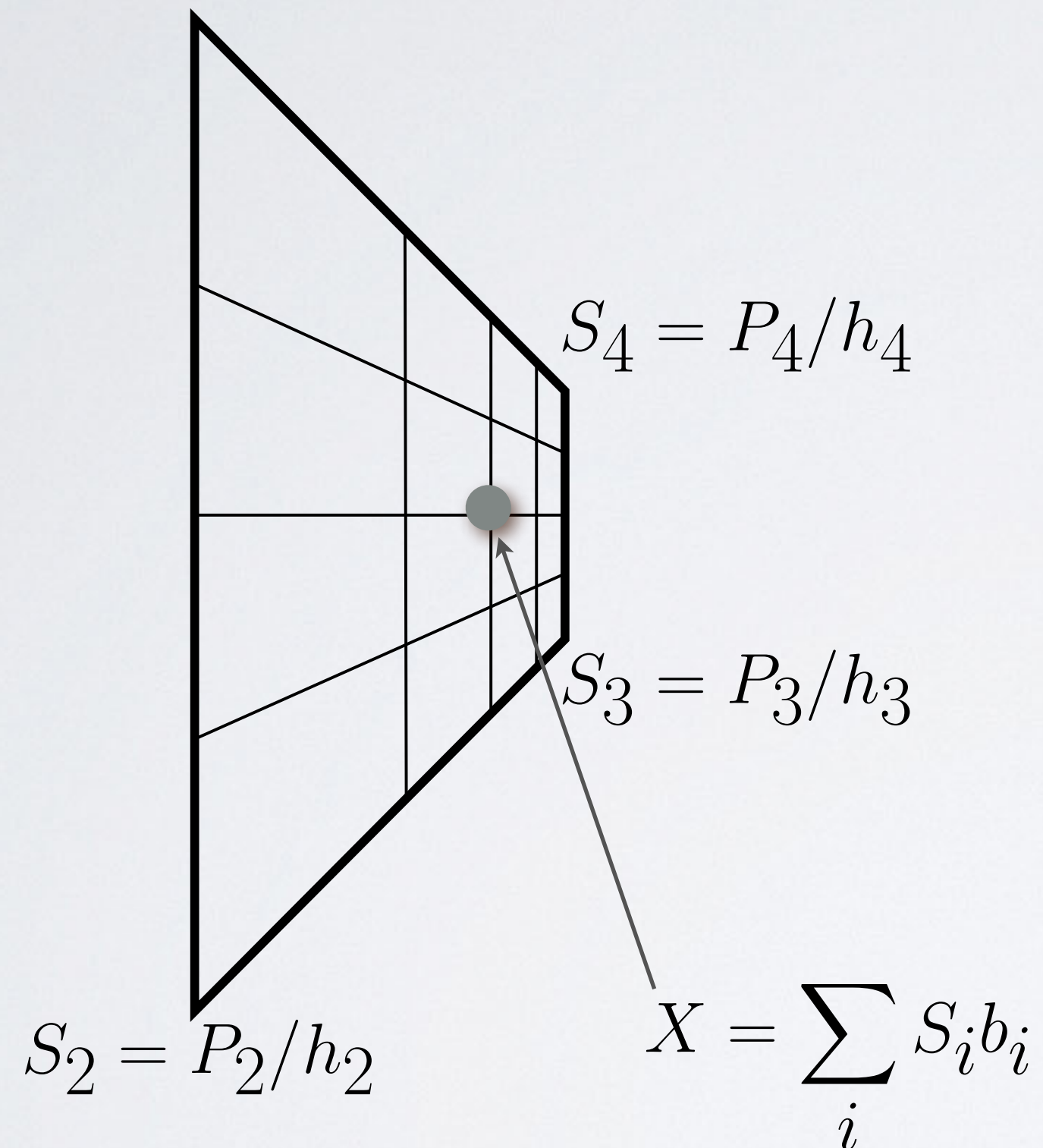
Depth Distortion



We know the S_i , P_i , and b_i , but not the a_i

Depth Distortion

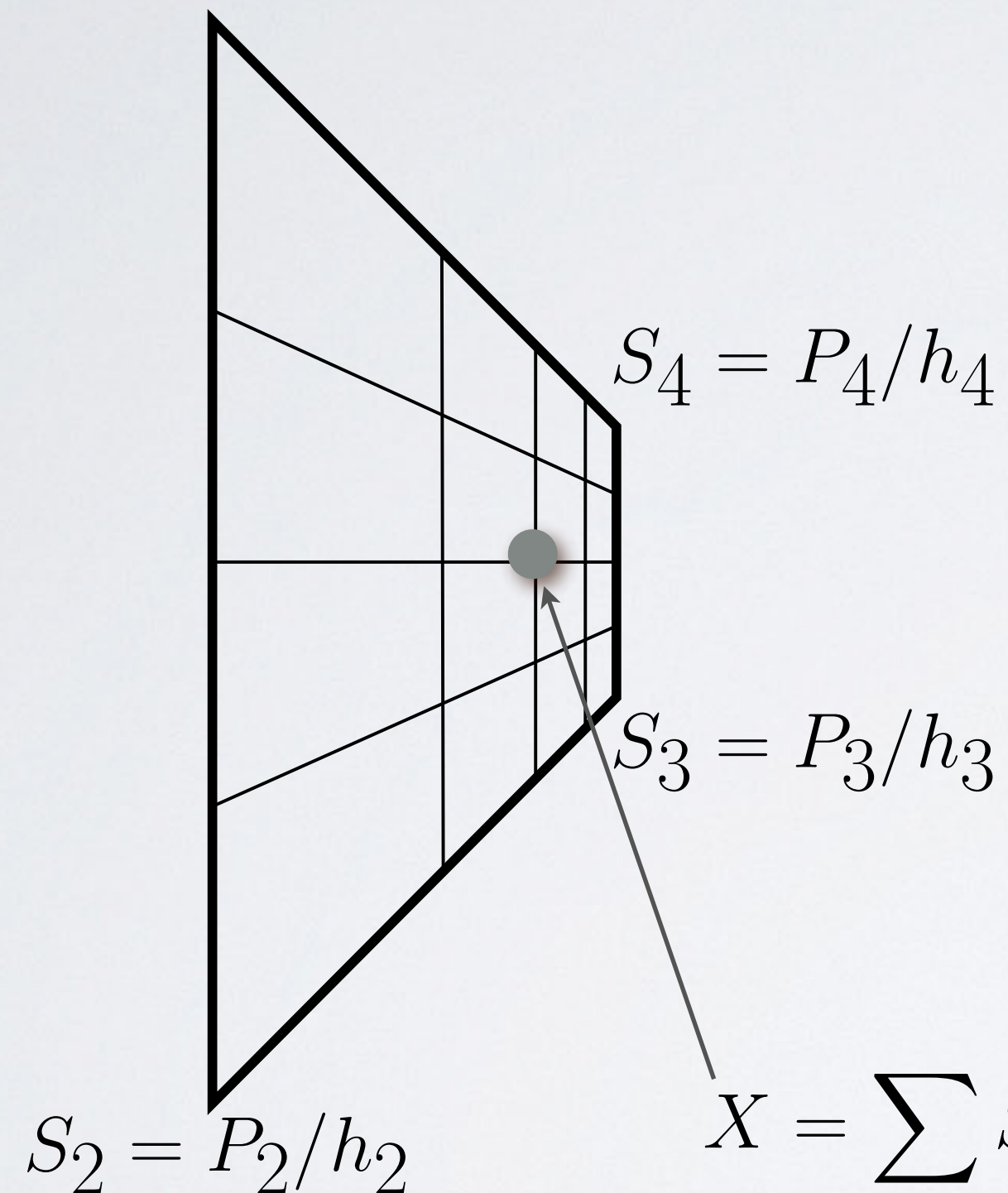
$$S_1 = P_1/h_1$$



$$X = Q/h = \left(\sum_i P_i a_i \right) / \left(\sum_j h_j a_j \right)$$

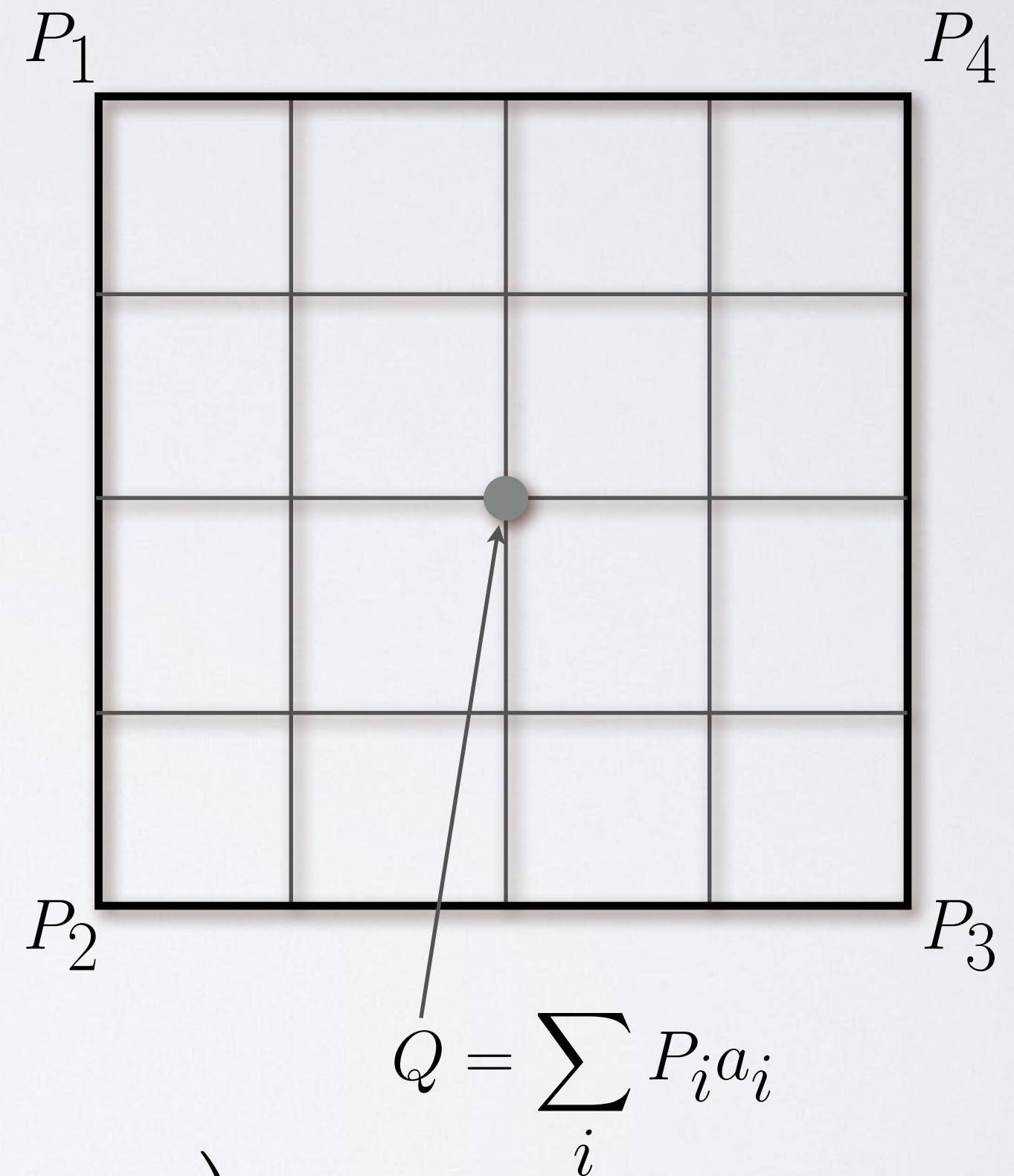
Depth Distortion

$$S_1 = P_1/h_1$$



$$X = \sum_i S_i b_i$$

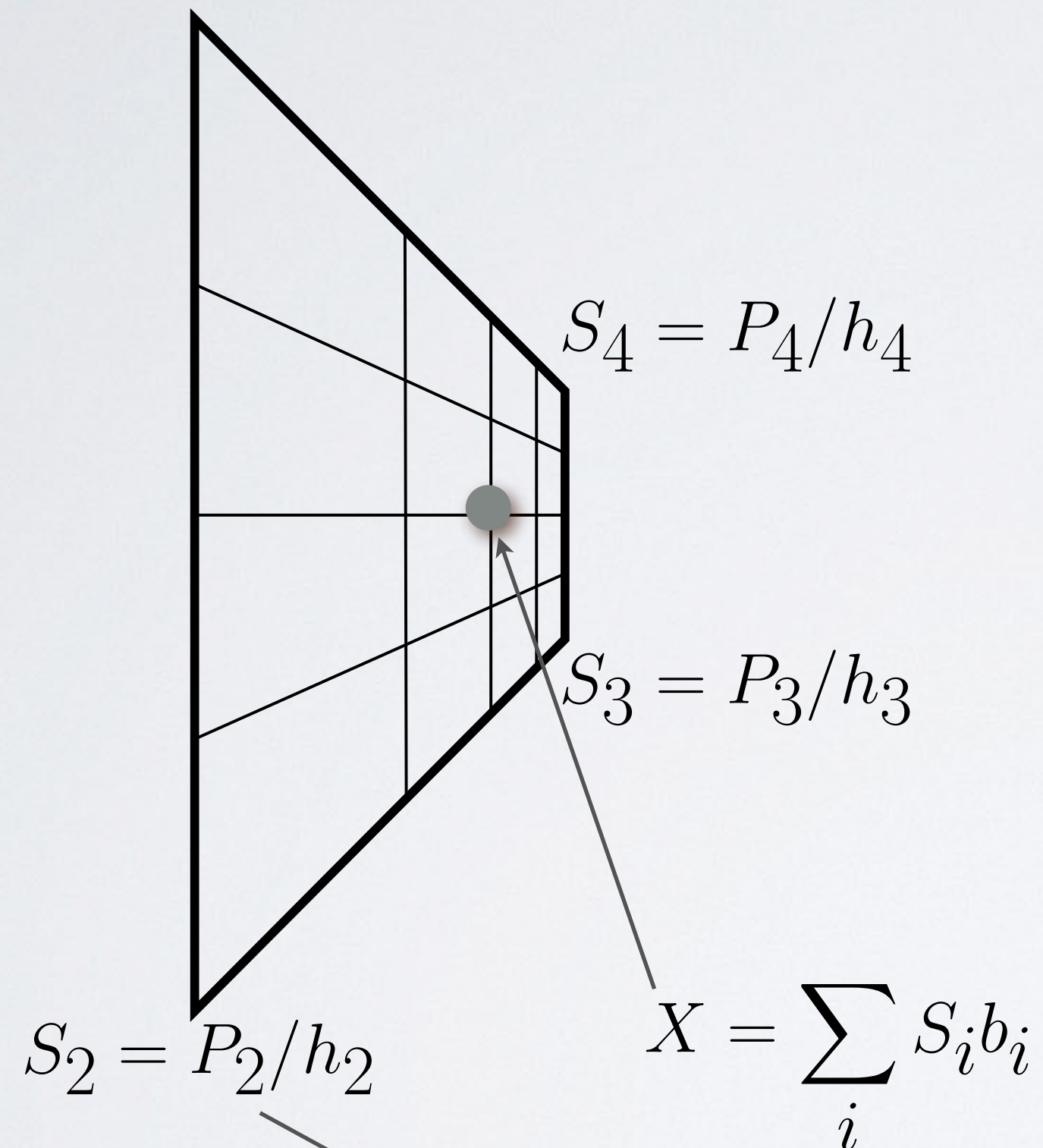
$$\sum_i S_i b_i = \left(\sum_i P_i a_i \right) / \left(\sum_j h_j a_j \right)$$



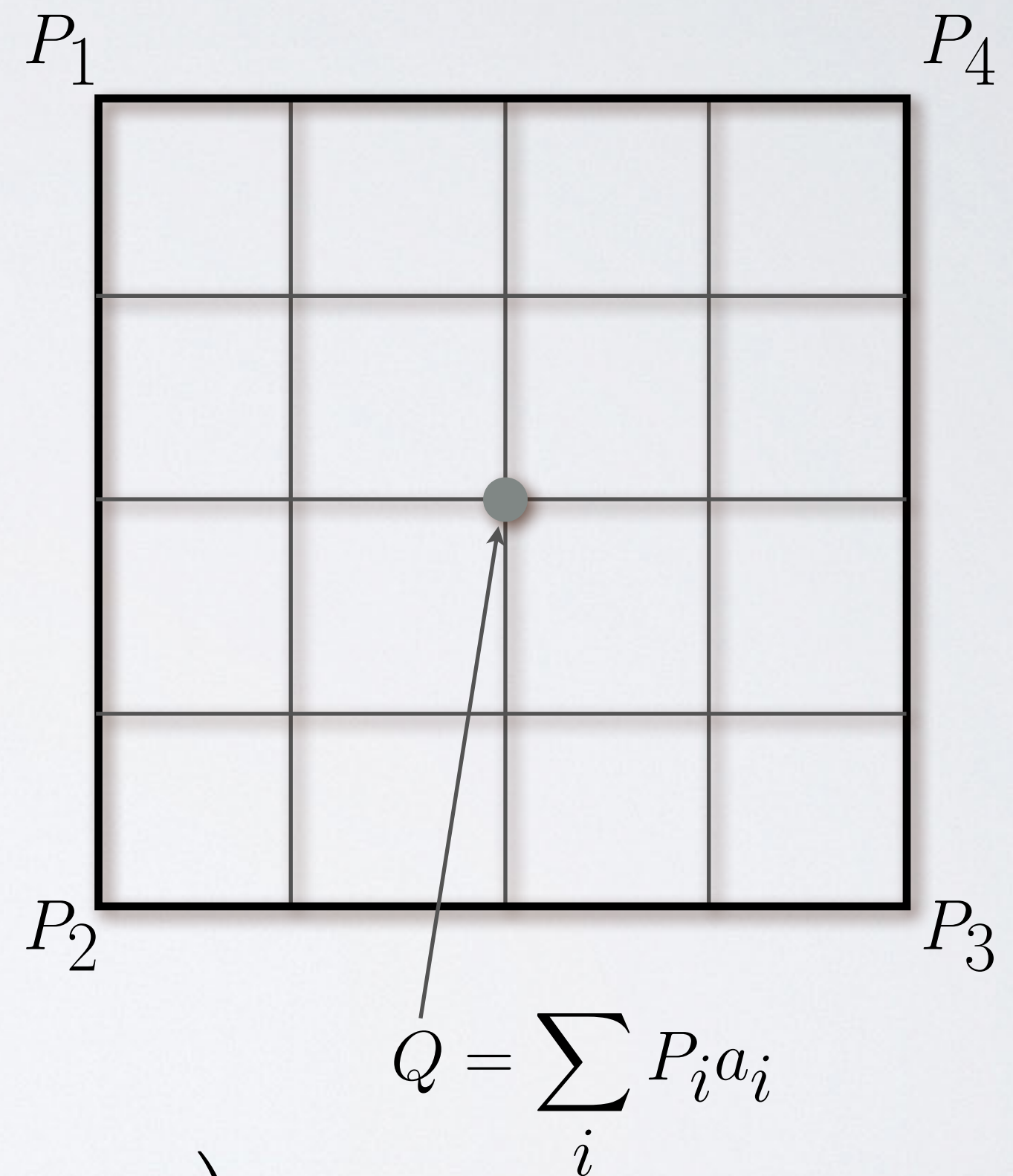
$$Q = \sum_i P_i a_i$$

Depth Distortion

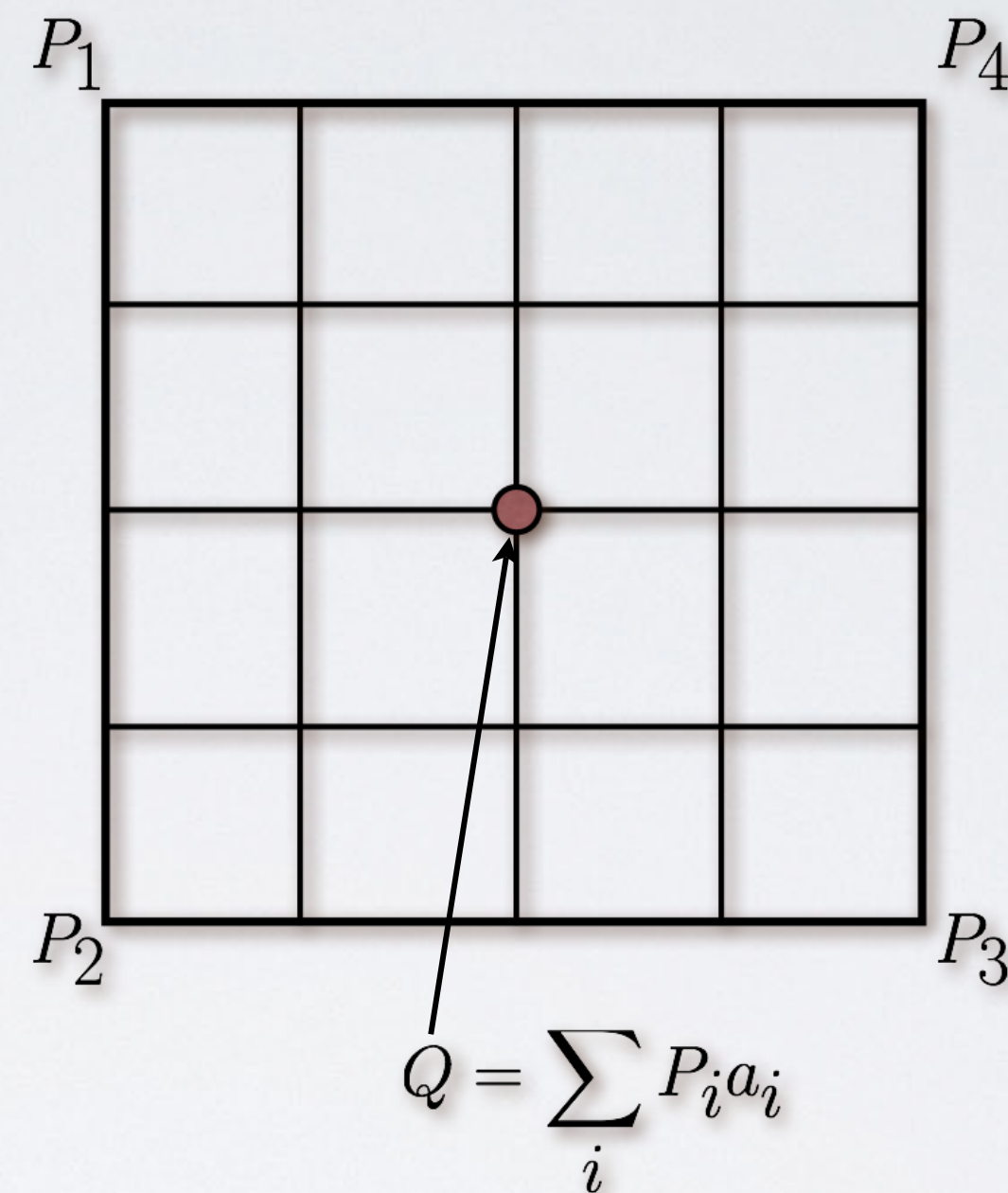
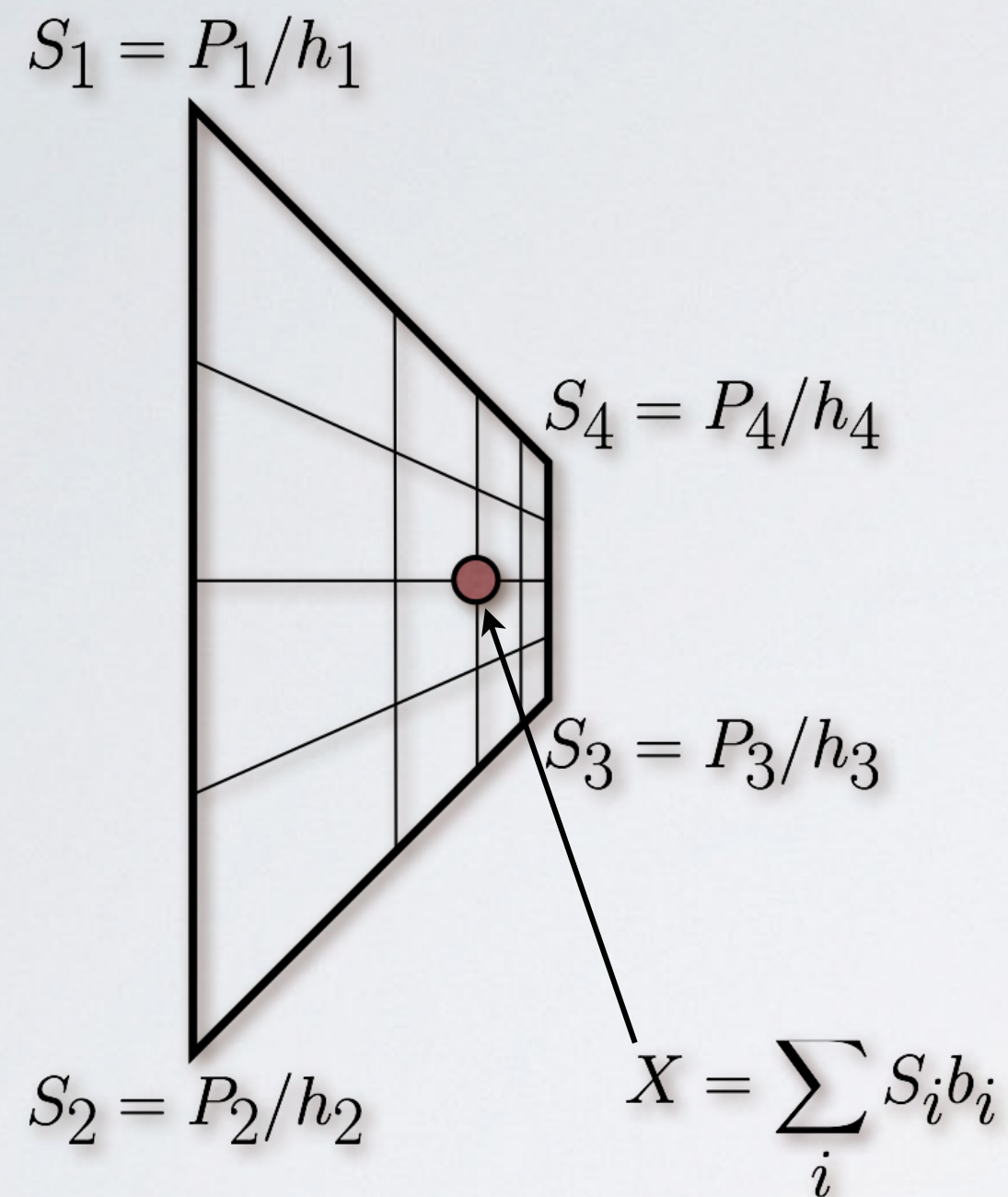
$$S_1 = P_1/h_1$$



$$\sum_i P_i b_i / h_i = \left(\sum_i P_i a_i \right) / \left(\sum_j h_j a_j \right)$$



Depth Distortion



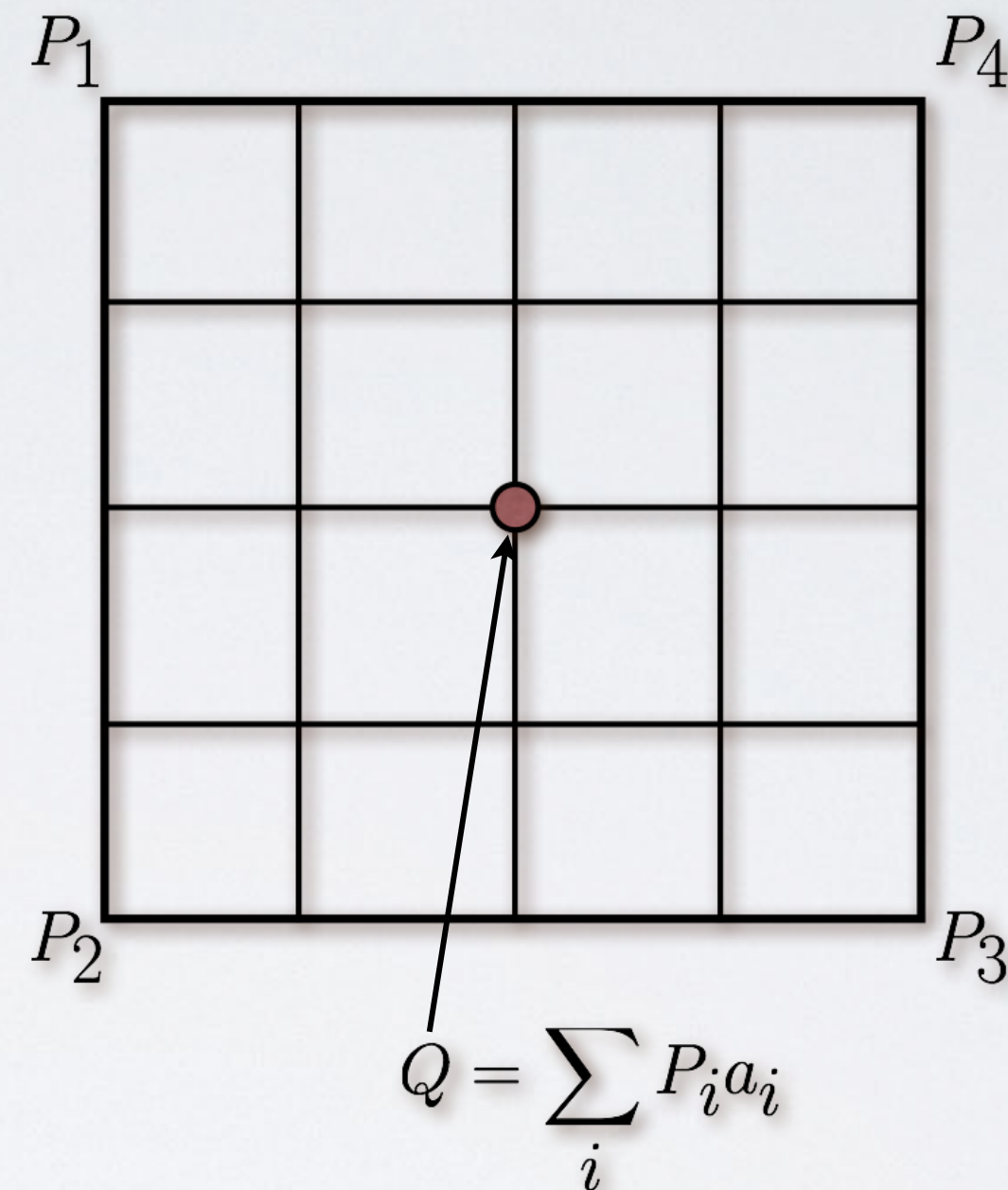
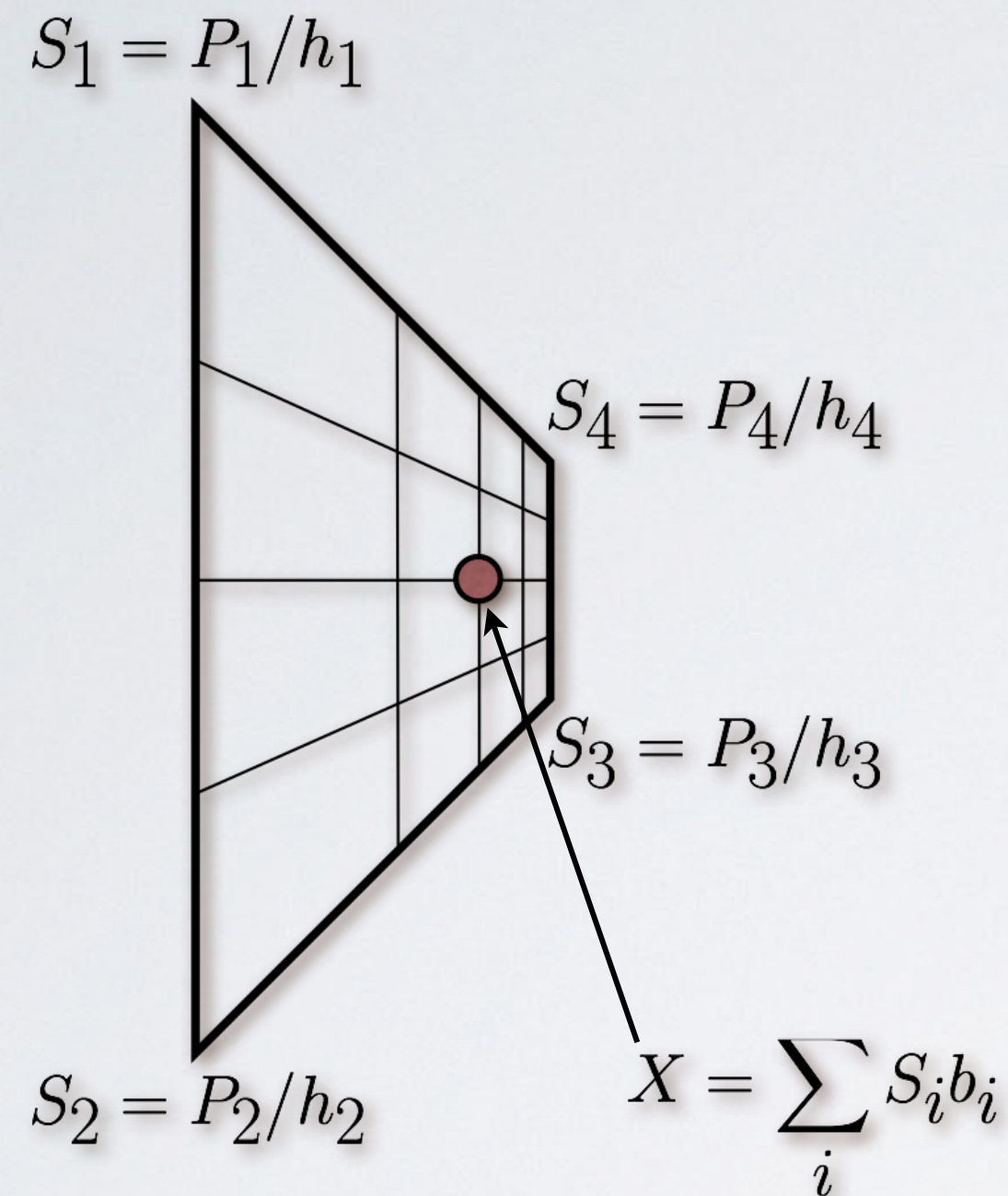
$$\sum_i P_i b_i / h_i = \left(\sum_i P_i a_i \right) / \left(\sum_j h_j a_j \right)$$

$$b_i / h_i = a_i / \left(\sum_j h_j a_j \right) \quad \forall i$$

S26 - O'Brien 42

Independent of given vertex locations.
CS184/284A

Depth Distortion

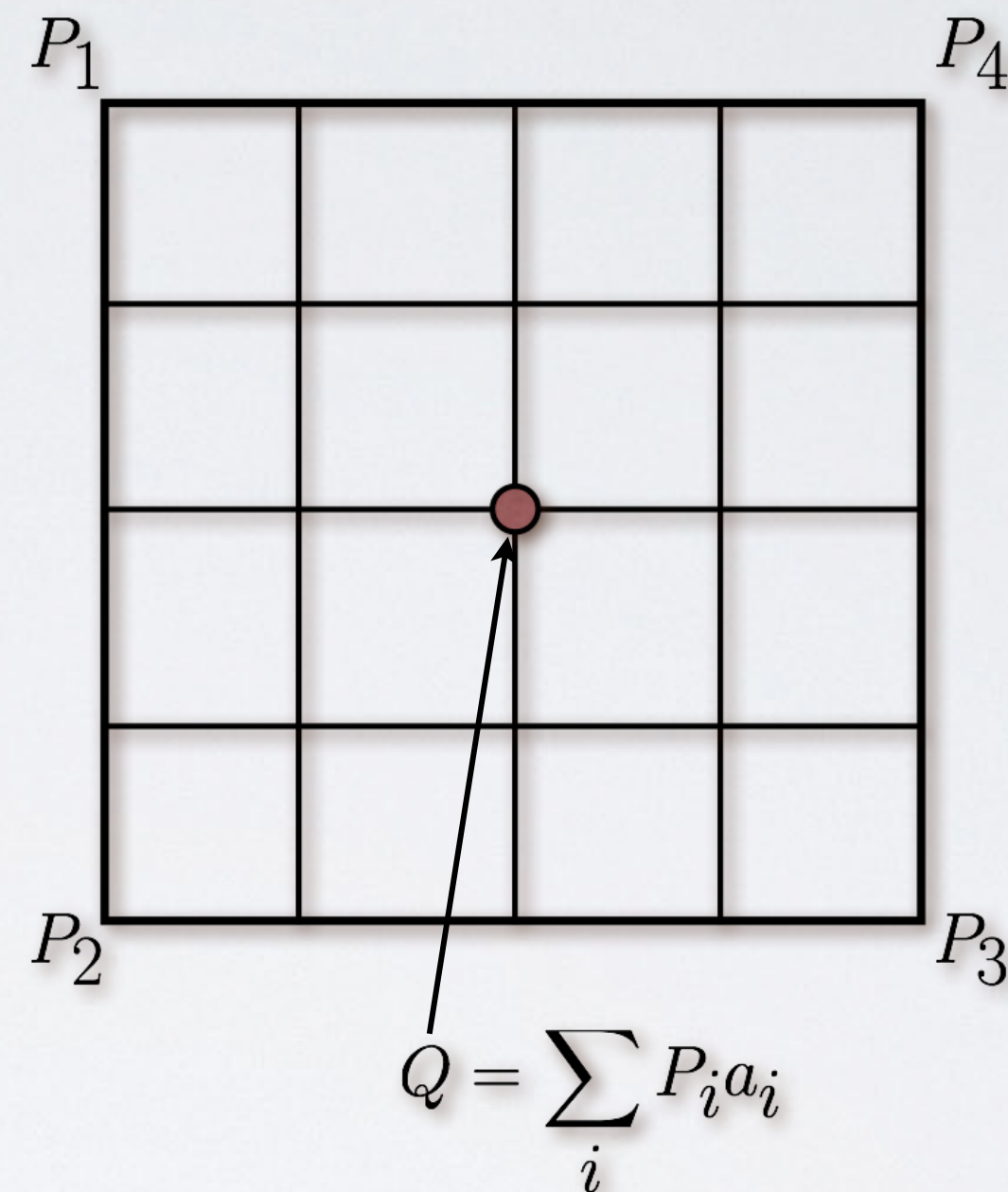
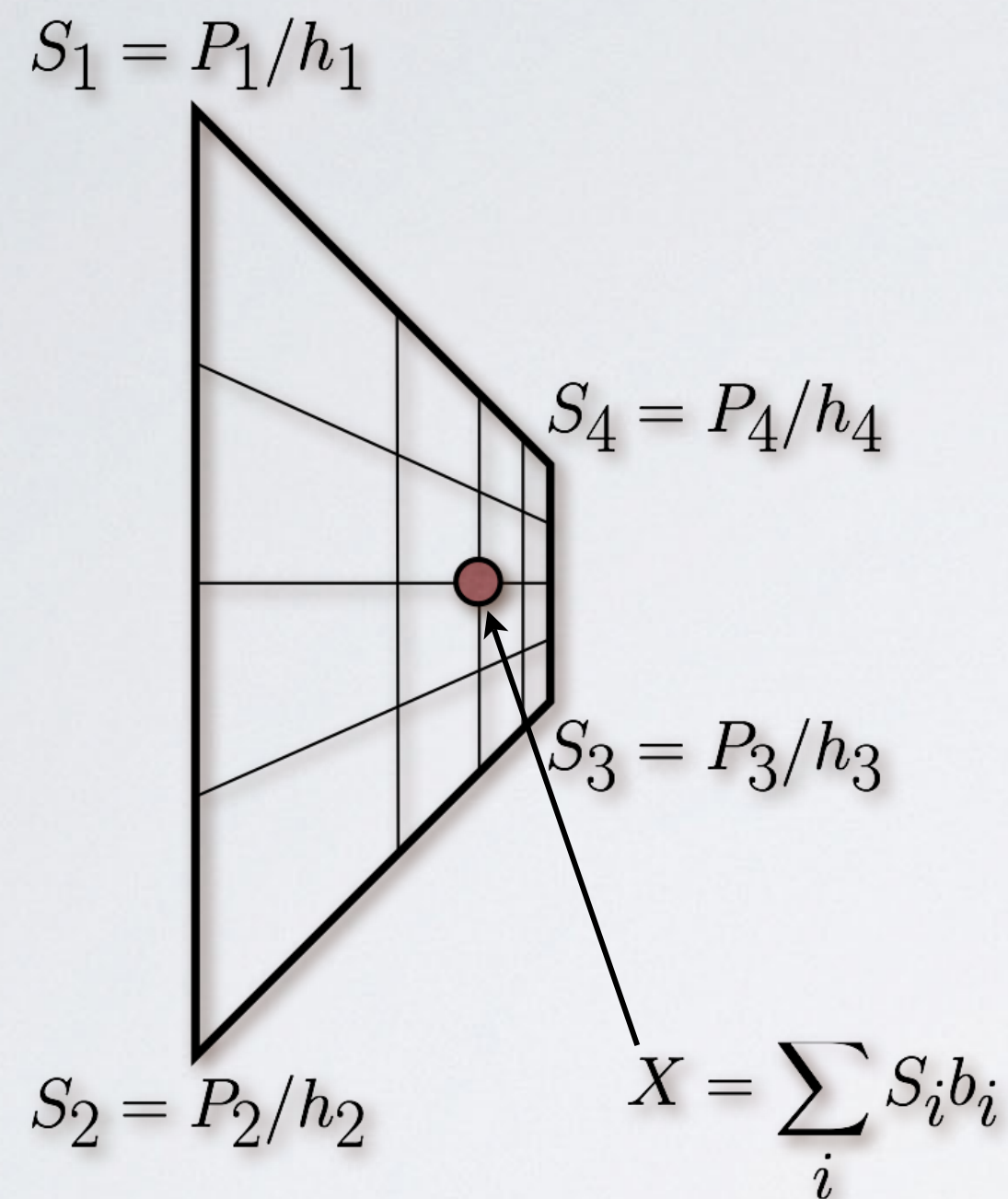


$$b_i/h_i = a_i / \left(\sum_j h_j a_j \right) \quad \forall i$$

$$\left(\sum_j h_j a_j \right) b_i/h_i - a_i = 0 \quad \forall i$$

Linear equations in the a_i .

Depth Distortion



Linear equations in the a_i .

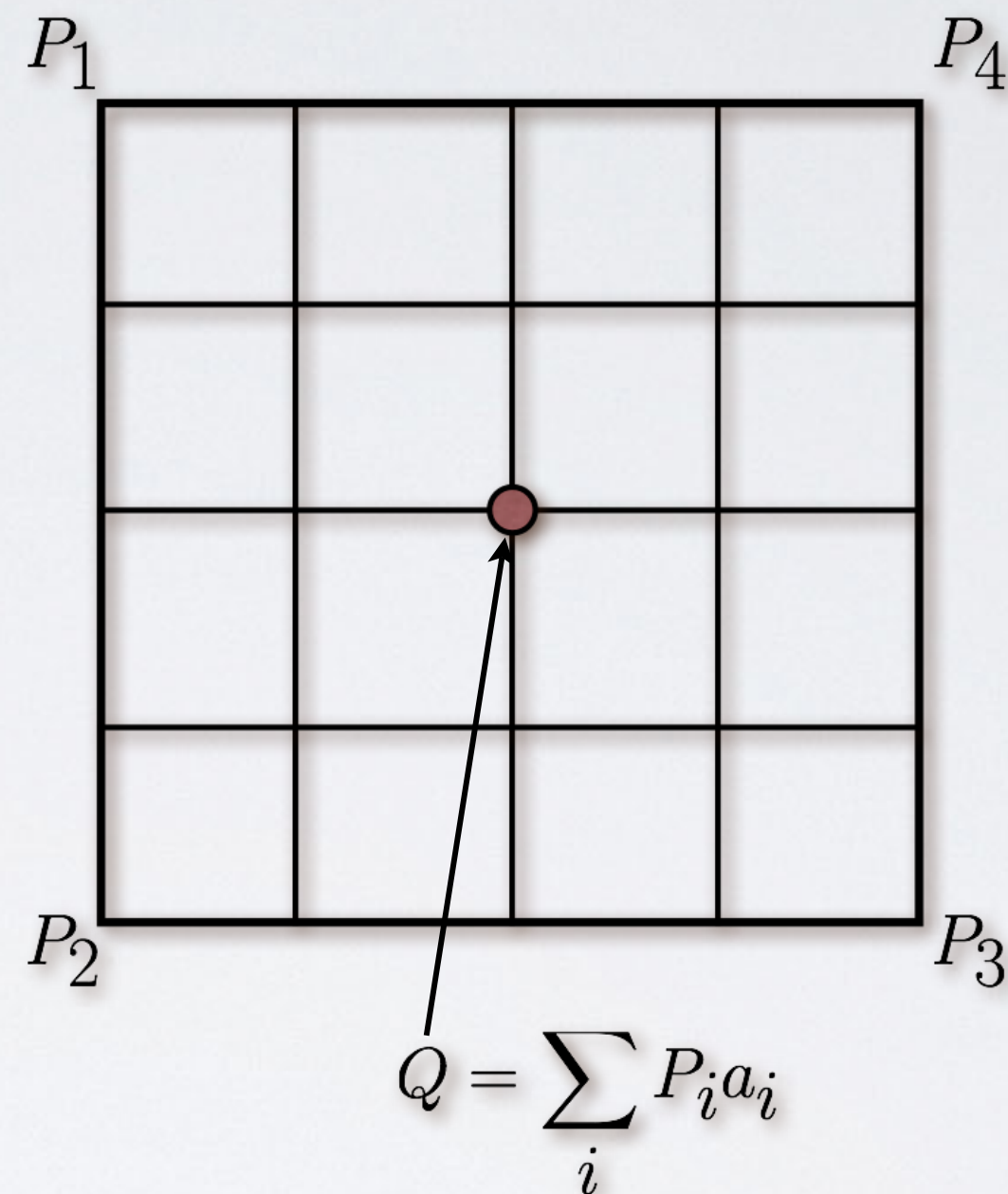
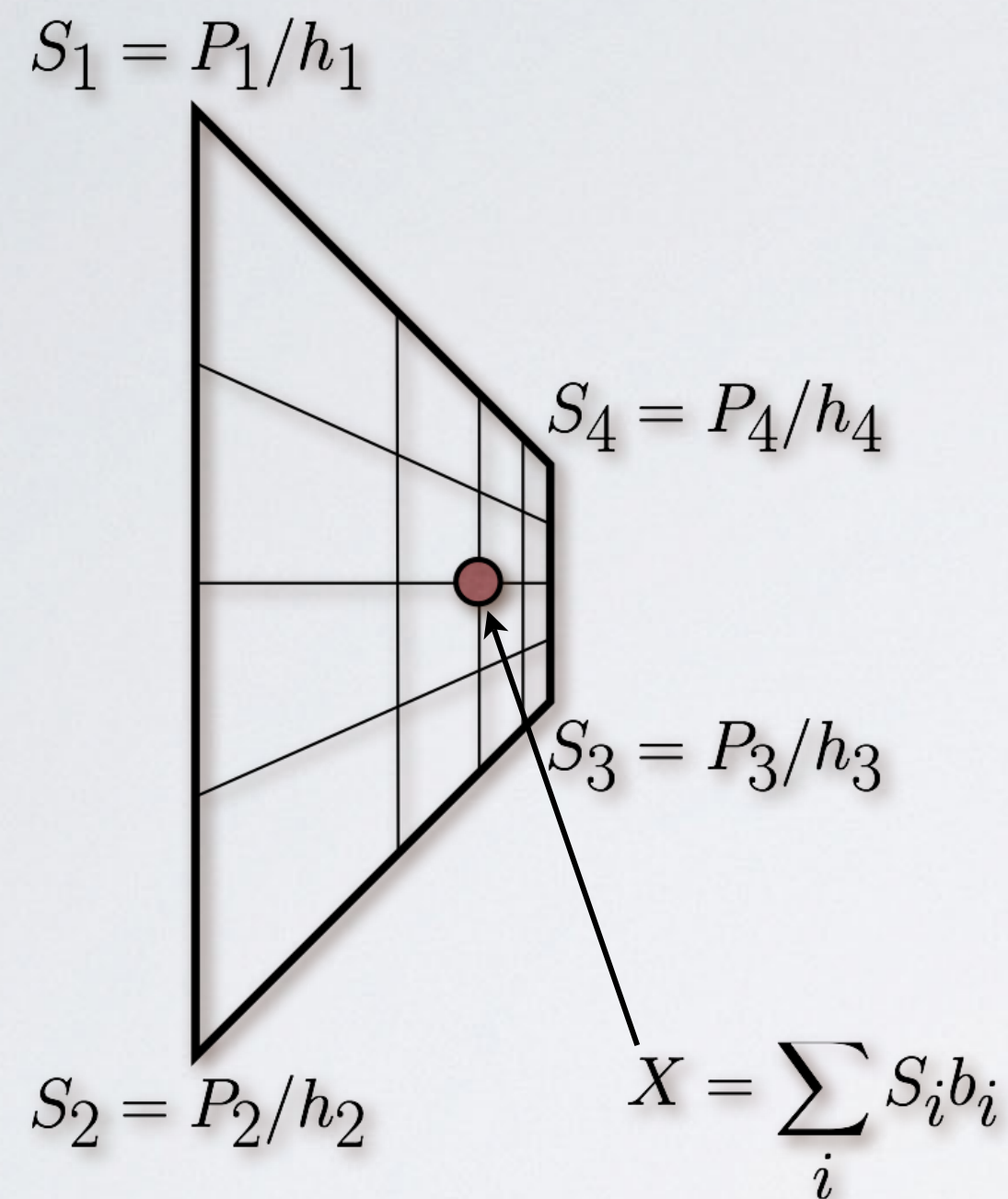
$$\left(\sum_j h_j a_j \right) b_i / h_i - a_i = 0 \quad \forall i$$

Not invertible so add some
extra constraints.

$$\sum_i a_i = \sum_i b_i = 1$$

S26 - O'Brien

Depth Distortion



For a line: $a_1 = h_2 b_i / (b_1 h_2 + h_1 b_2)$

For a triangle: $a_1 = h_2 h_3 b_1 / (h_2 h_3 b_1 + h_1 h_3 b_2 + h_1 h_2 b_3)$

Applying Textures is Sampling!

Simple Texture Mapping Operation

```
for each rasterized screen sample (x,y):  
    (u,v) = evaluate texcoord value at (x,y)  
    float3 texcolor = texture.sample(u,v);  
    set sample's color to texcolor;
```


Applying Textures is Sampling!

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Actually “re-sampling”

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Mathematically, to draw a texture sample at (u,v) :

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- Start with discrete, sampled 2D function $f(x,y)$. This function is only non-zero at sampled locations

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Signal processing concepts that should come to mind for you:

Applying Textures is Sampling!

Actually “re-sampling”

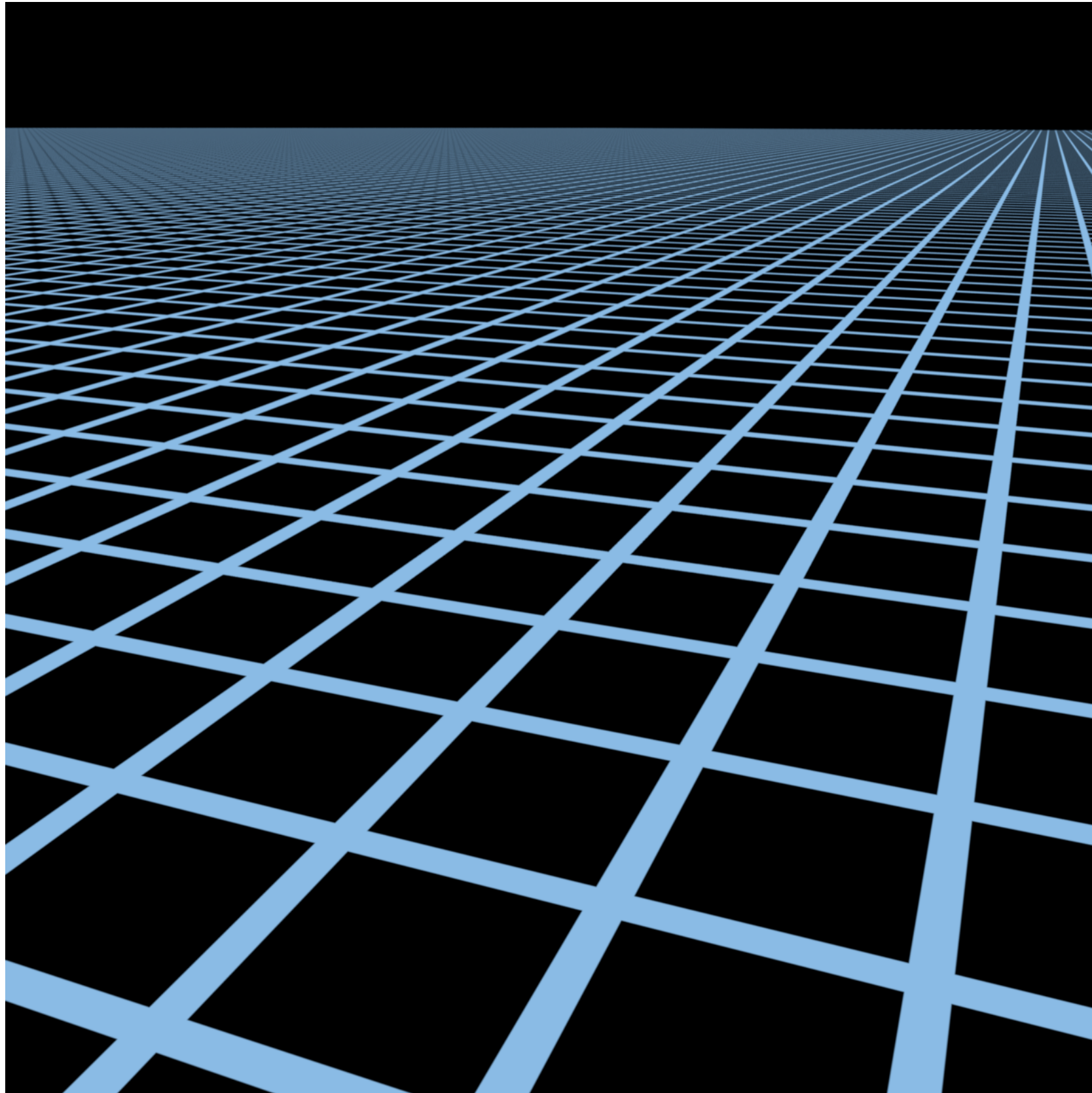
Mathematically, to draw a texture sample at (u,v) :

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- Draw the desired sample at (u,v) from the continuous 2D signal by function evaluation: $f_{\text{cont}}(u,v)$

Signal processing concepts that should come to mind for you:

- Frequency spectrum, aliasing, Nyquist frequency, filtering, anti-aliasing...

Point Sampling Textures



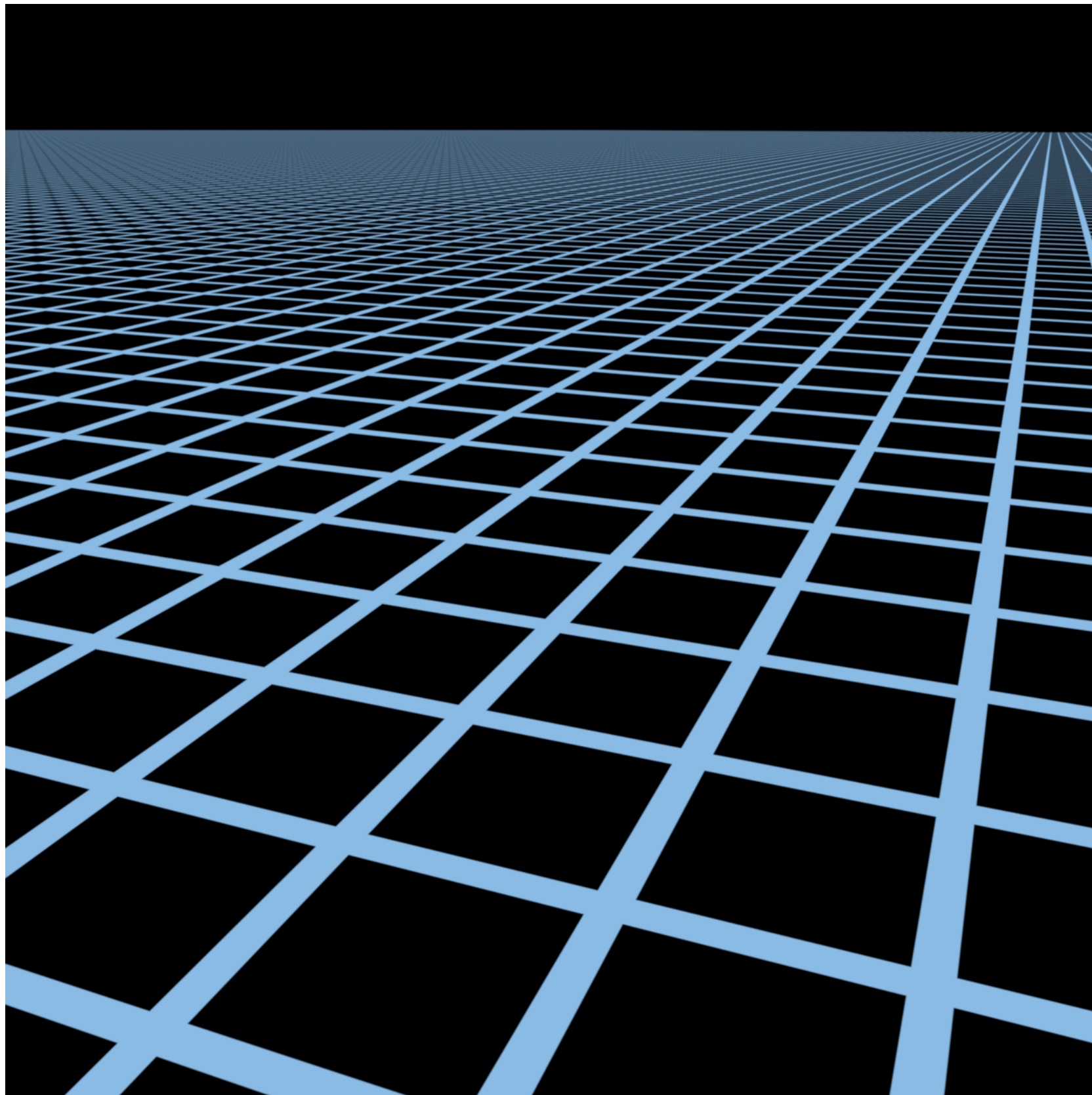
High-res reference

Source image: 1280x1280 pixels

Point sampling

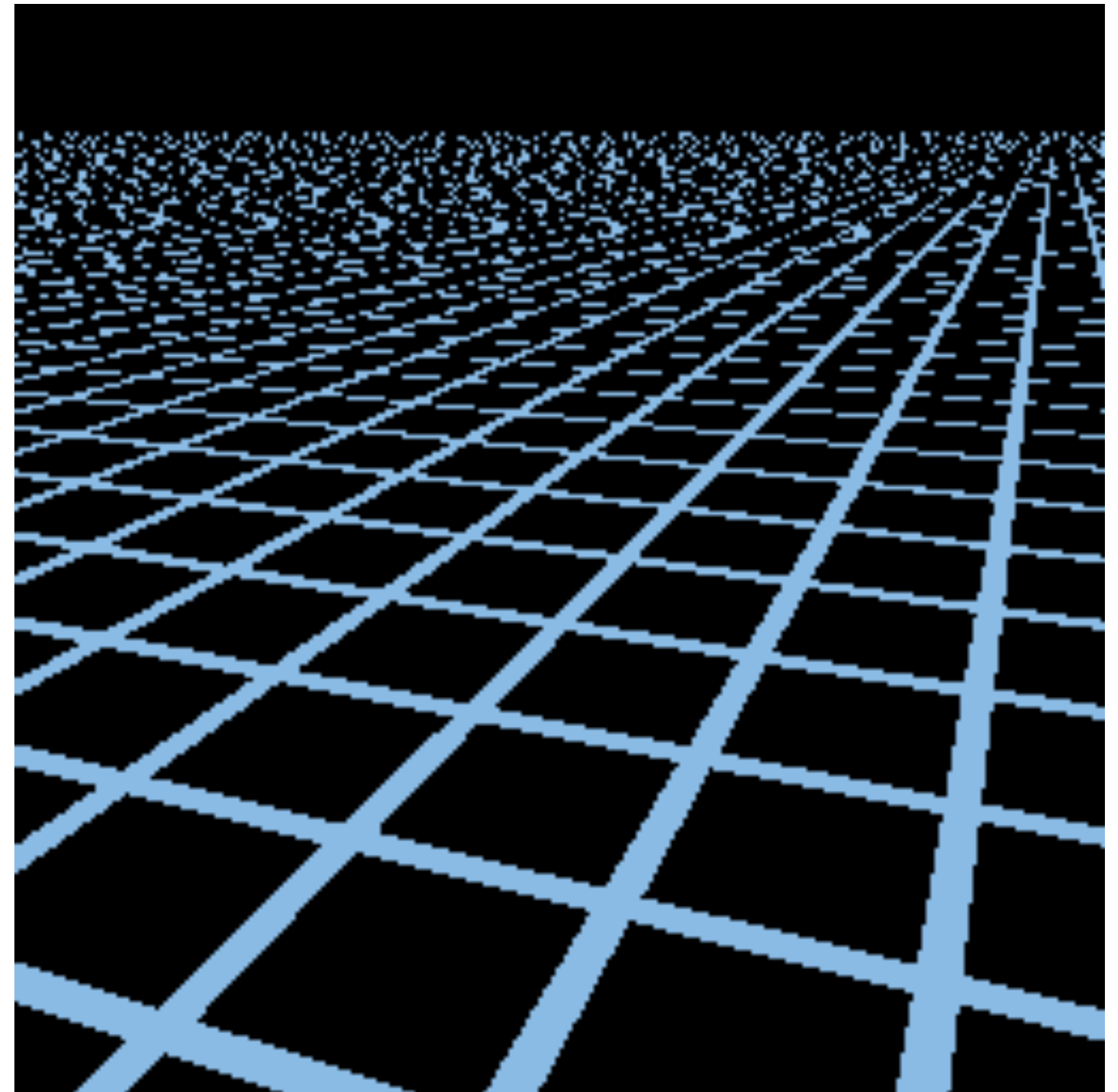
256x256 pixels

Point Sampling Textures



High-res reference

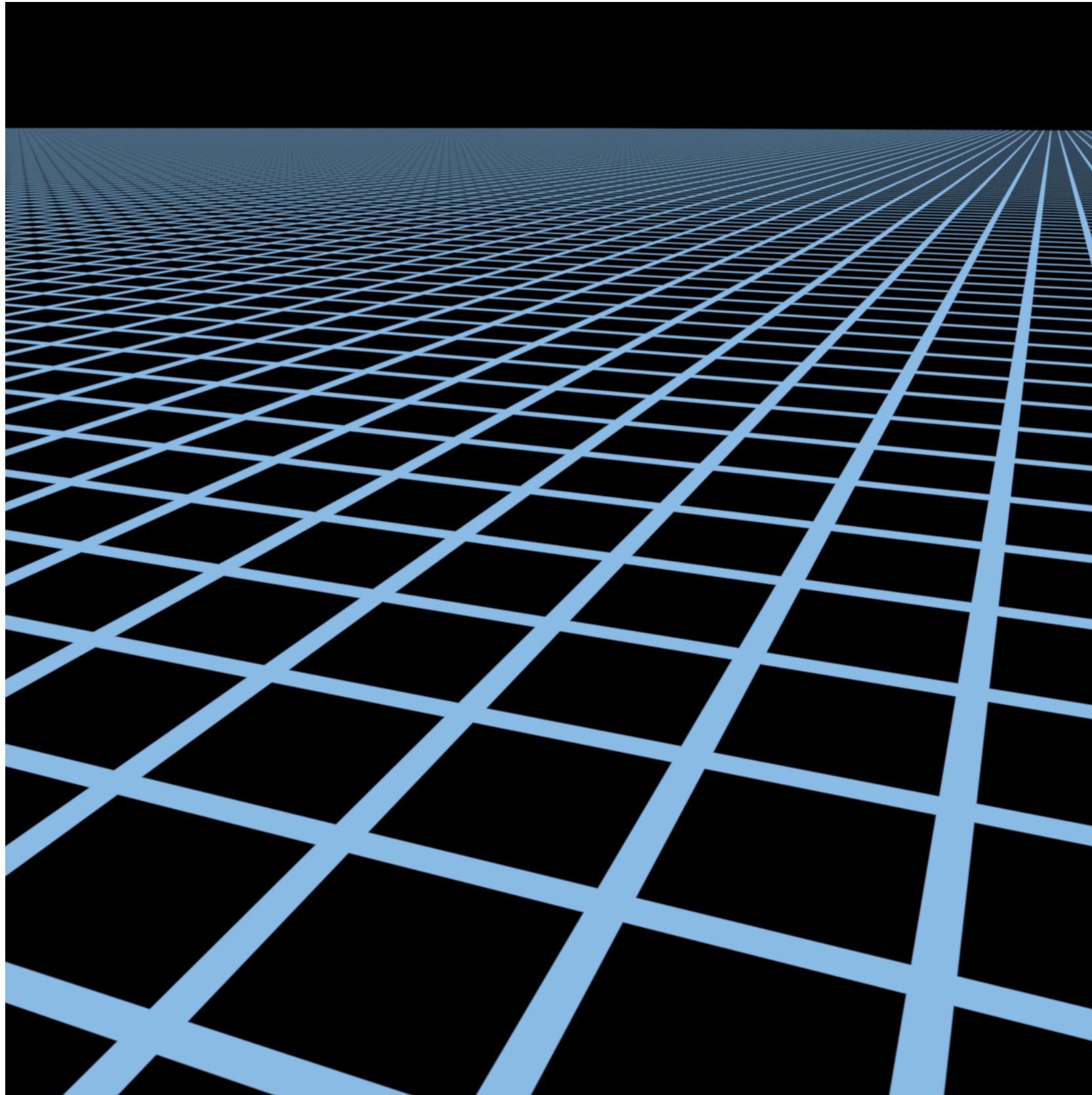
Source image: 1280x1280 pixels



Point sampling

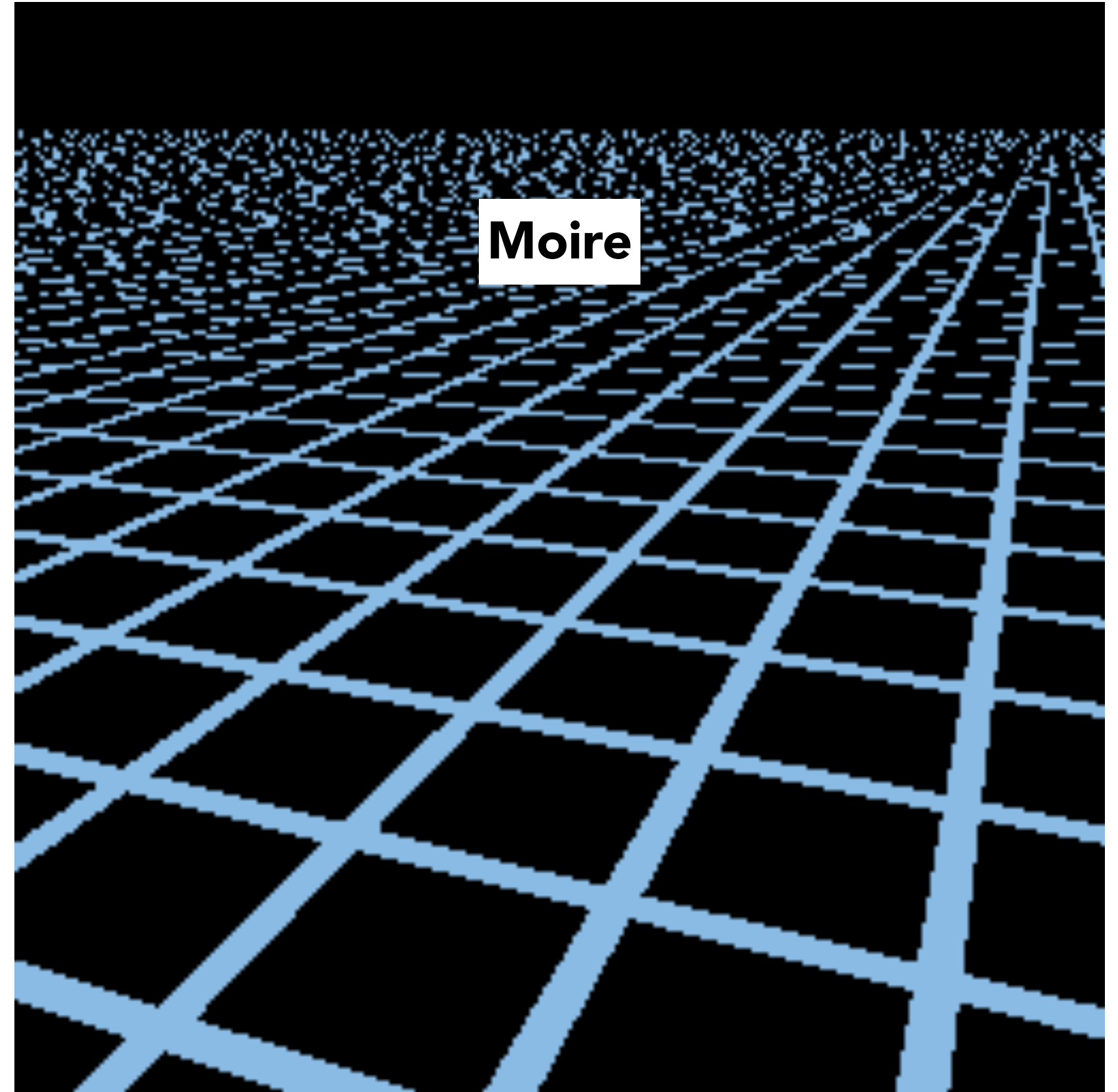
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Point Sampling Textures



High-res reference

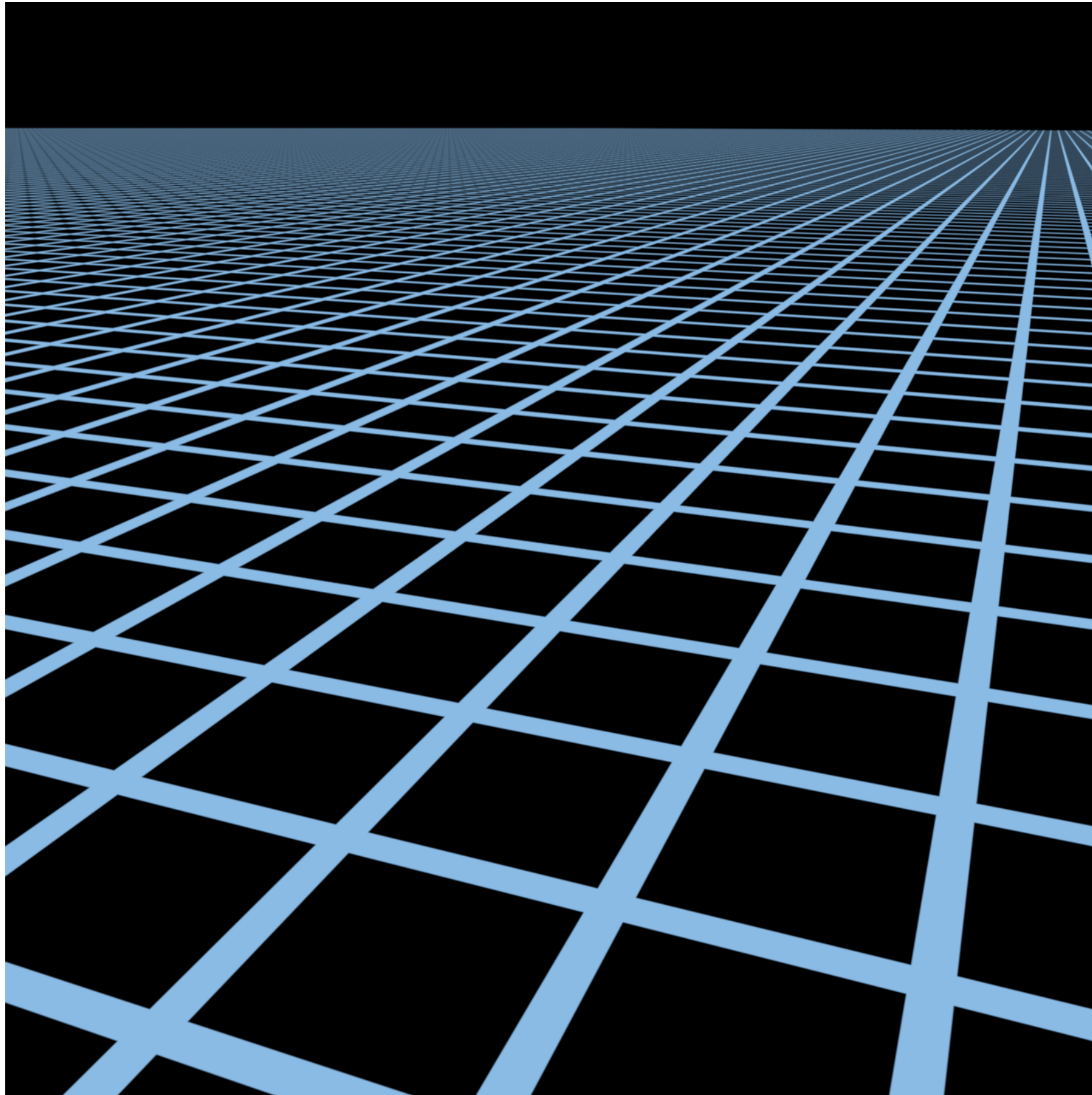
Source image: 1280x1280 pixels



Point sampling

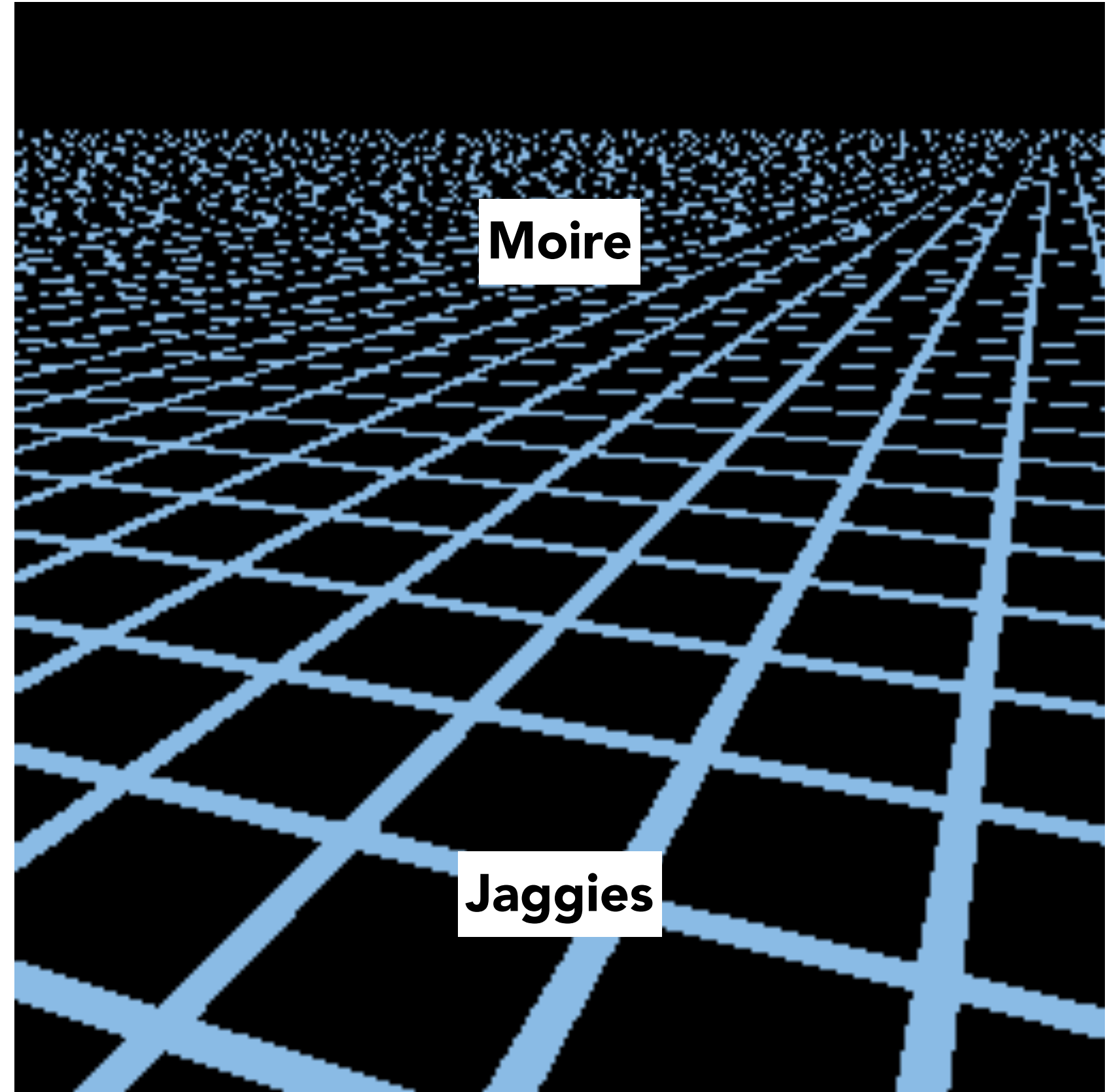
256x256 pixels

Point Sampling Textures



High-res reference

Source image: 1280x1280 pixels

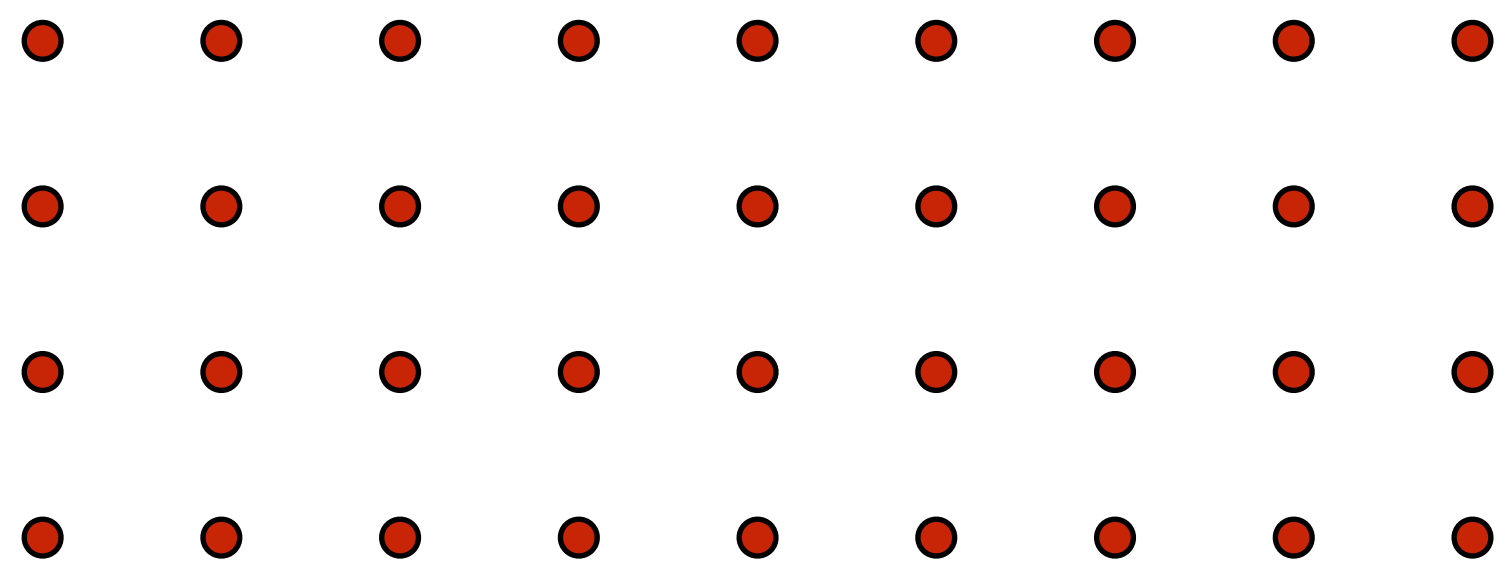
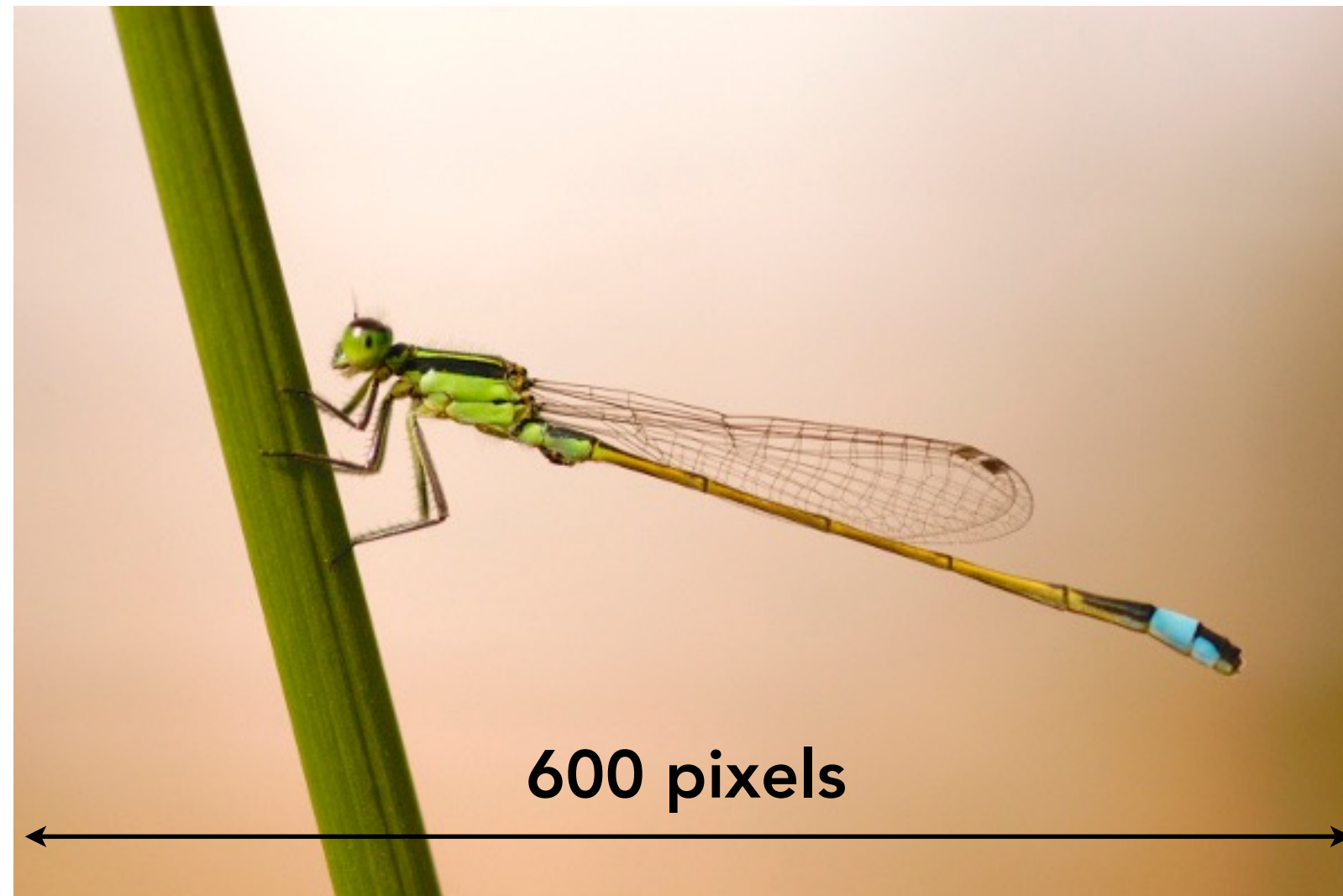


Point sampling

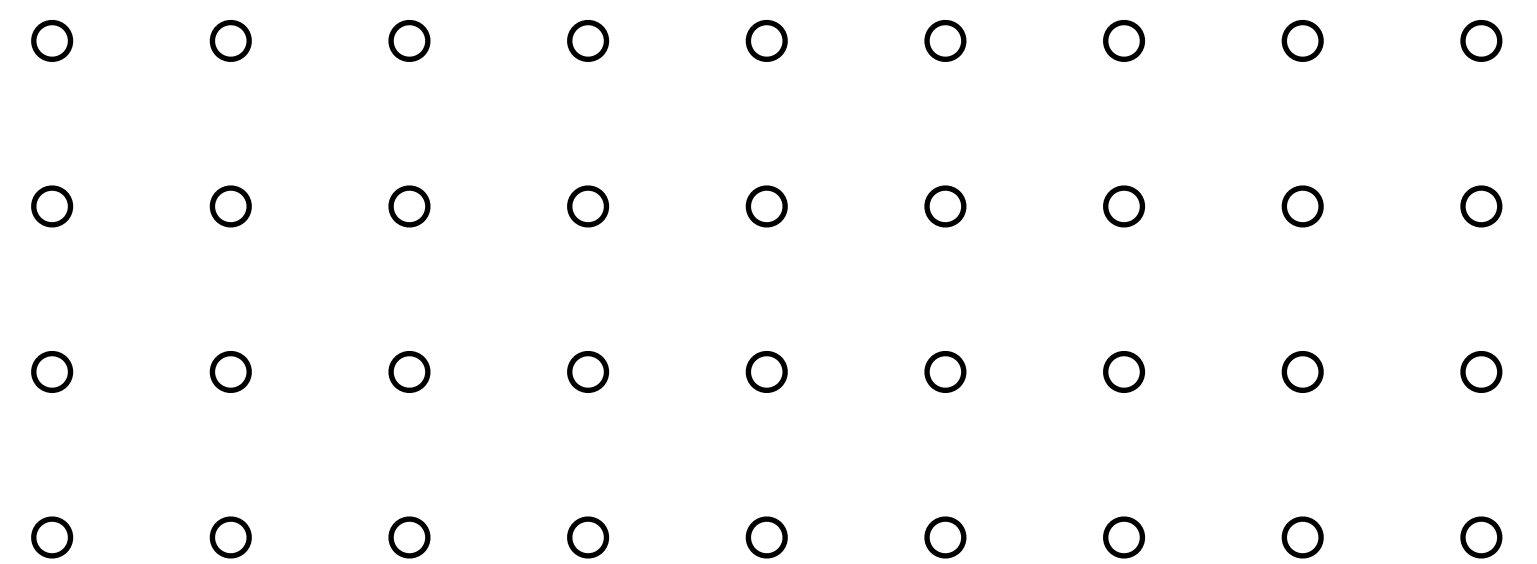
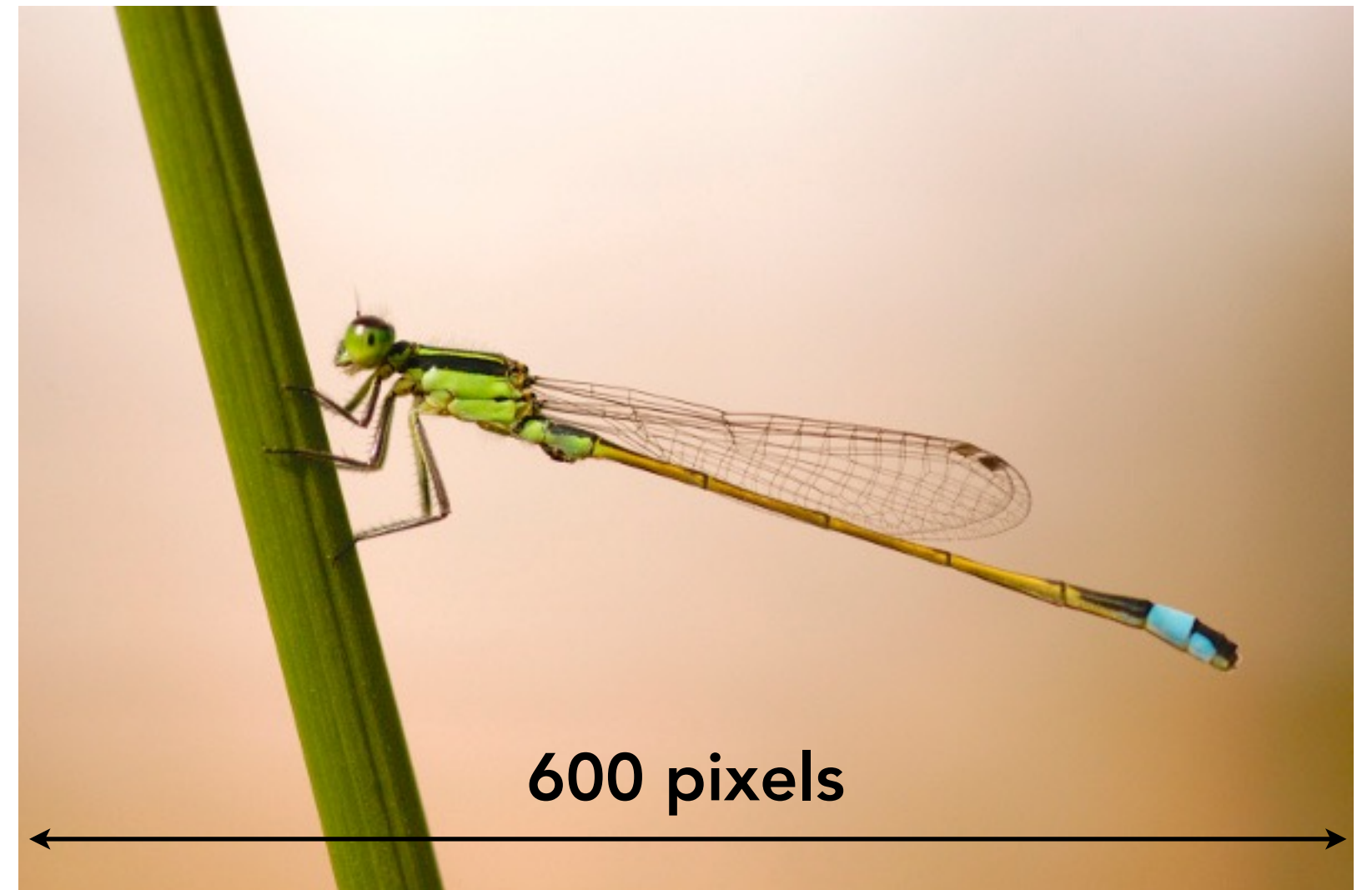
256x256 pixels

Texture Sampling Frequency

Sampling Rate on Screen vs Texture



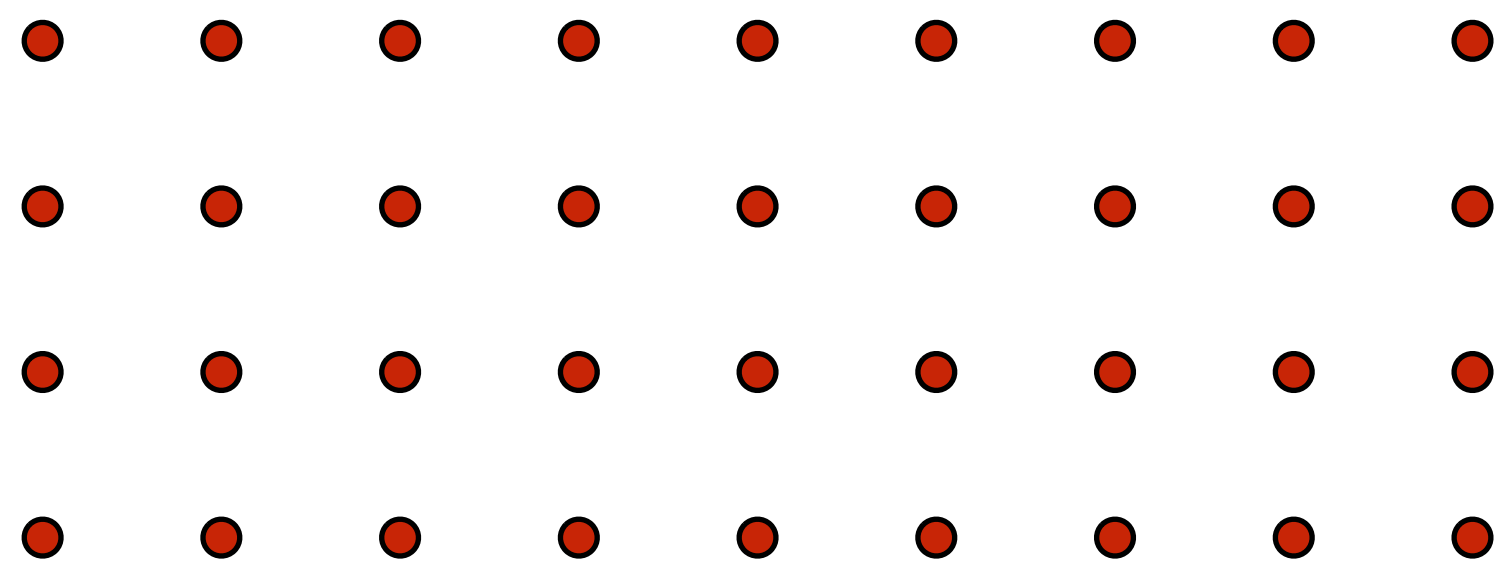
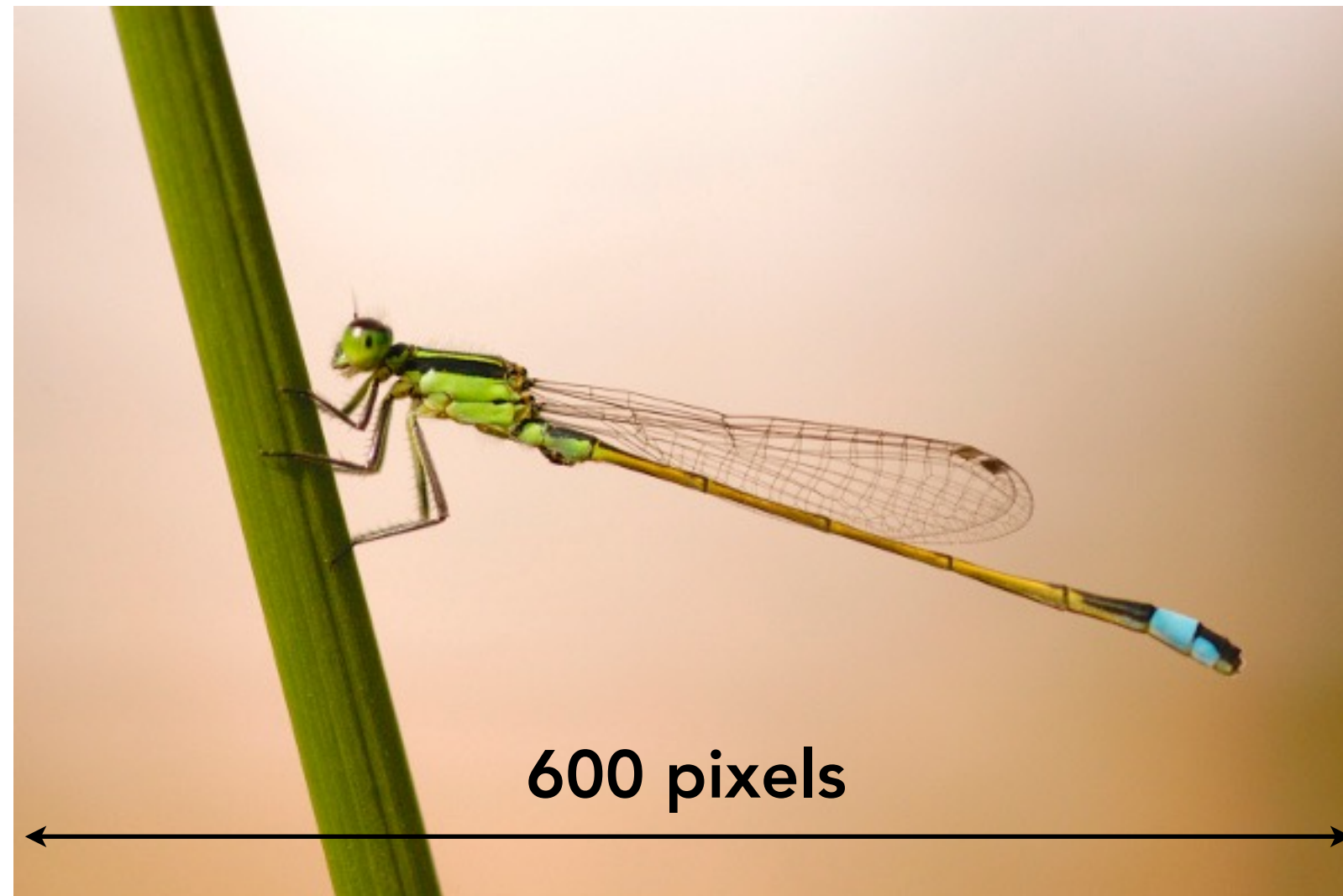
Screen space (x,y)



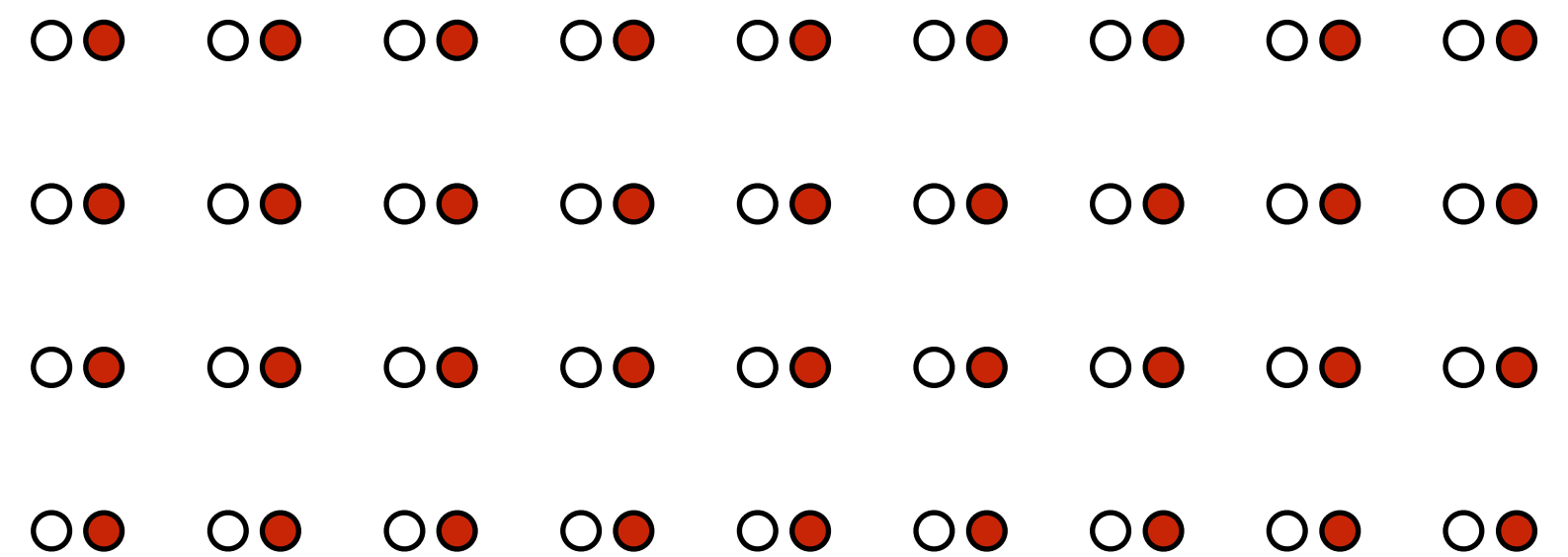
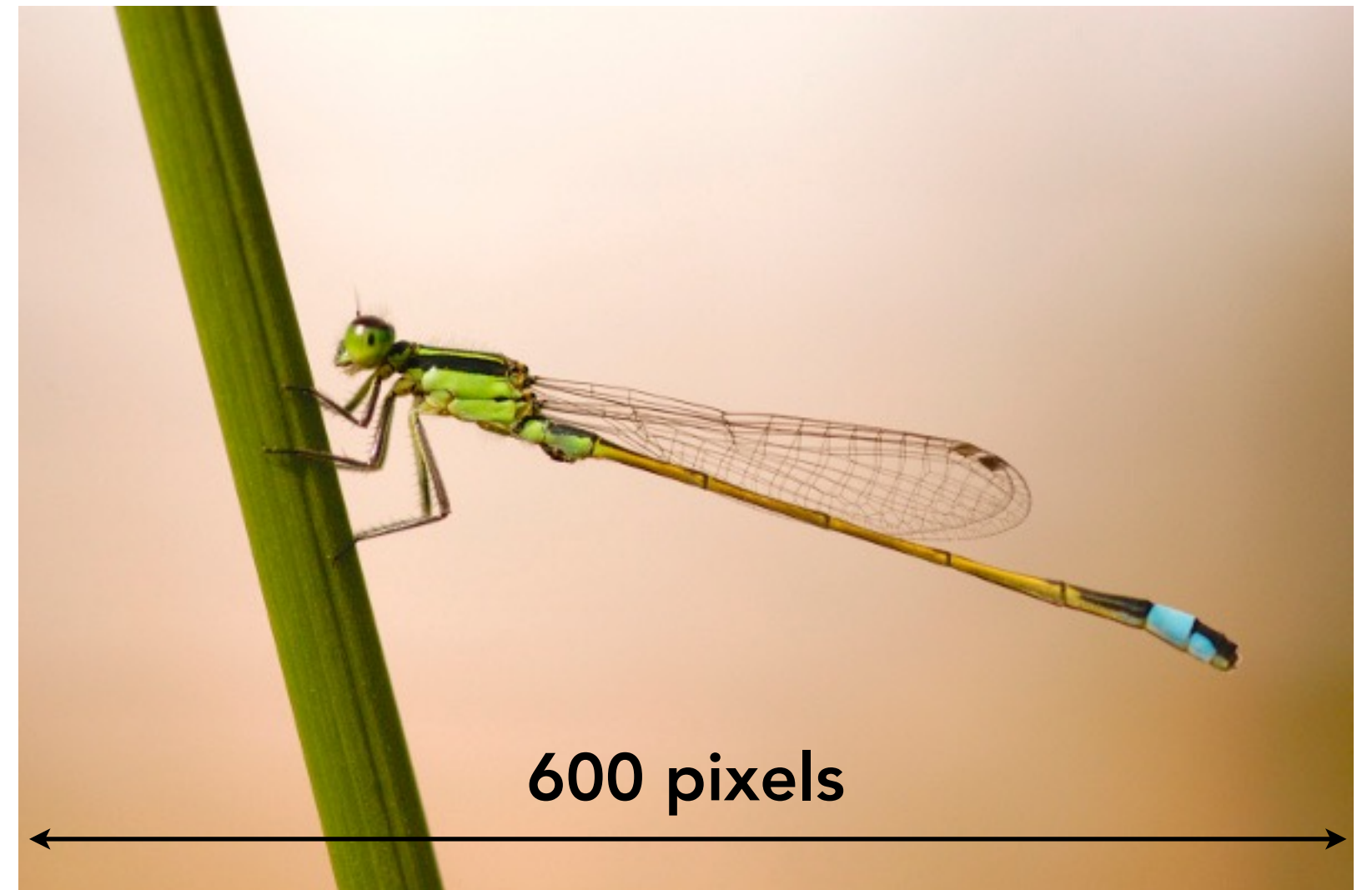
Texture space (u,v)

1:1 mapping

Sampling Rate on Screen vs Texture



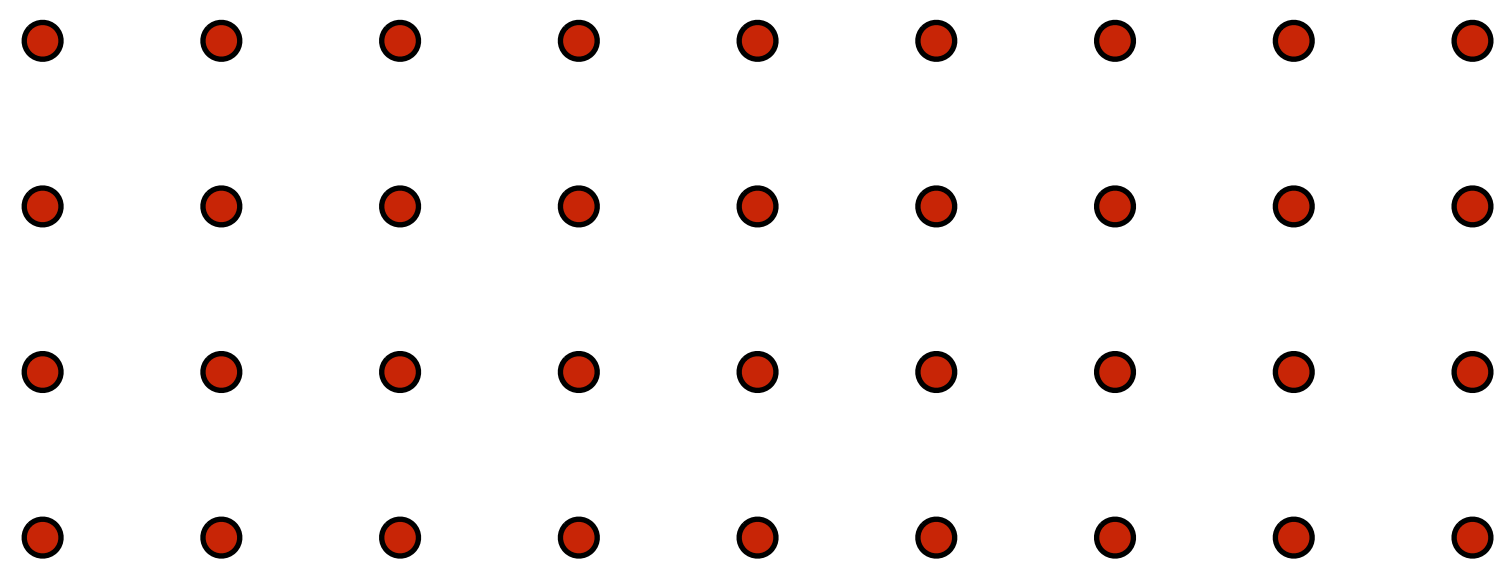
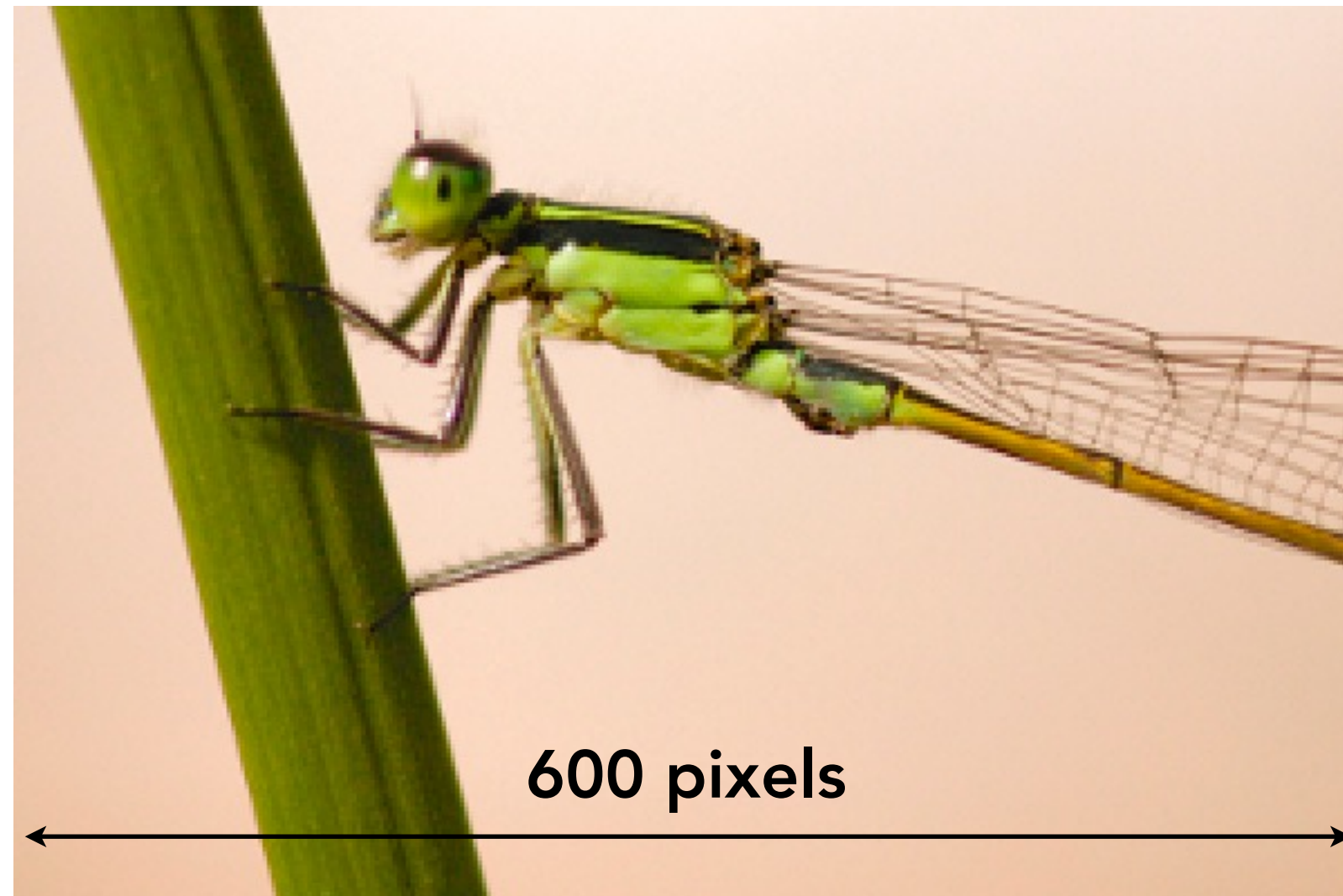
Screen space (x,y)



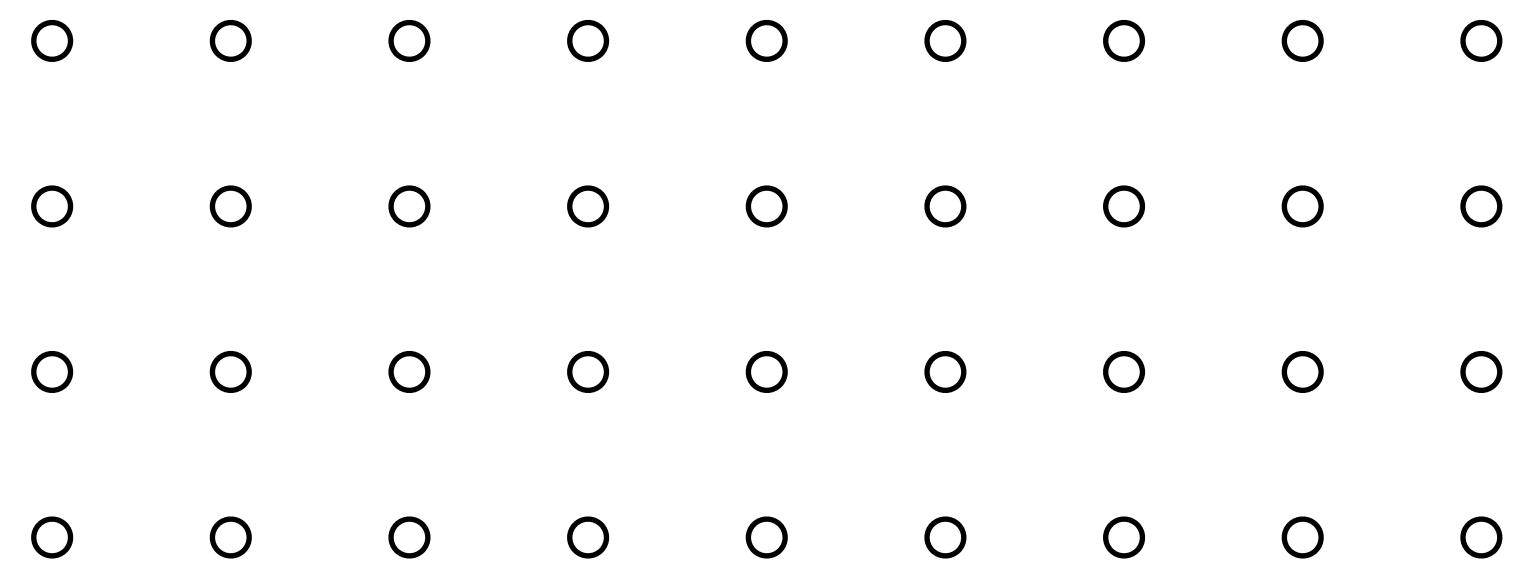
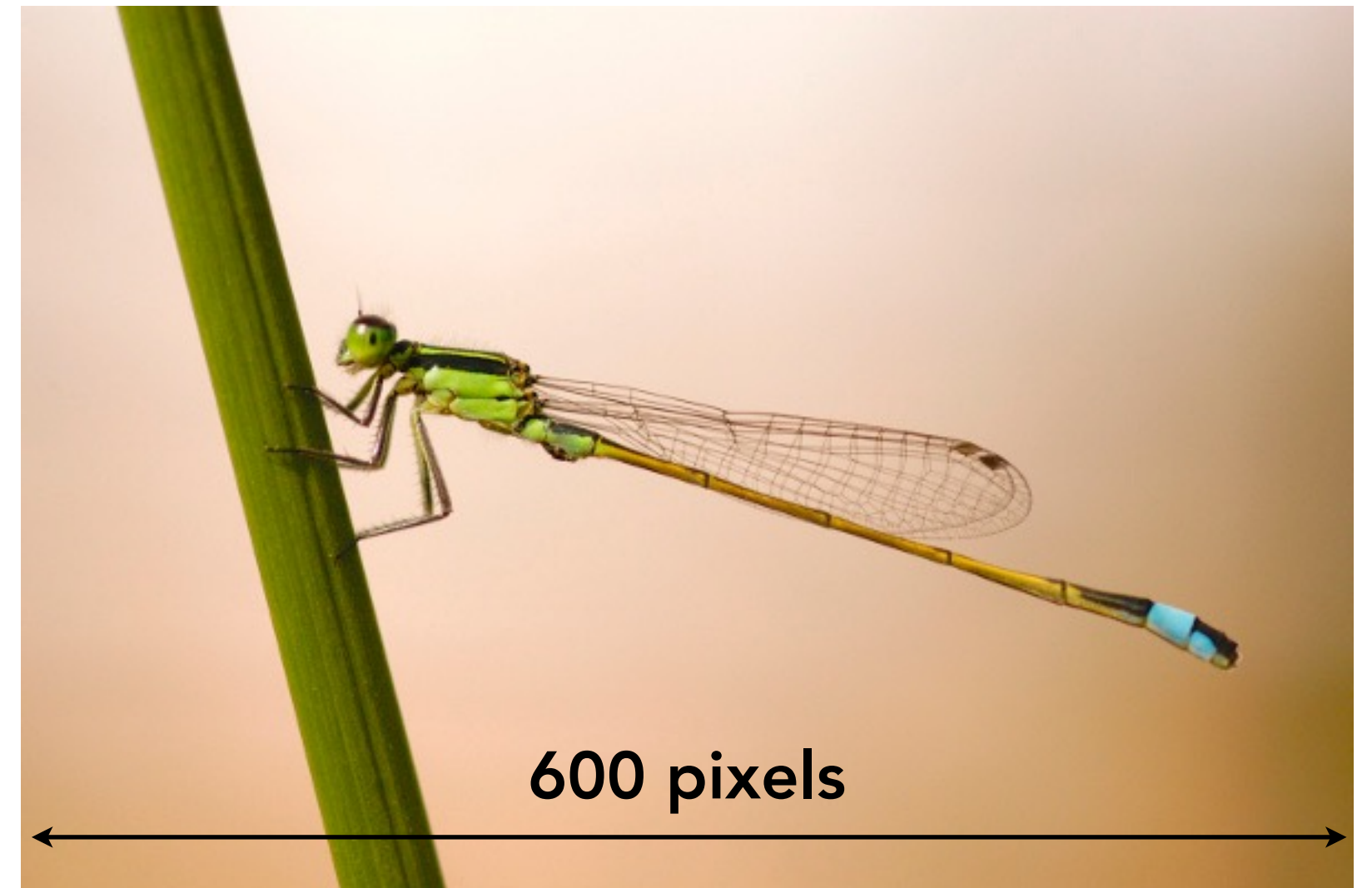
Texture space (u,v)

1:1 mapping

Sampling Rate on Screen vs Texture



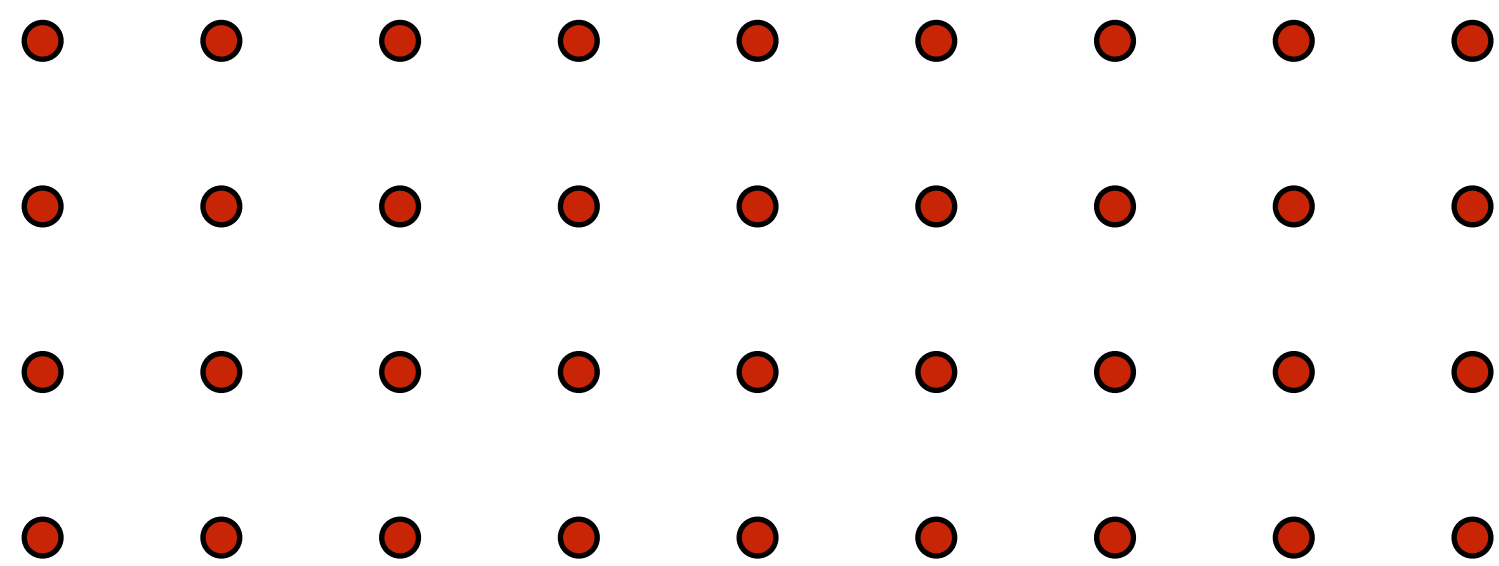
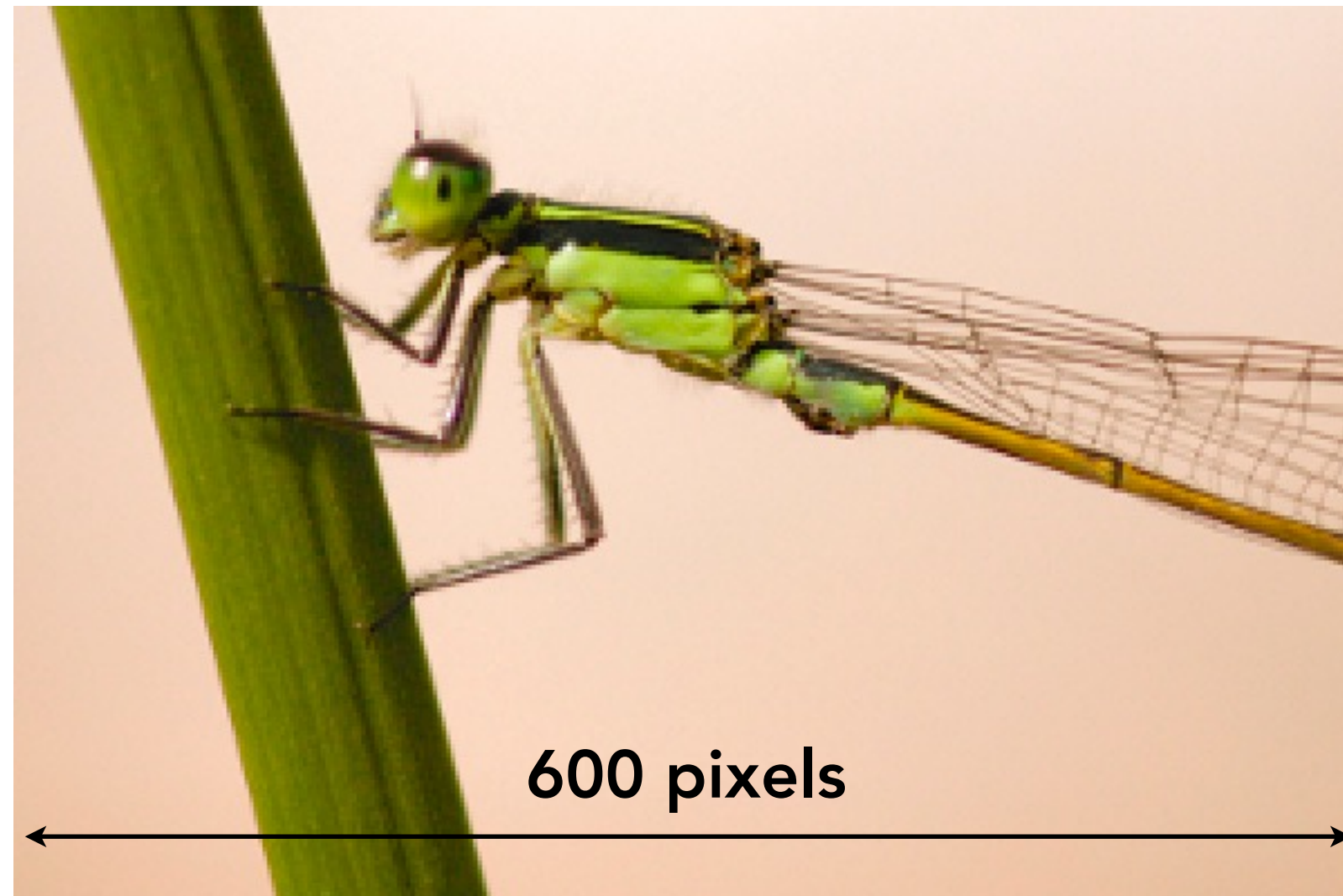
Screen space (x,y)



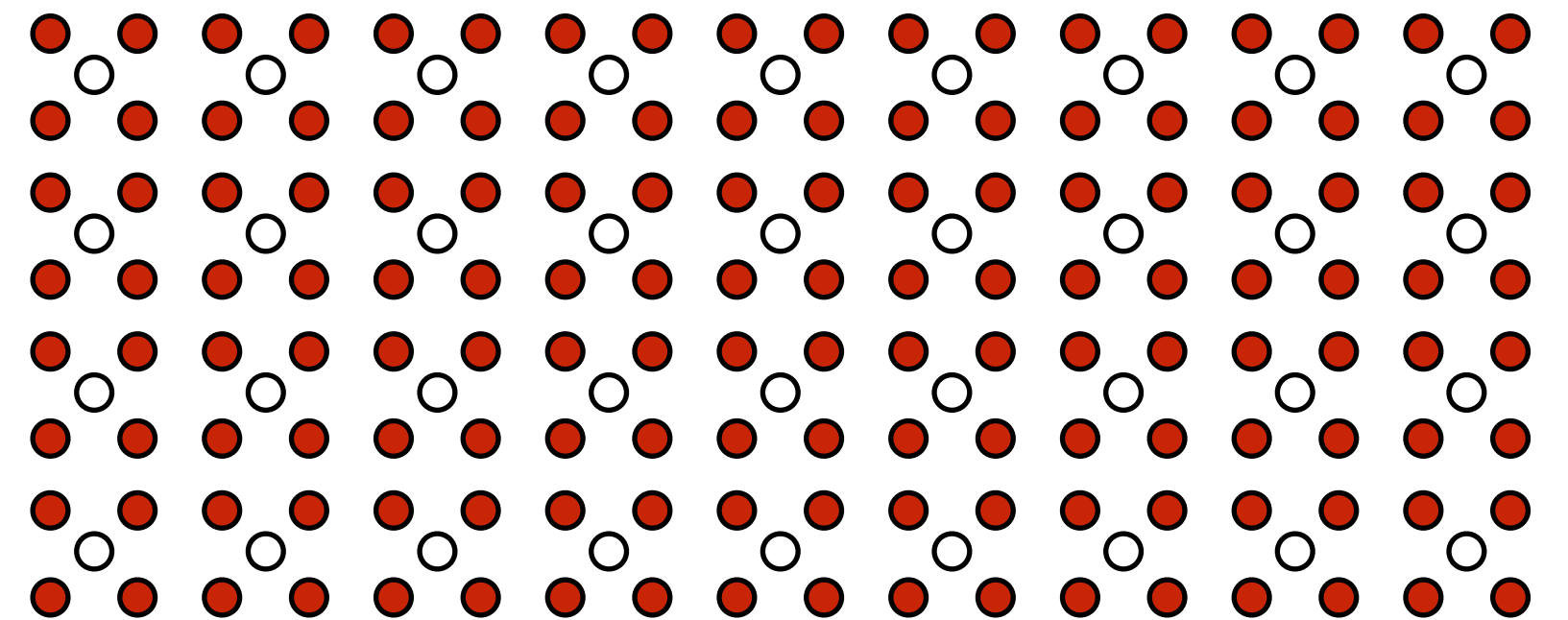
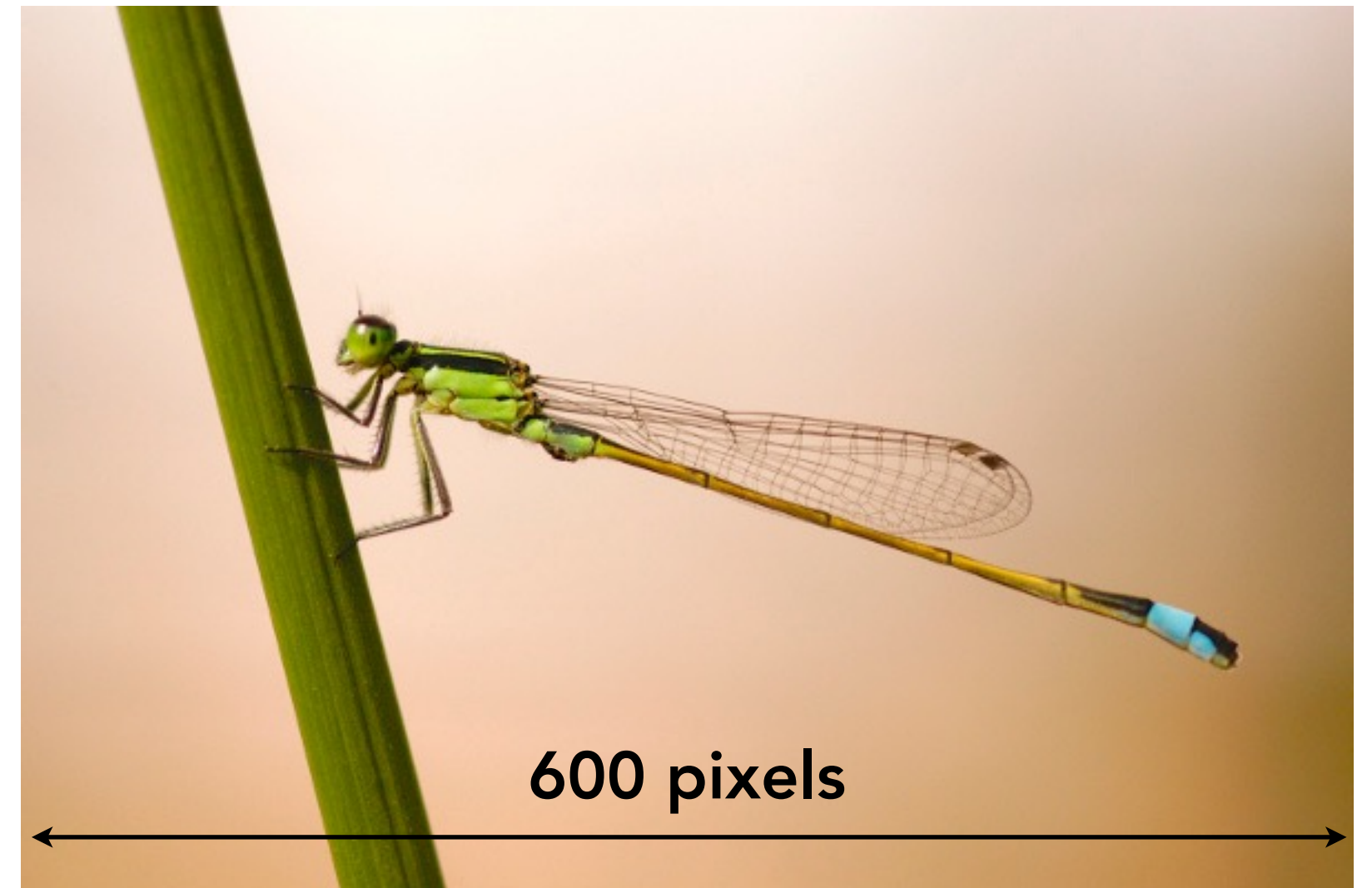
Texture space (u,v)

Magnified

Sampling Rate on Screen vs Texture



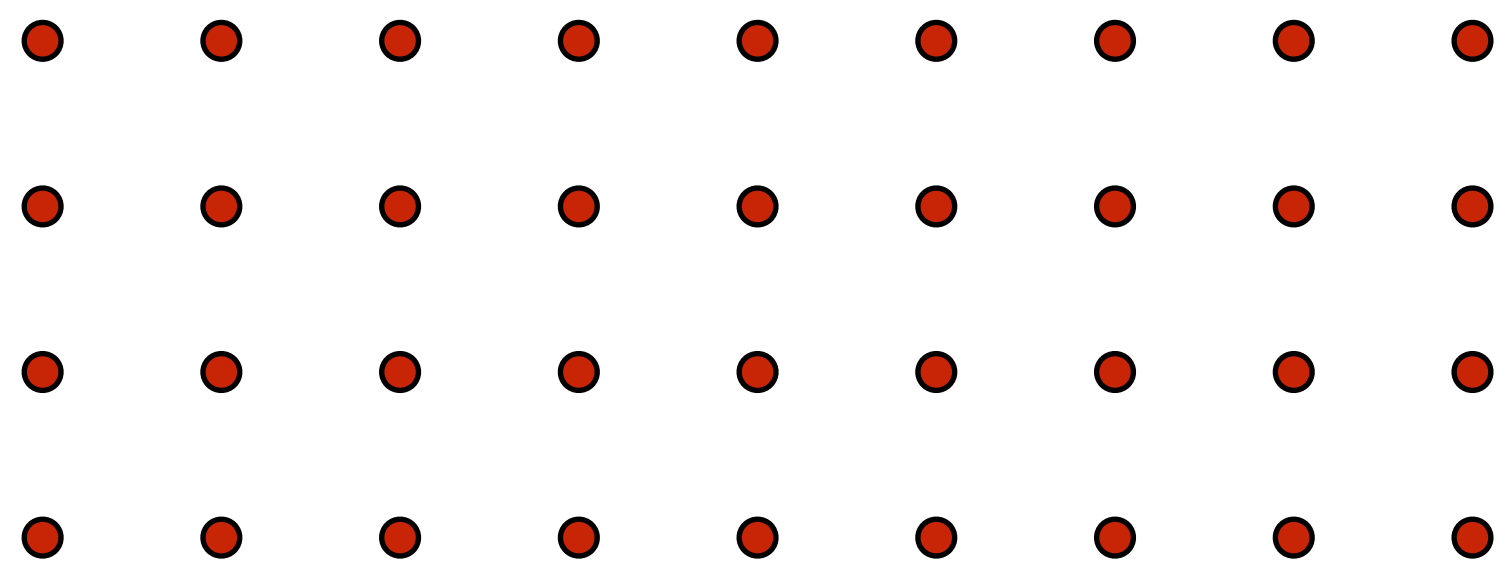
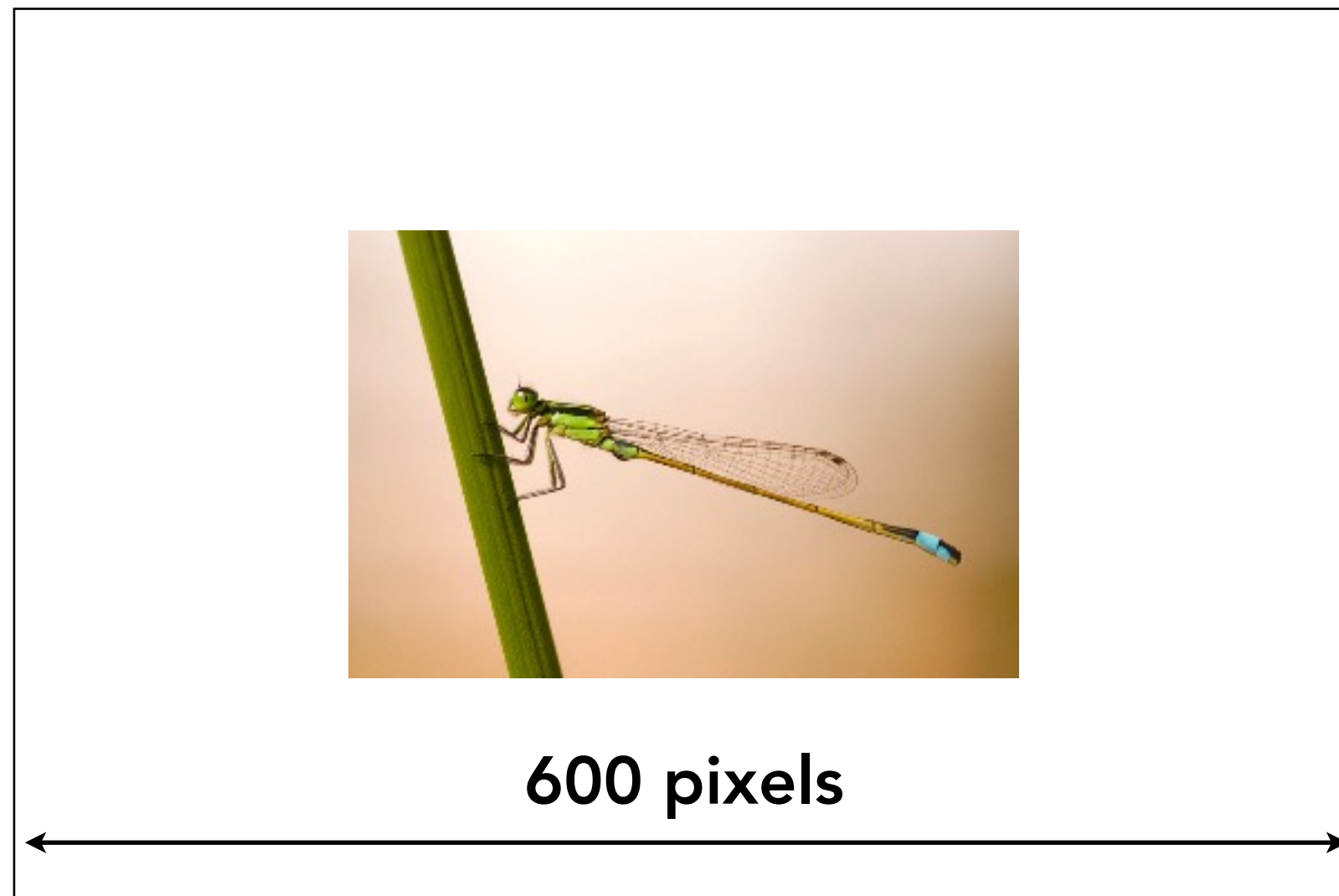
Screen space (x,y)



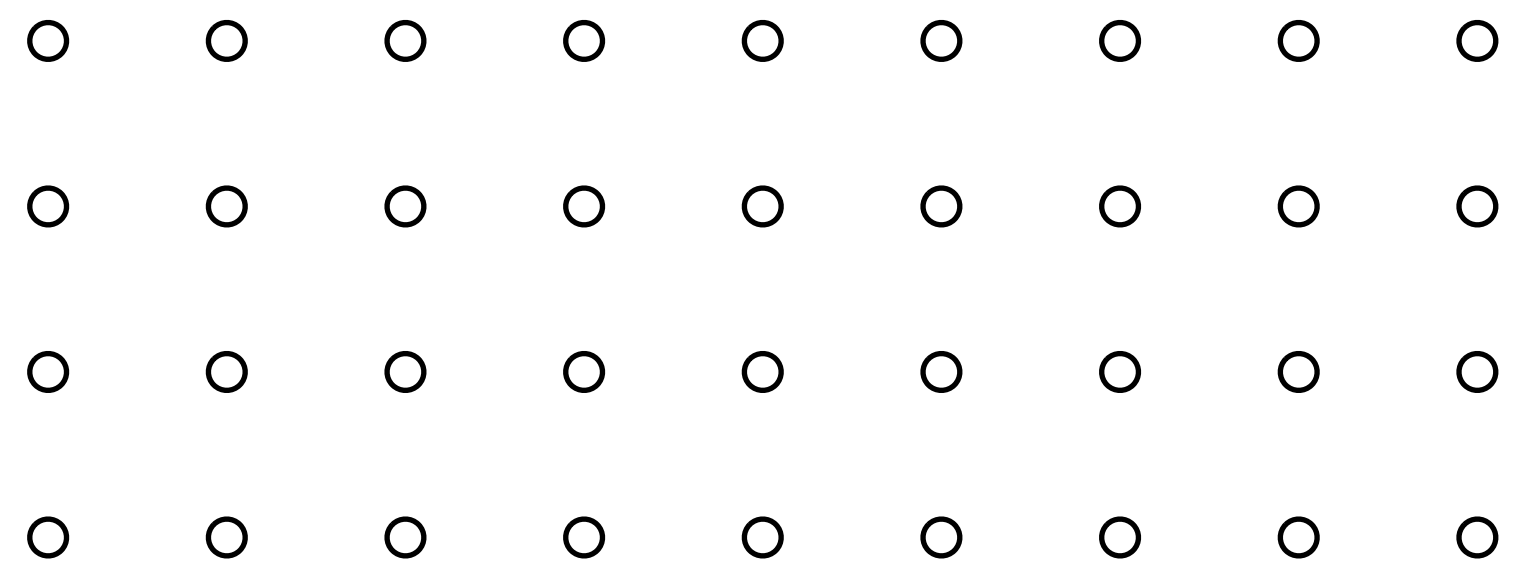
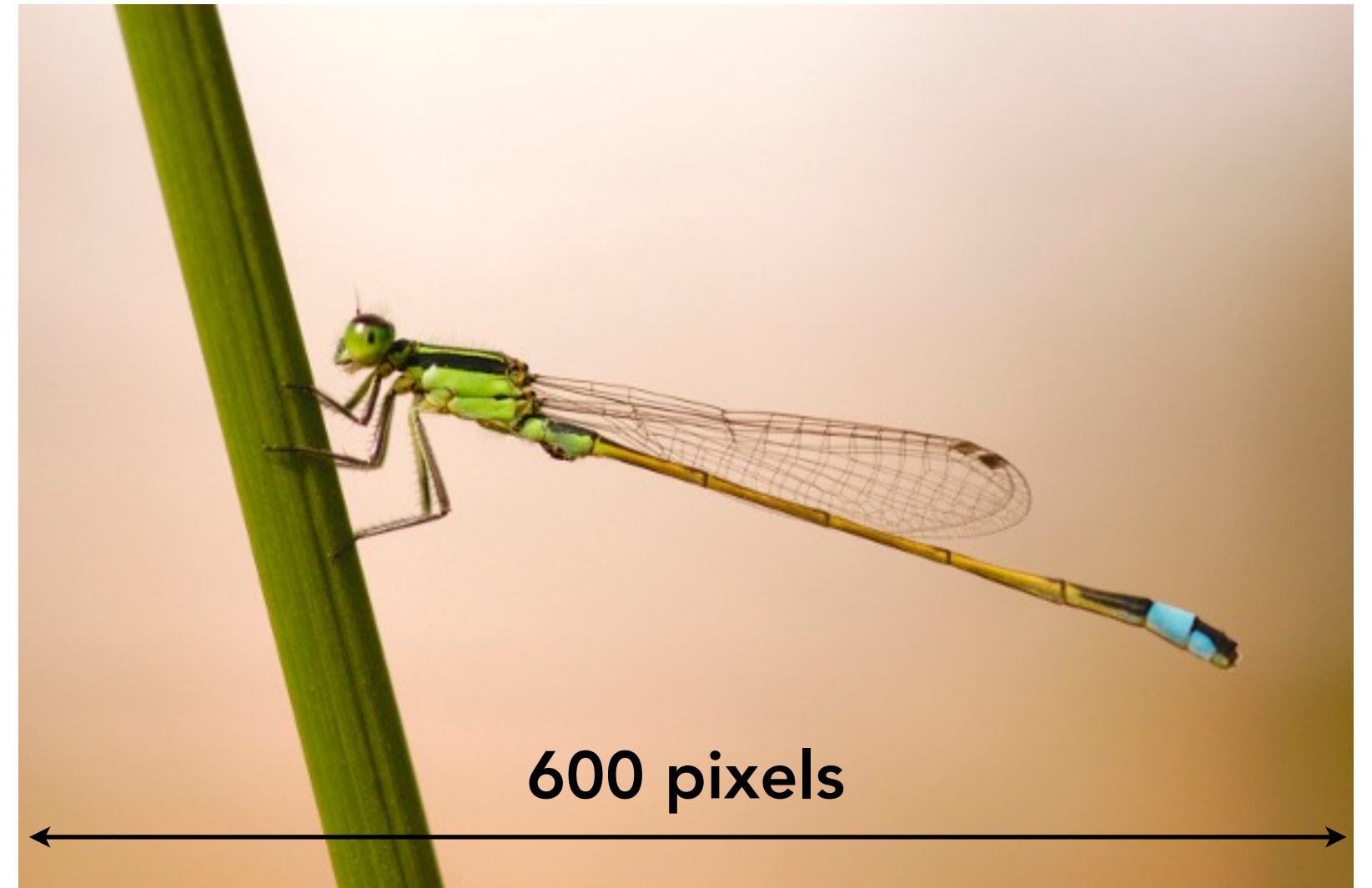
Texture space (u,v)

Magnified

Sampling Rate on Screen vs Texture



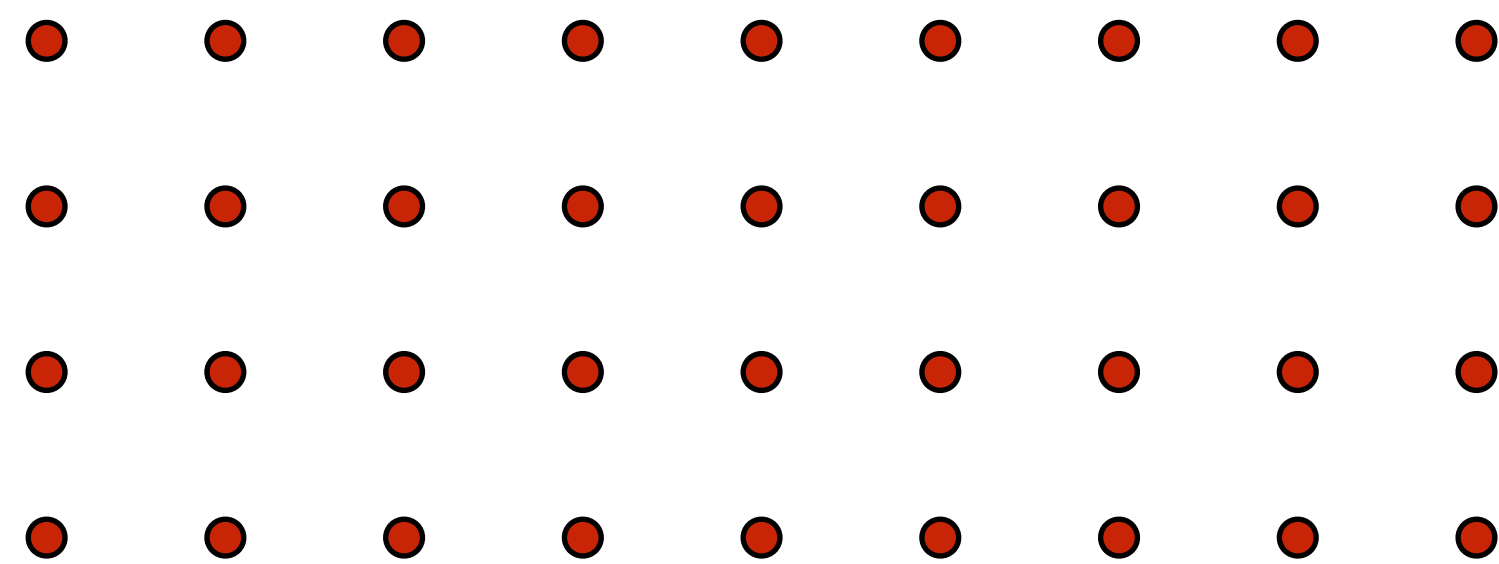
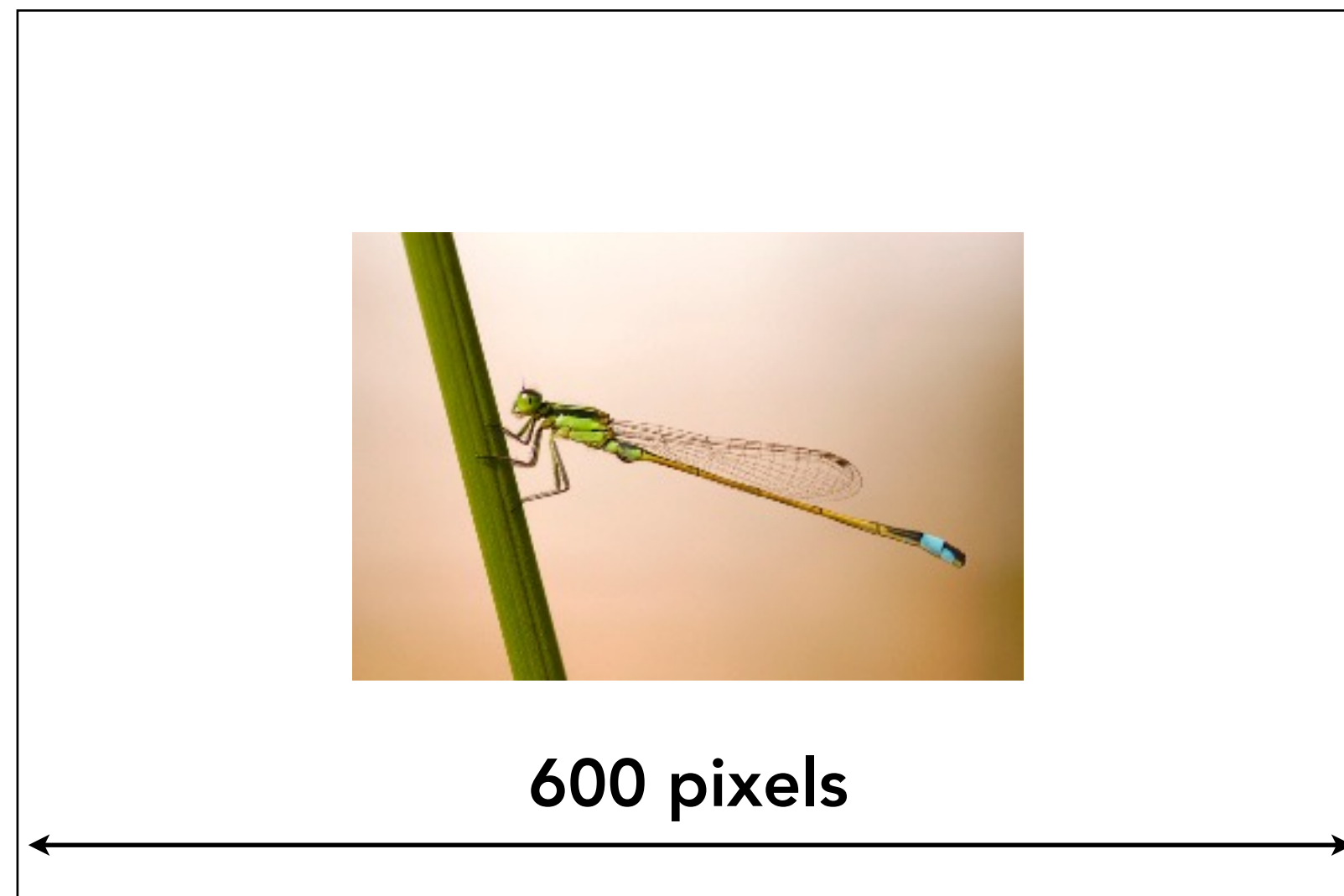
Screen space (x,y)



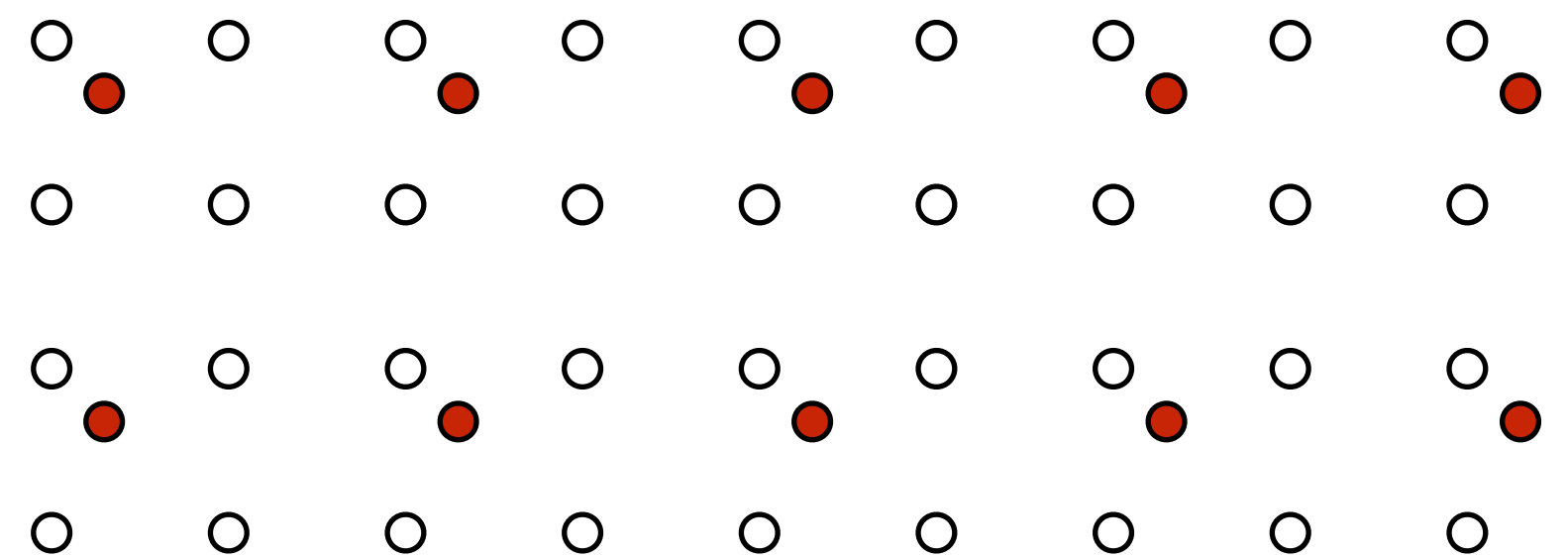
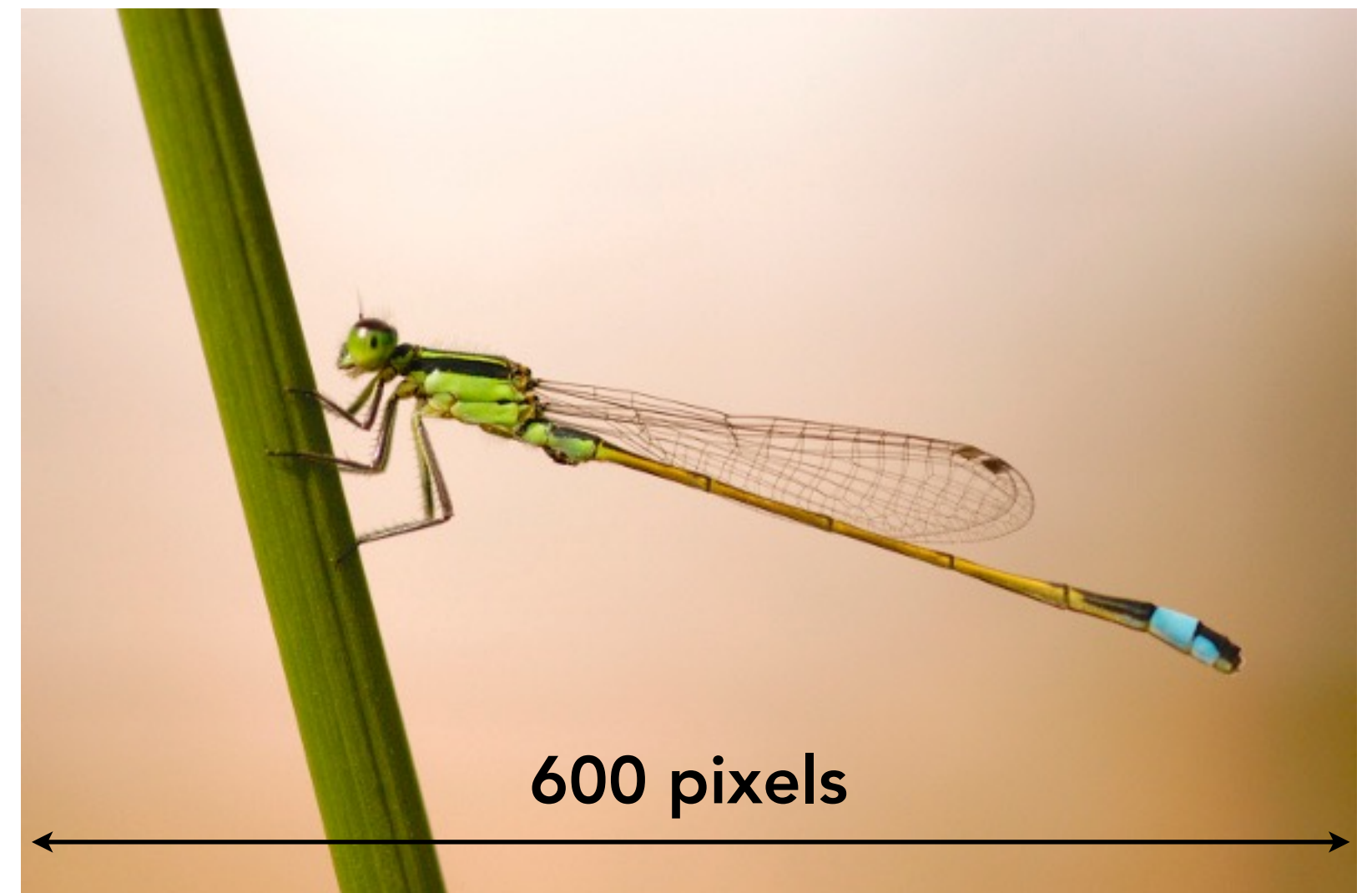
Texture space (u,v)

"Minified"

Sampling Rate on Screen vs Texture



Screen space (x,y)



Texture space (u,v)

"Minified"

Texture Sampling Rate

The sampling frequency in screen space translates to a sampling frequency in texture space as determined by the mapping function.

In general the frequency varies across the scene depending on geometric transforms, viewing transforms, and the texture coordinate function.

Screen Pixel Area vs Texel Area

At optimal viewing size:

- 1:1 mapping between pixel sampling rate and texel sampling rate
- Dependent on texture resolution! e.g. 512x512

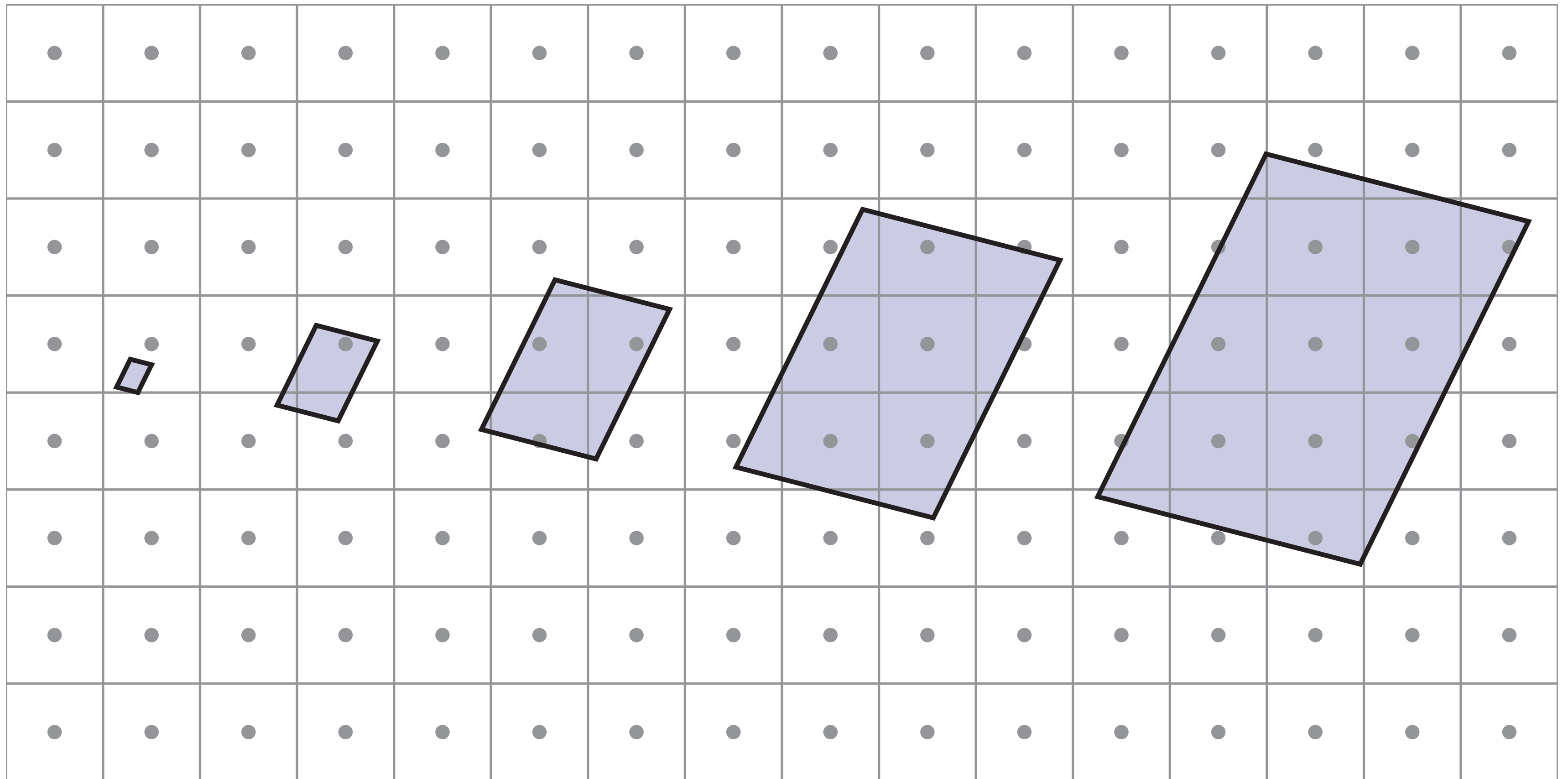
When larger (magnification)

- Multiple pixel samples per texel sample

When smaller (minification)

- One pixel sample per multiple texel samples

Screen Pixel Footprint in Texture

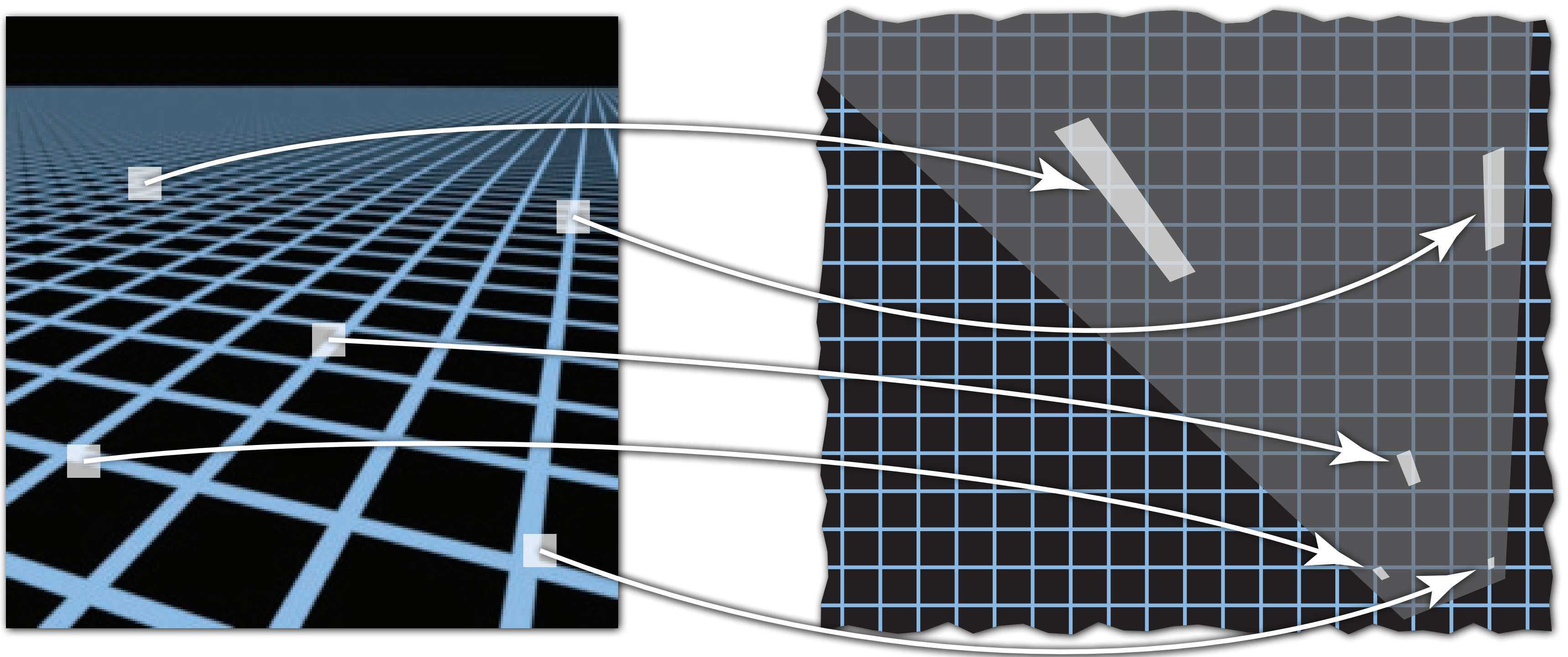


**Upsampling
(Magnification)**



**Downsampling
(Minification)**

Screen Pixel Footprint in Texture

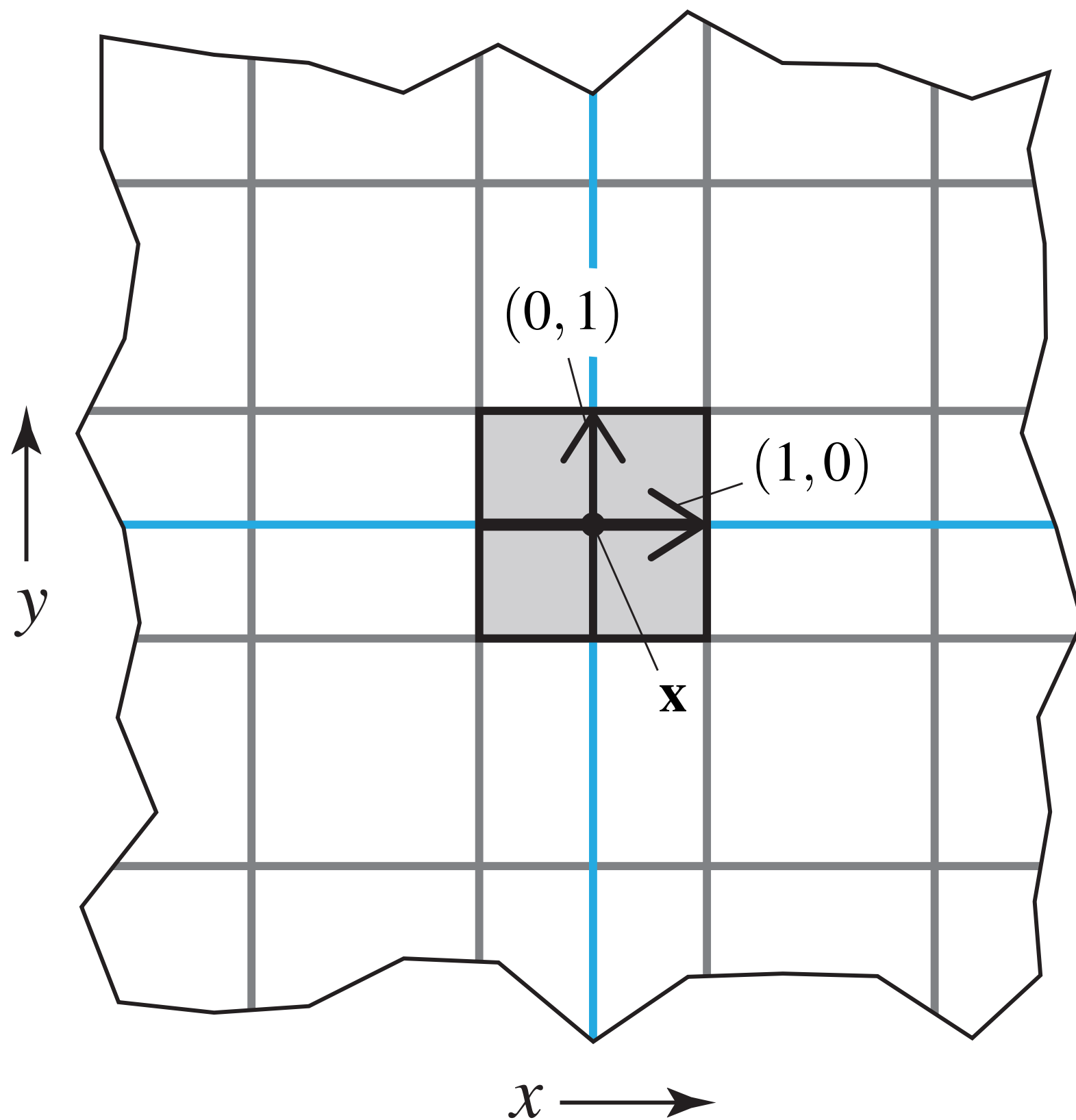


Screen space

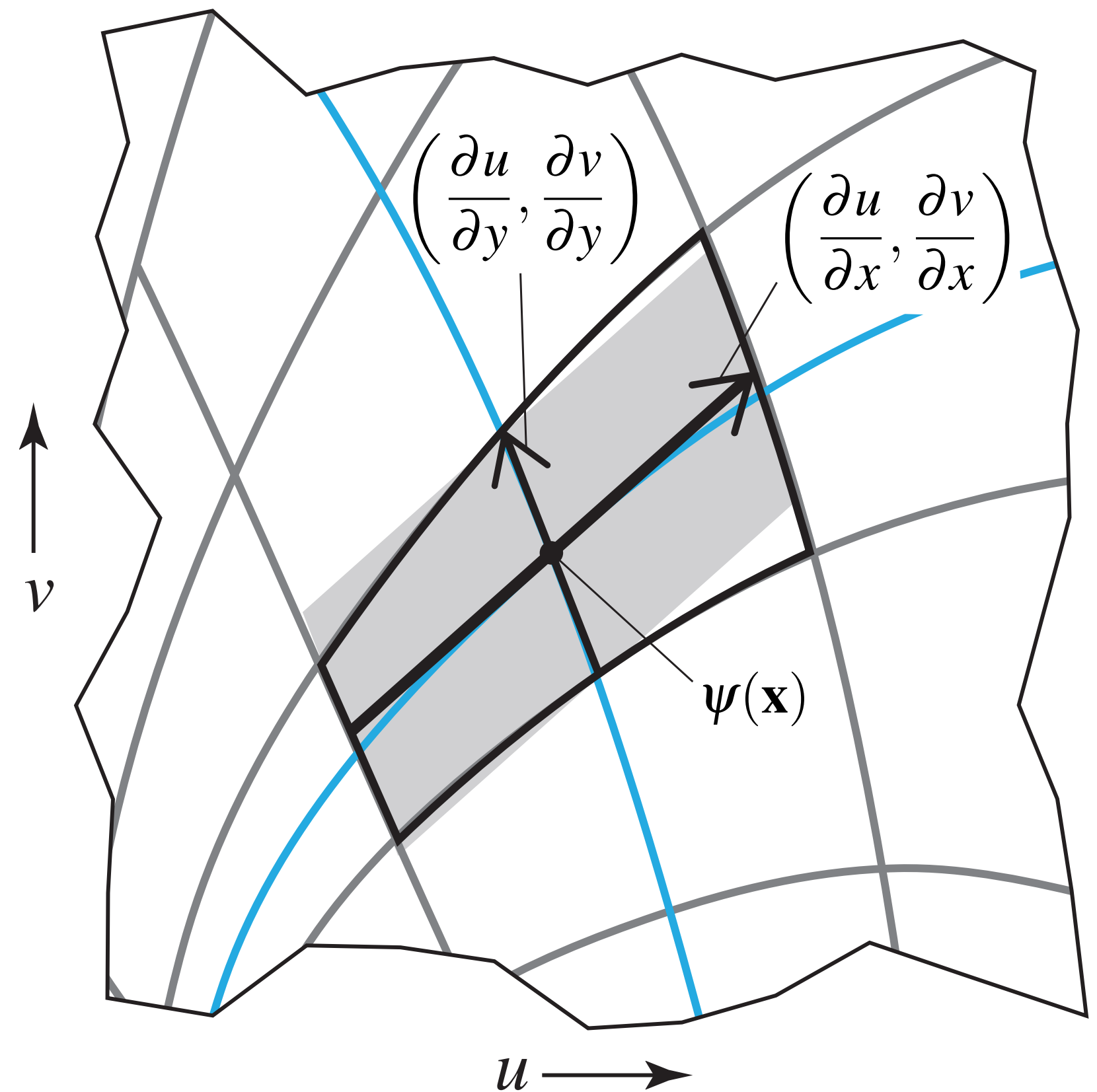
Texture space

NB: texture sampling pattern not rectilinear or isotropic

Estimating Footprint Area With Jacobian



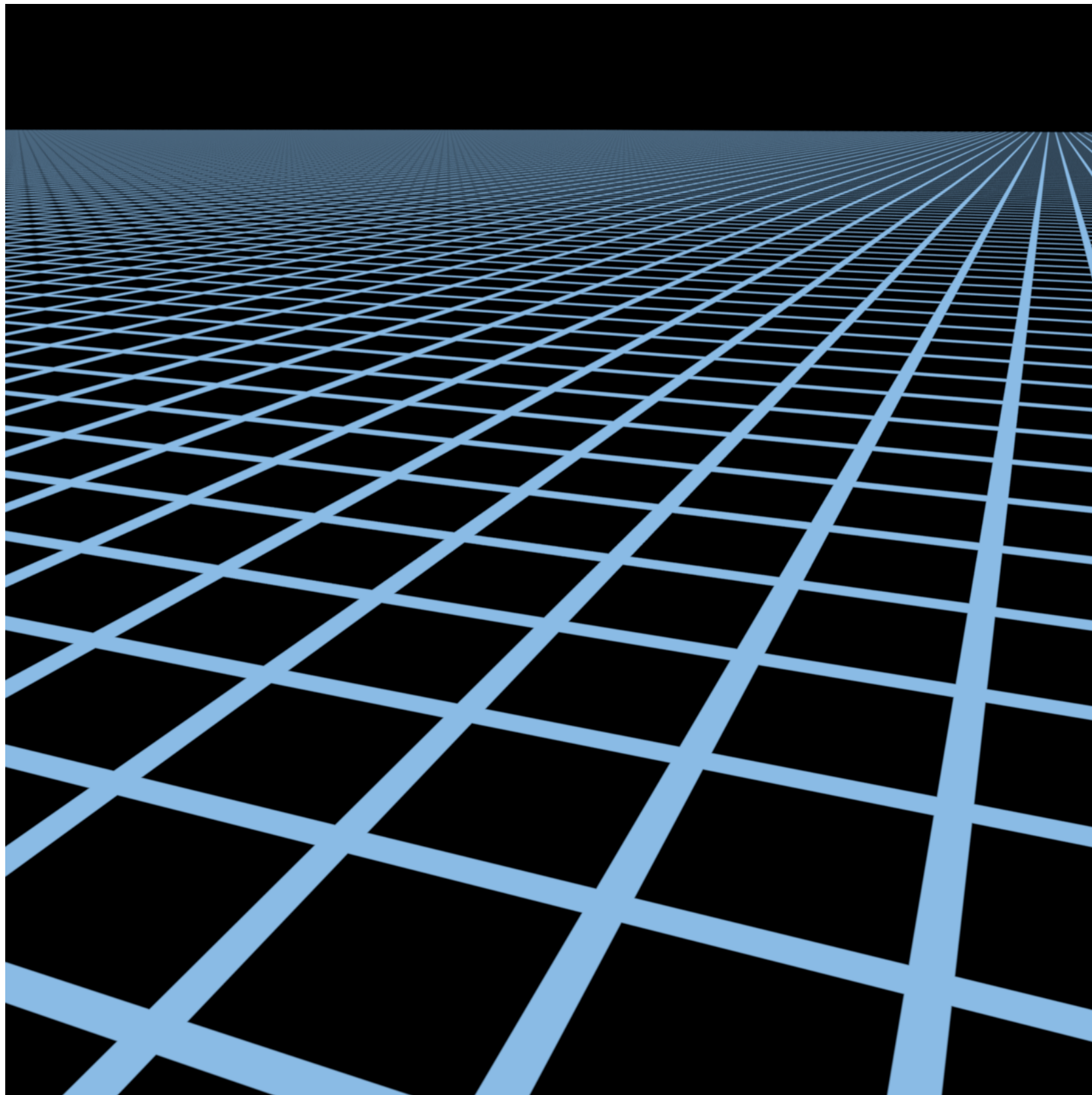
Screen space



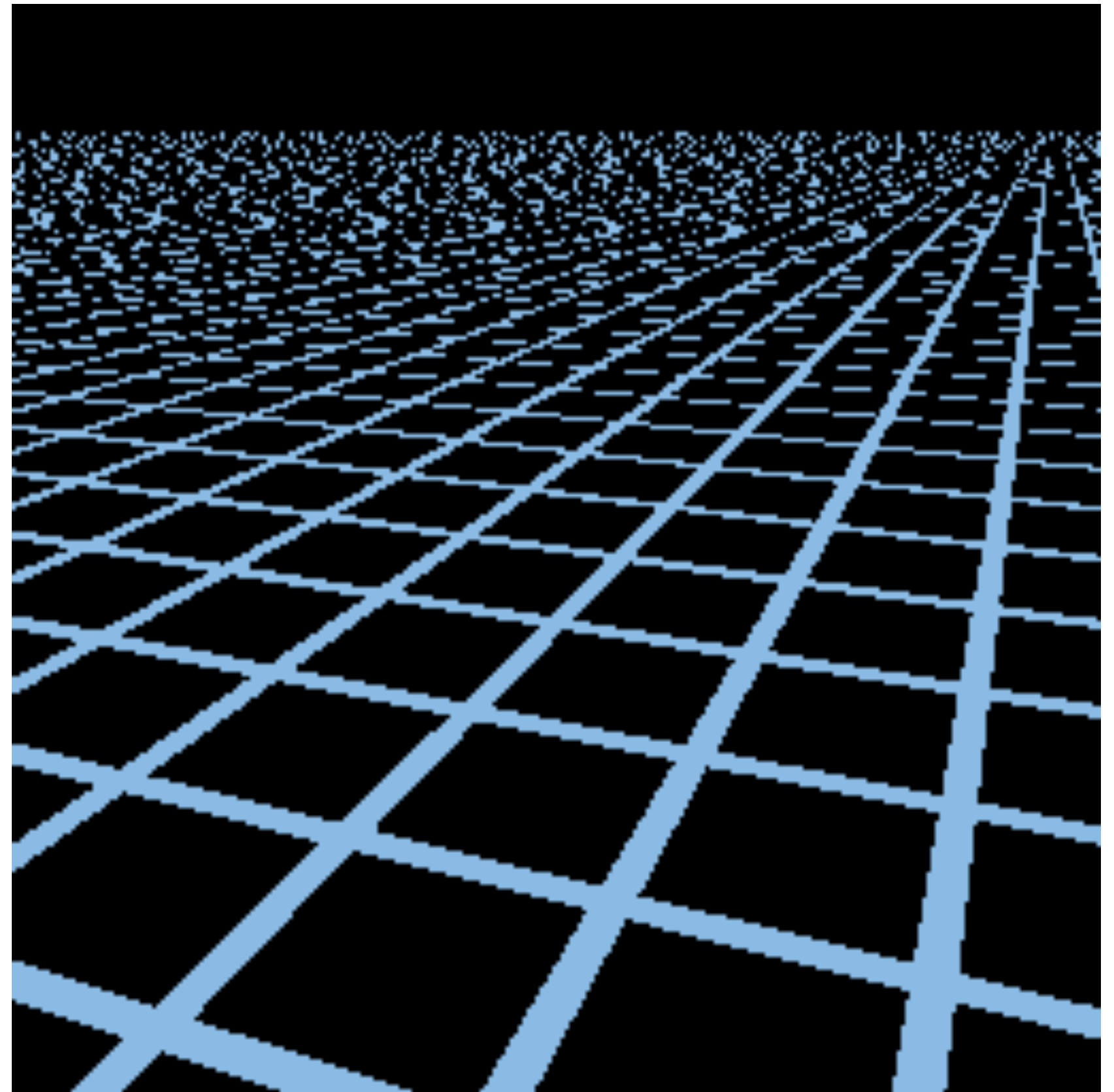
Texture space

Texture Antialiasing

Will Supersampling Antialias?

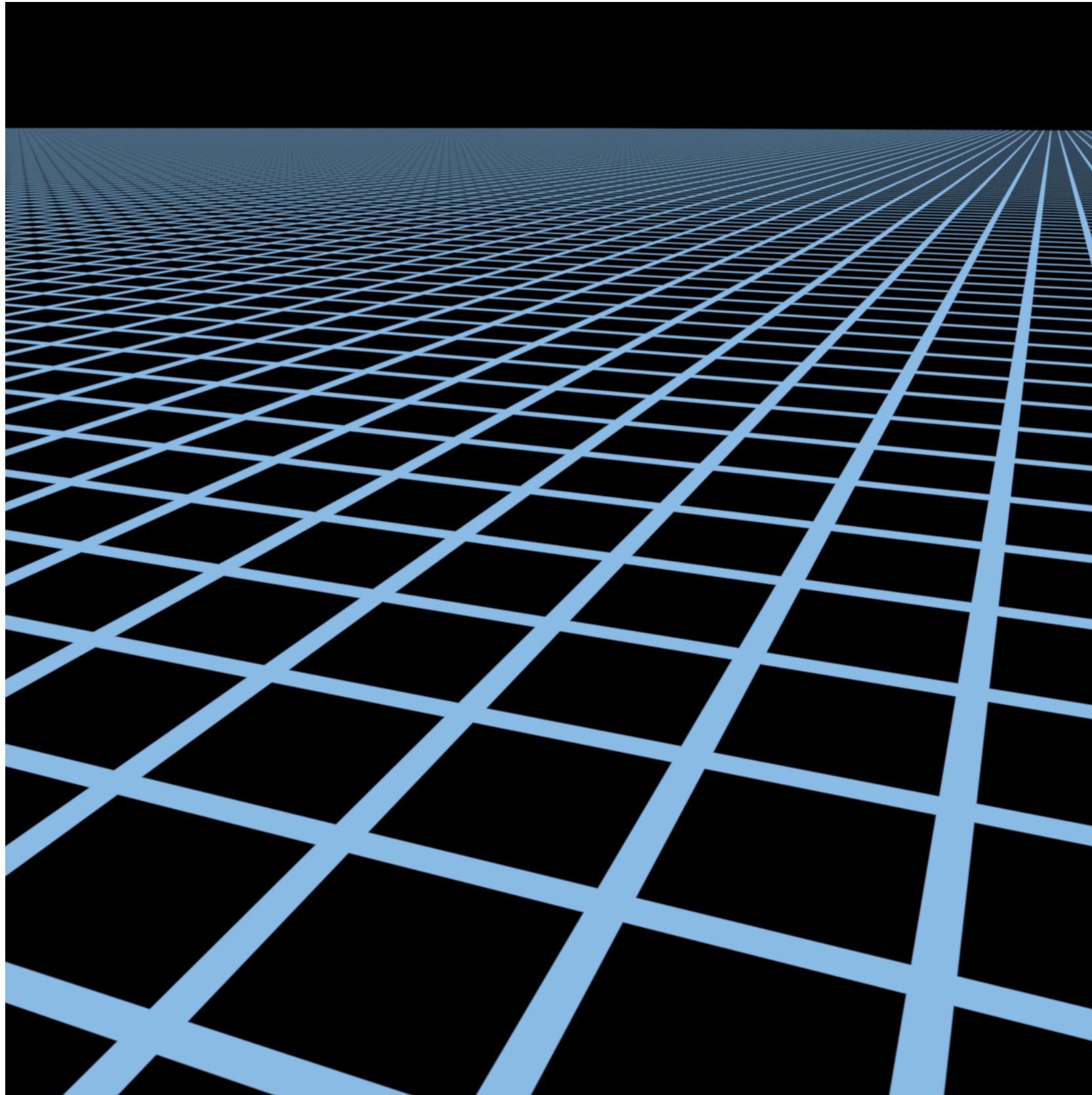


High-res reference

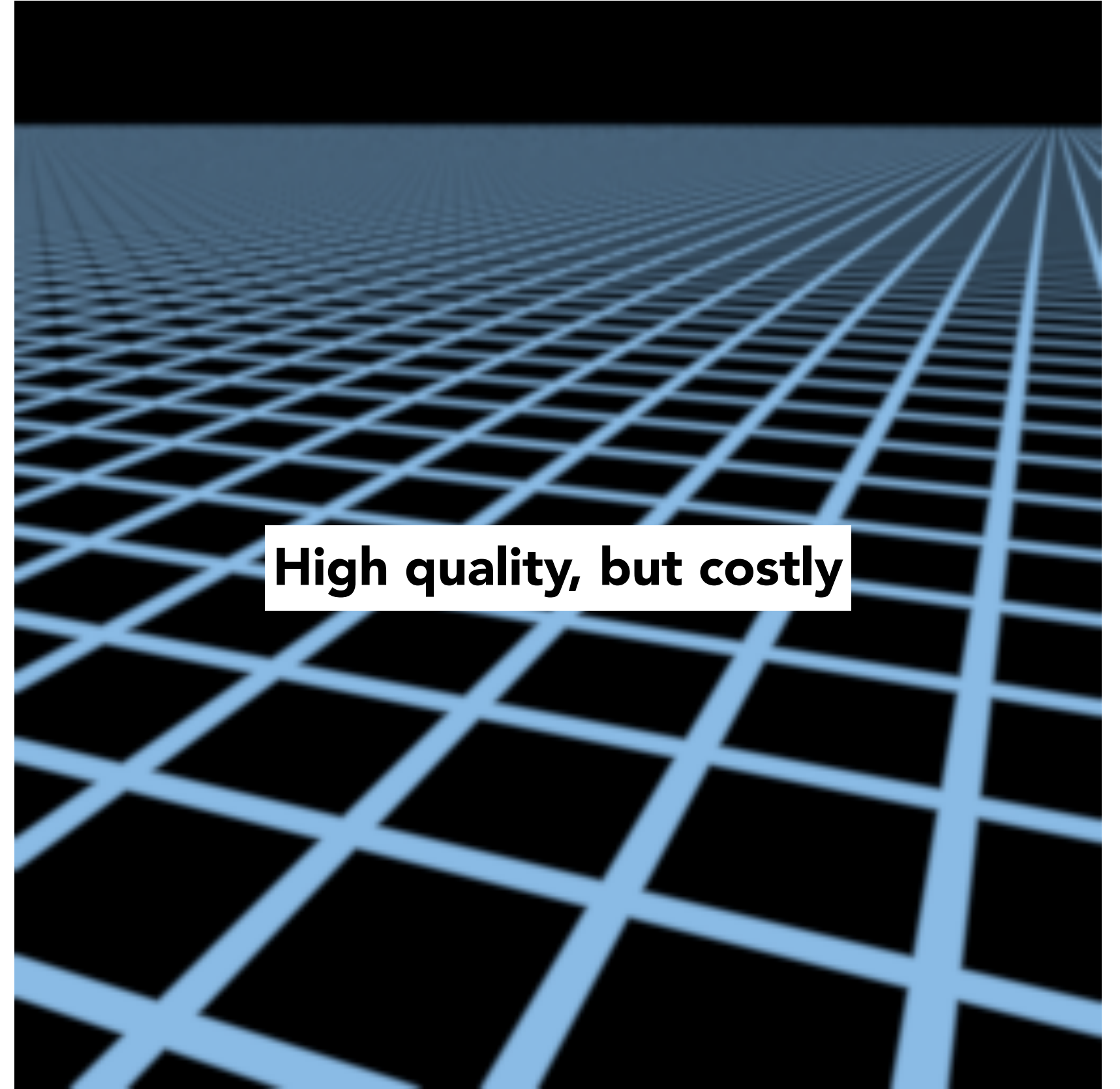


Point sampling

Will Supersampling Antialias?



High-res reference



512x supersampling

Texture Antialiasing

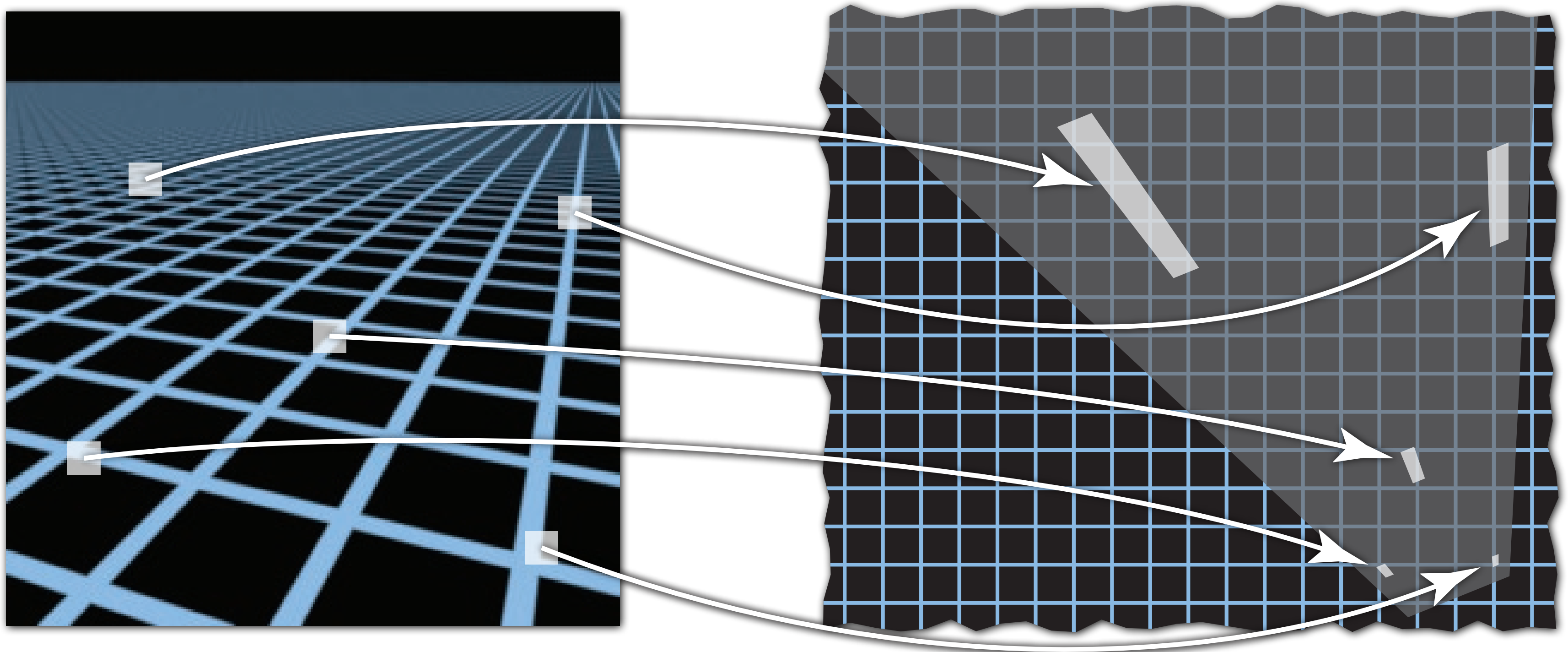
Will supersampling work?

- Yes, high quality, but costly
- When highly minified, many texels in pixel footprint

Goal: efficient texture antialiasing

- Want antialiasing with one/few texels per pixel
- How? Antialiasing = filtering before sampling!

Antialiasing: Signal, Sampling Rate, Nyquist Rate?



Screen space

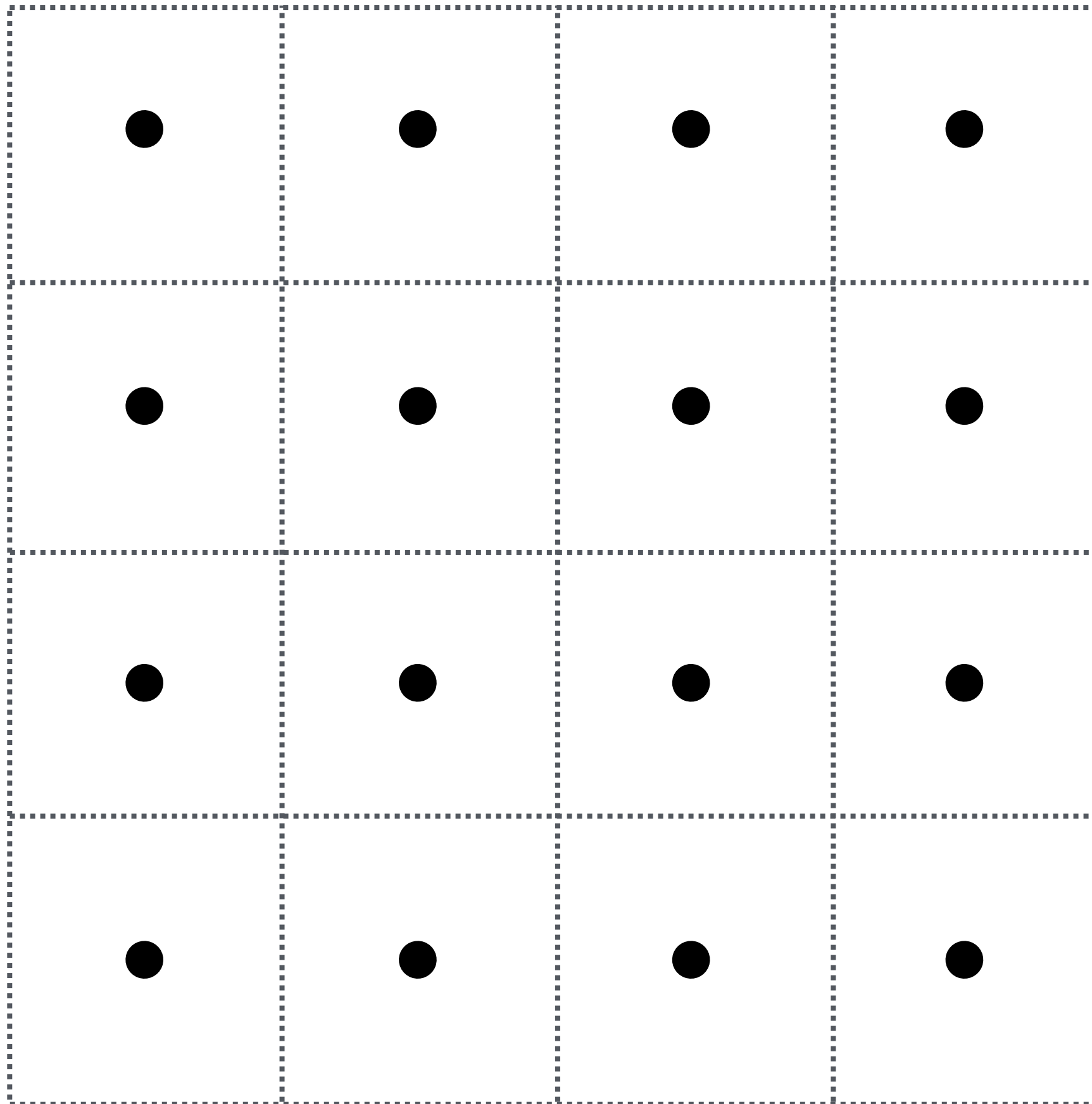
Texture space

What signal are we sampling? What is the sampling frequency? What is the Nyquist frequency?

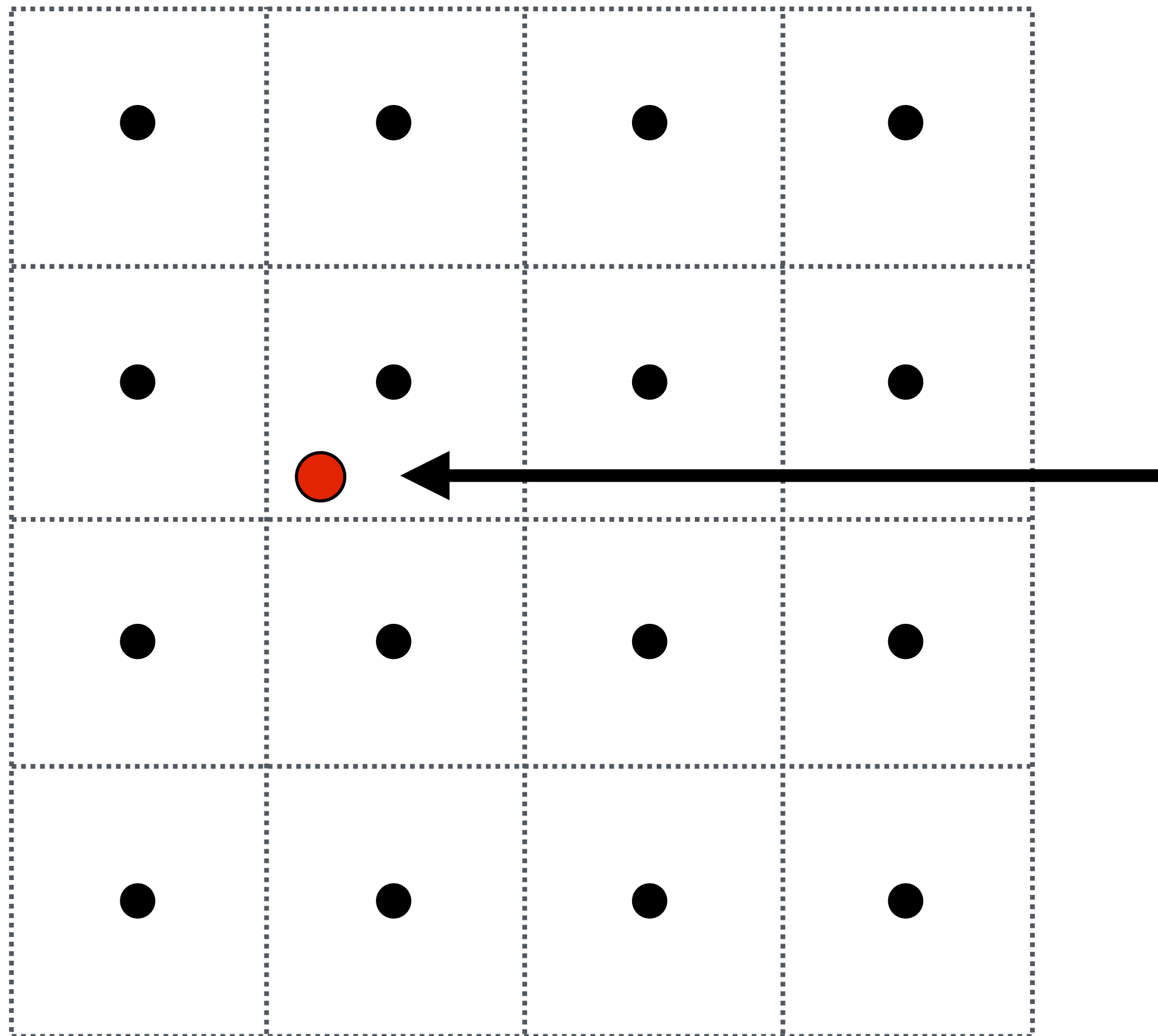
Texture Filtering

Texture Magnification

Bilinear Filtering



Bilinear Filtering



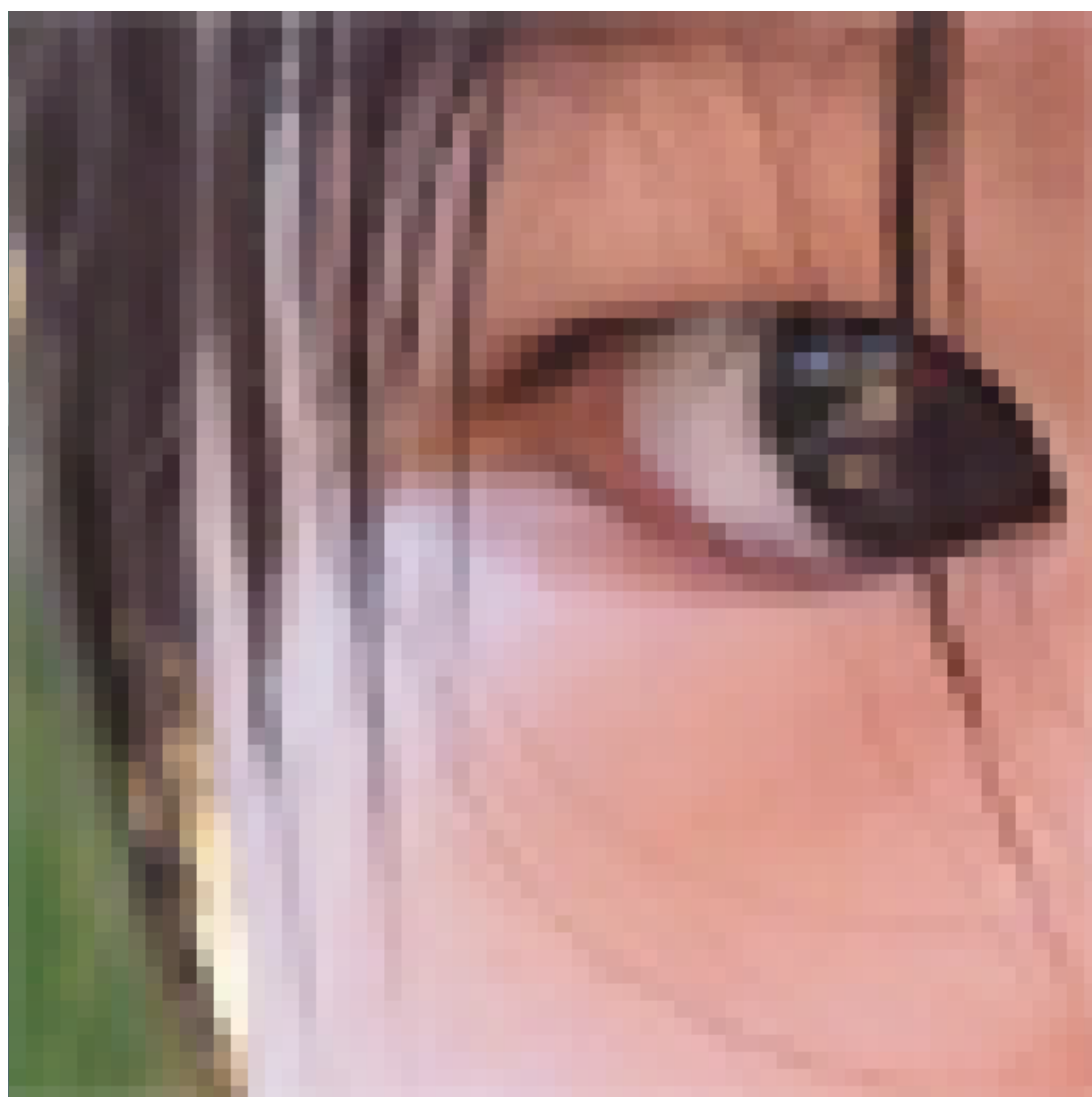
Want to sample
texture value $f(u, v)$ at
red point

Black points indicate
texture sample
locations

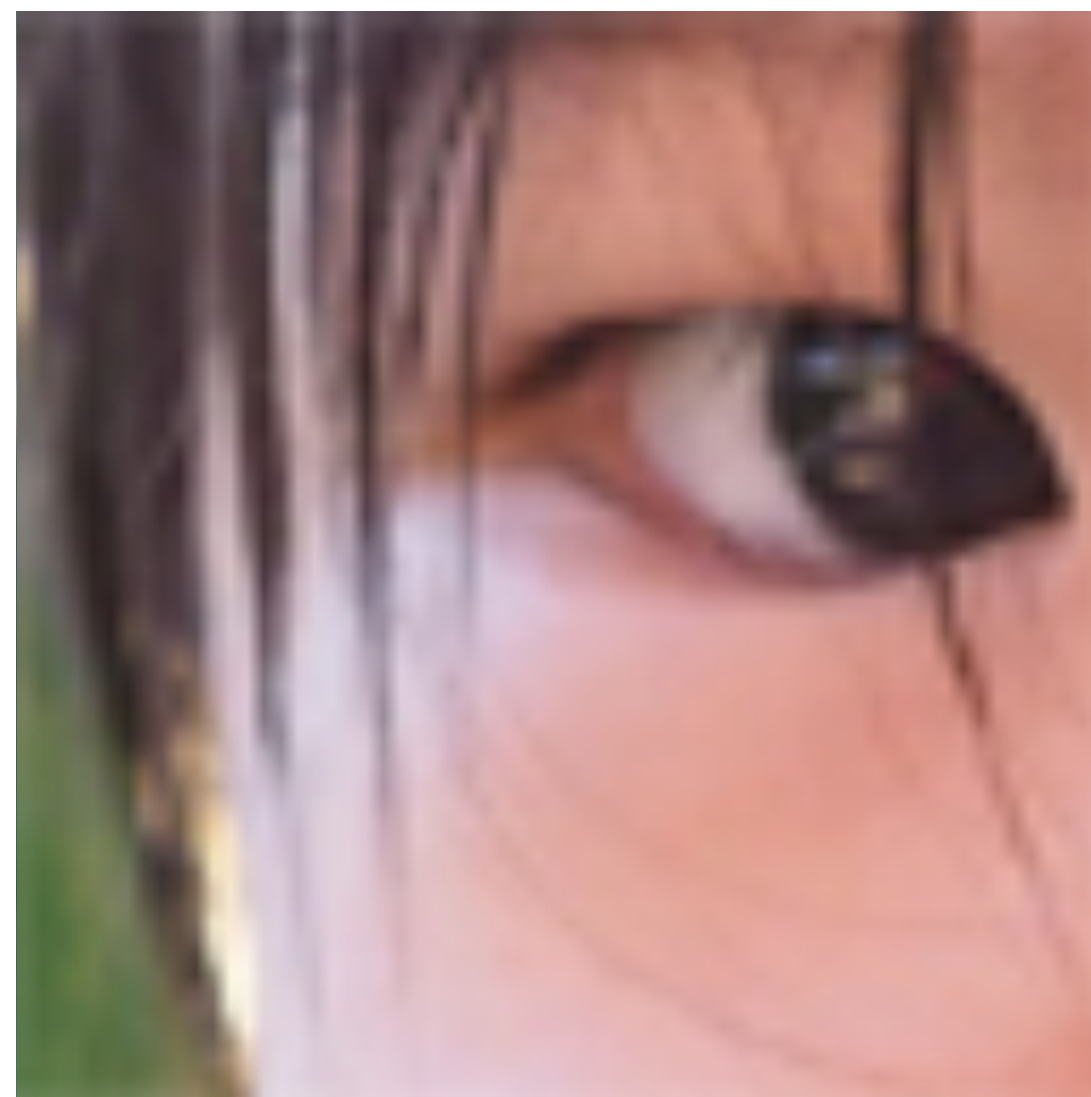
Texture Magnification - Easy Case

(Generally don't want this — insufficient resolution)

This is image interpolation (will see kernel function)



Nearest

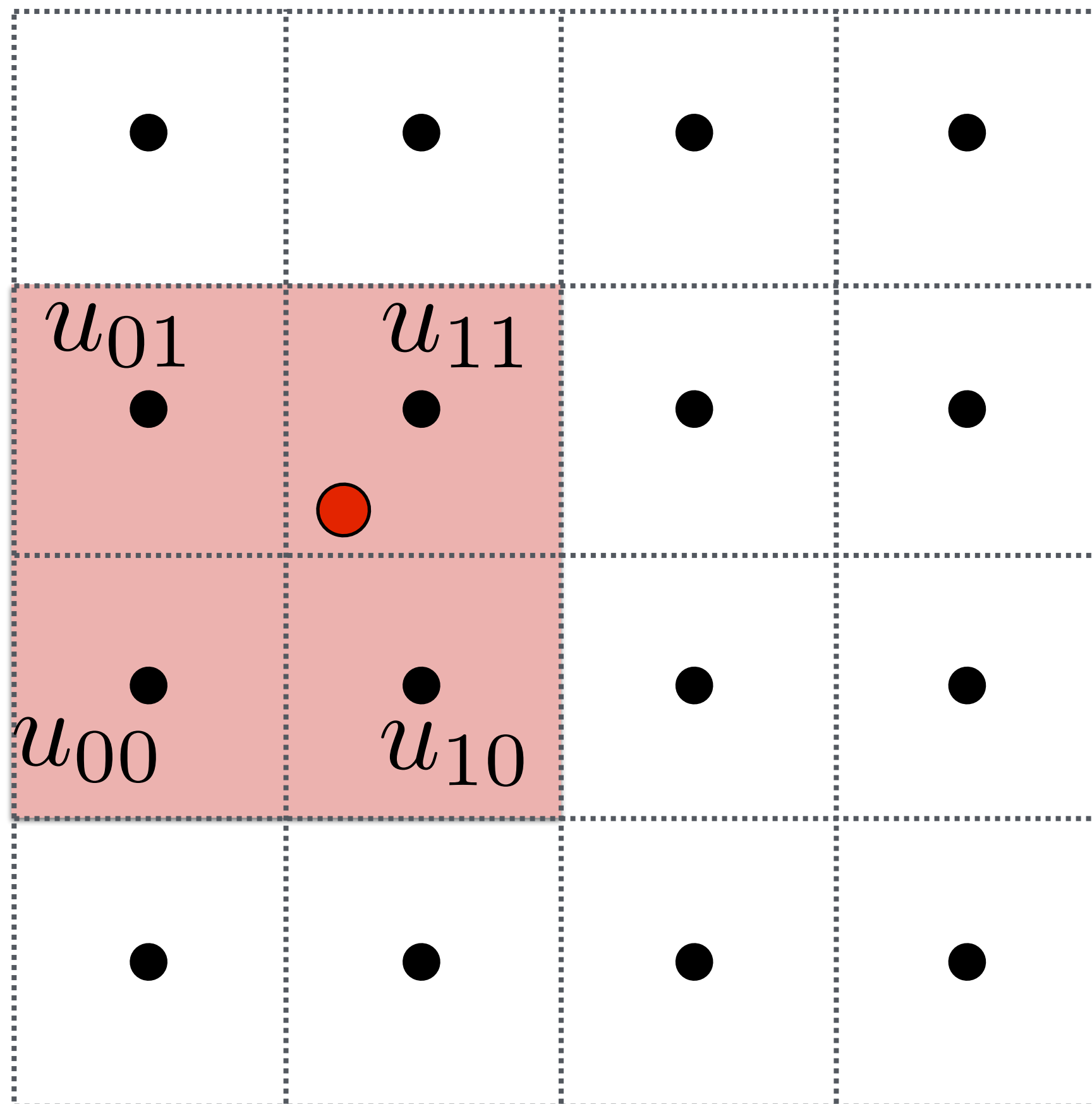


Bilinear



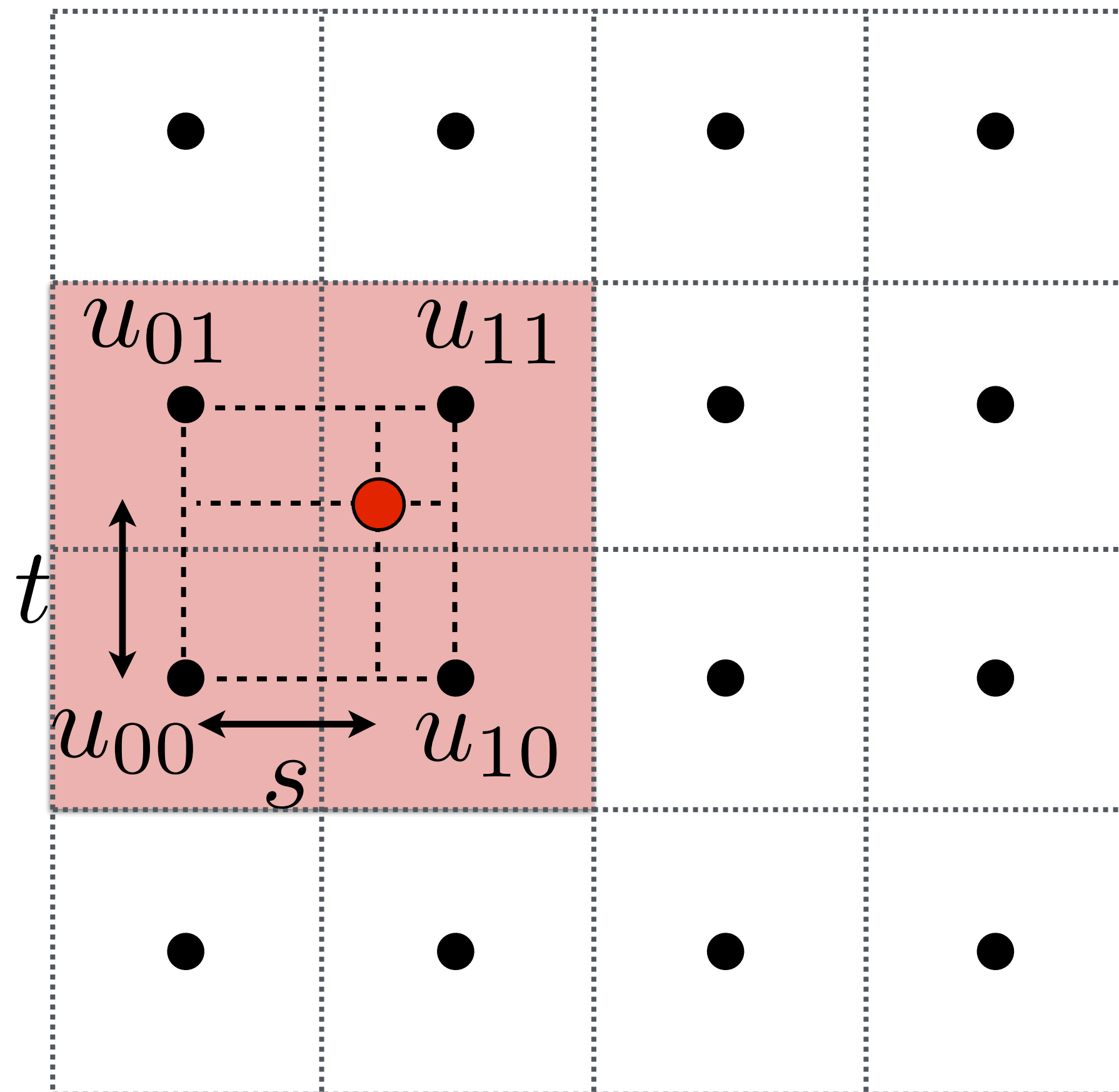
Bicubic

Bilinear Filtering



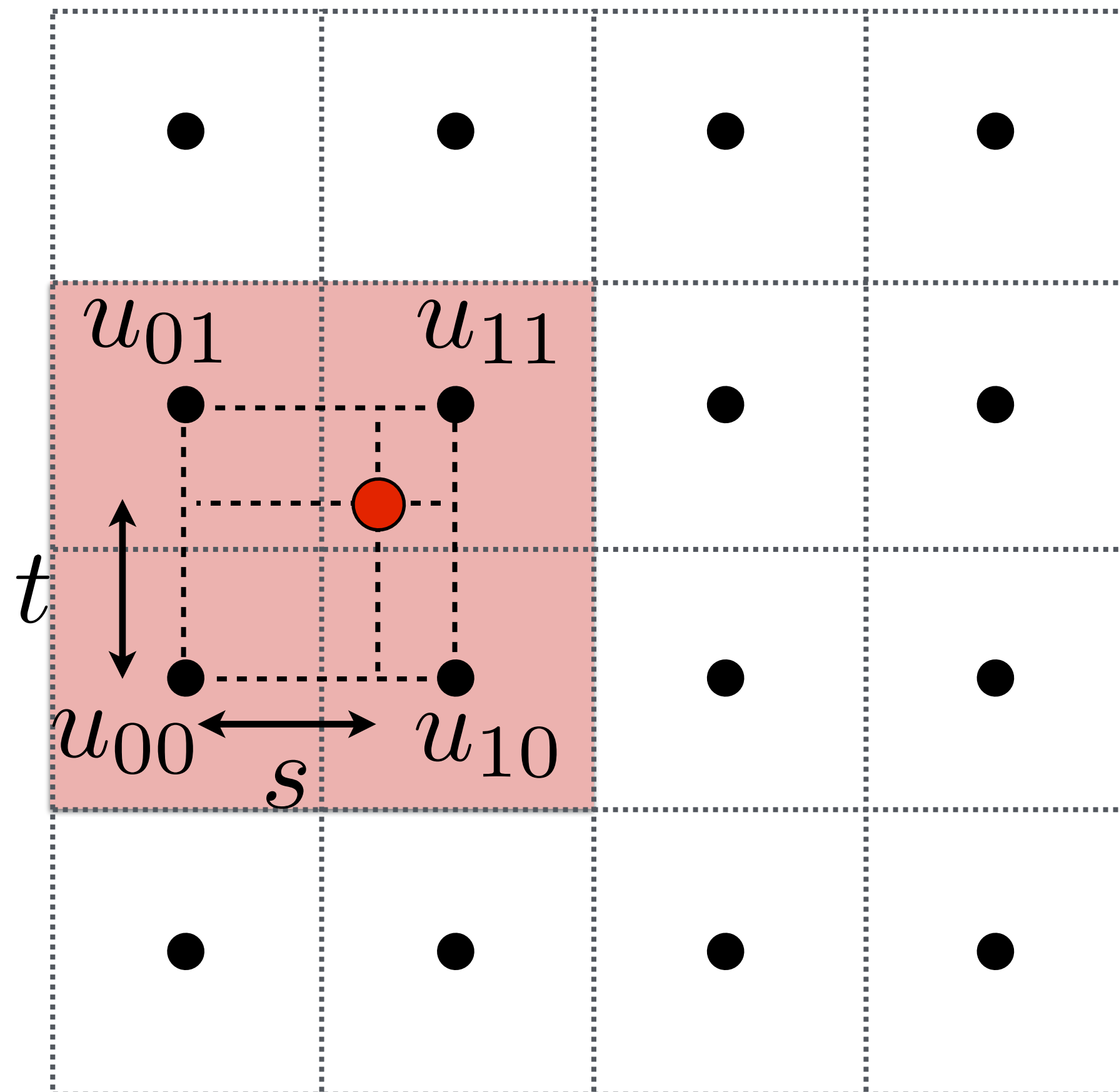
**Take 4 nearest
sample locations,
with texture values
as labeled.**

Bilinear Filtering



**And fractional
offsets, (s,t) as shown**

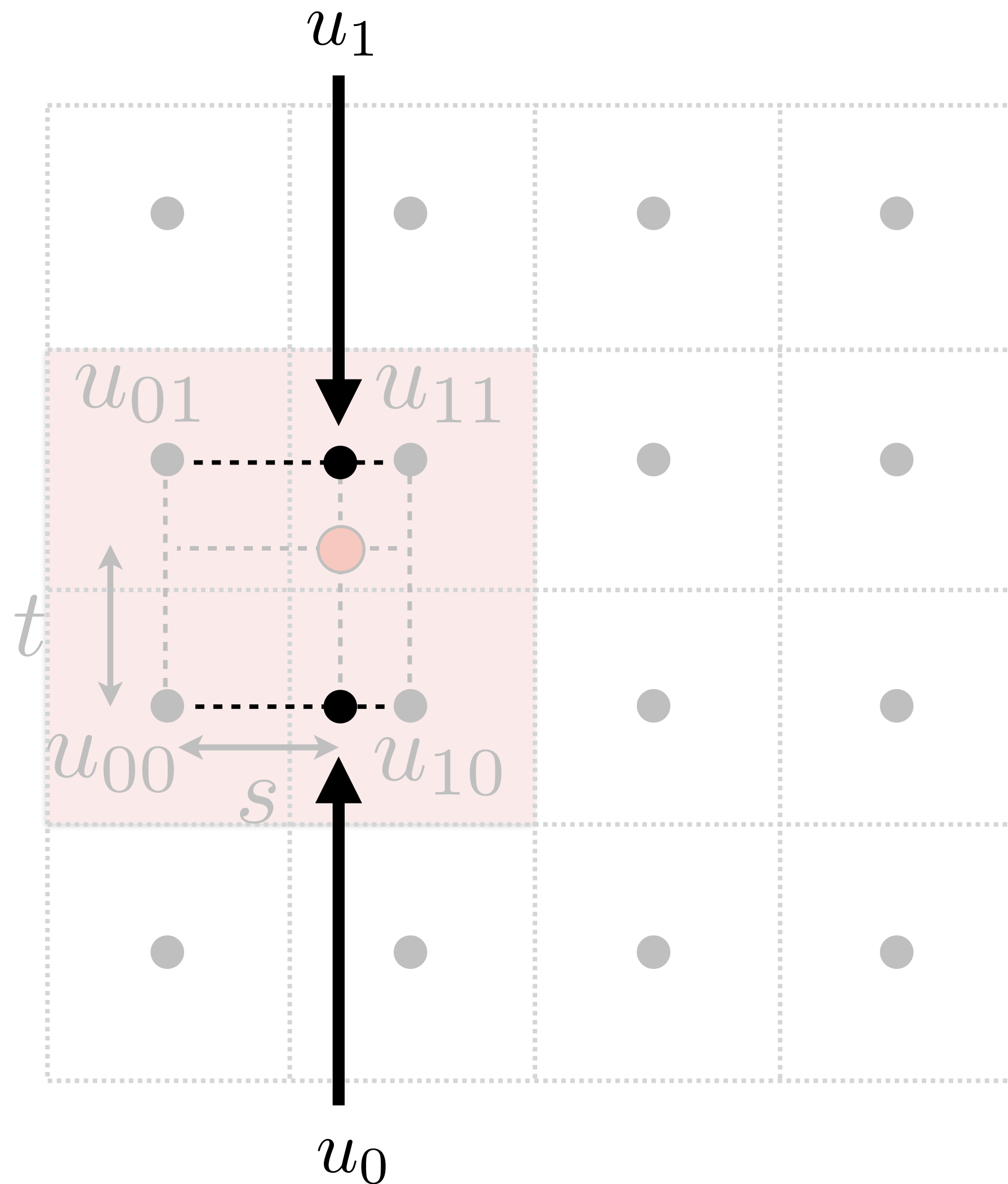
Bilinear Filtering



Linear interpolation (1D)

$$\text{lerp}(x, v_0, v_1) = v_0 + x(v_1 - v_0)$$

Bilinear Filtering



Linear interpolation (1D)

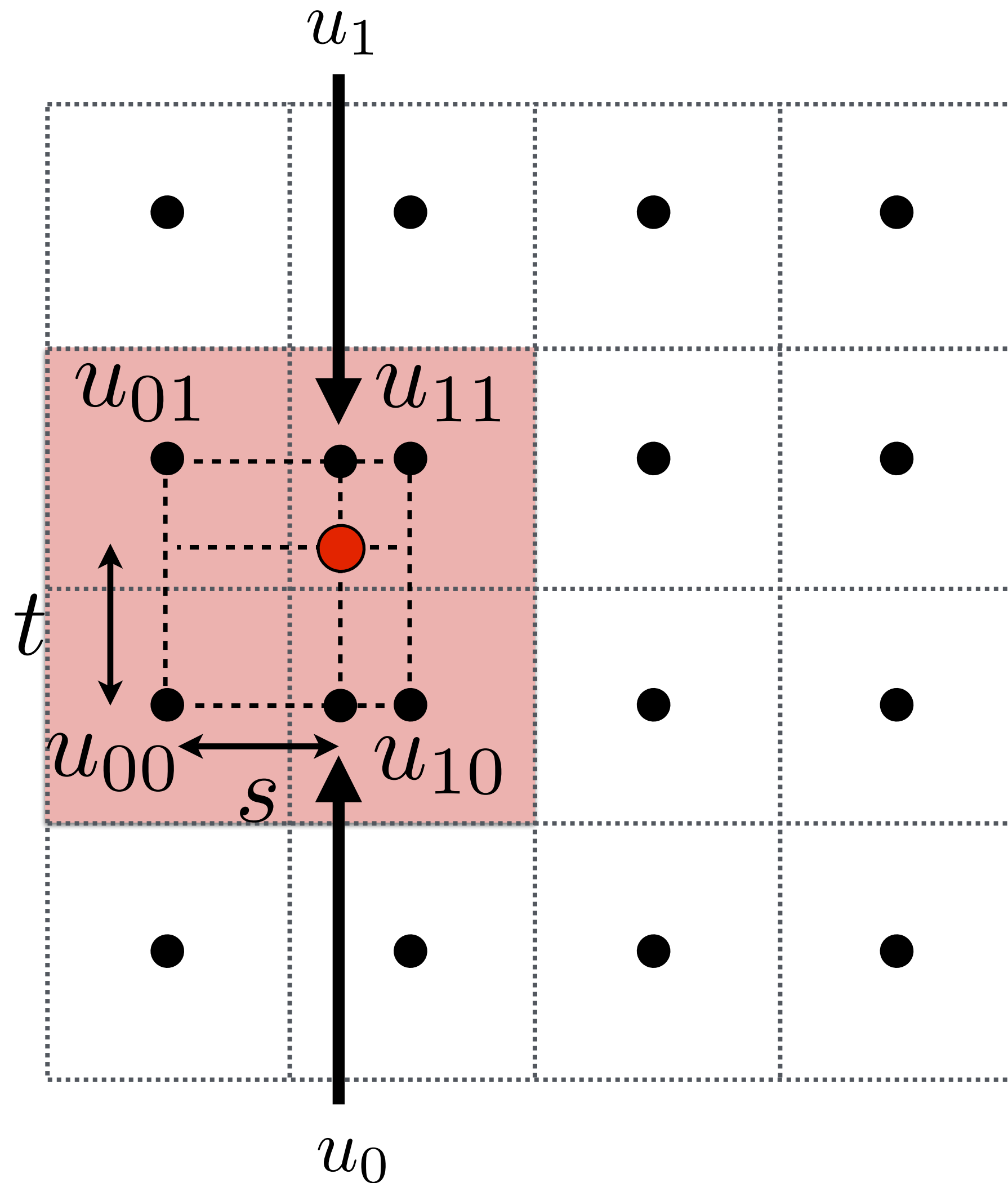
$$\text{lerp}(x, v_0, v_1) = v_0 + x(v_1 - v_0)$$

Two helper lerps (horizontal)

$$u_0 = \text{lerp}(s, u_{00}, u_{10})$$

$$u_1 = \text{lerp}(s, u_{01}, u_{11})$$

Bilinear Filtering



Linear interpolation (1D)

$$\text{lerp}(x, v_0, v_1) = v_0 + x(v_1 - v_0)$$

Two helper lerps

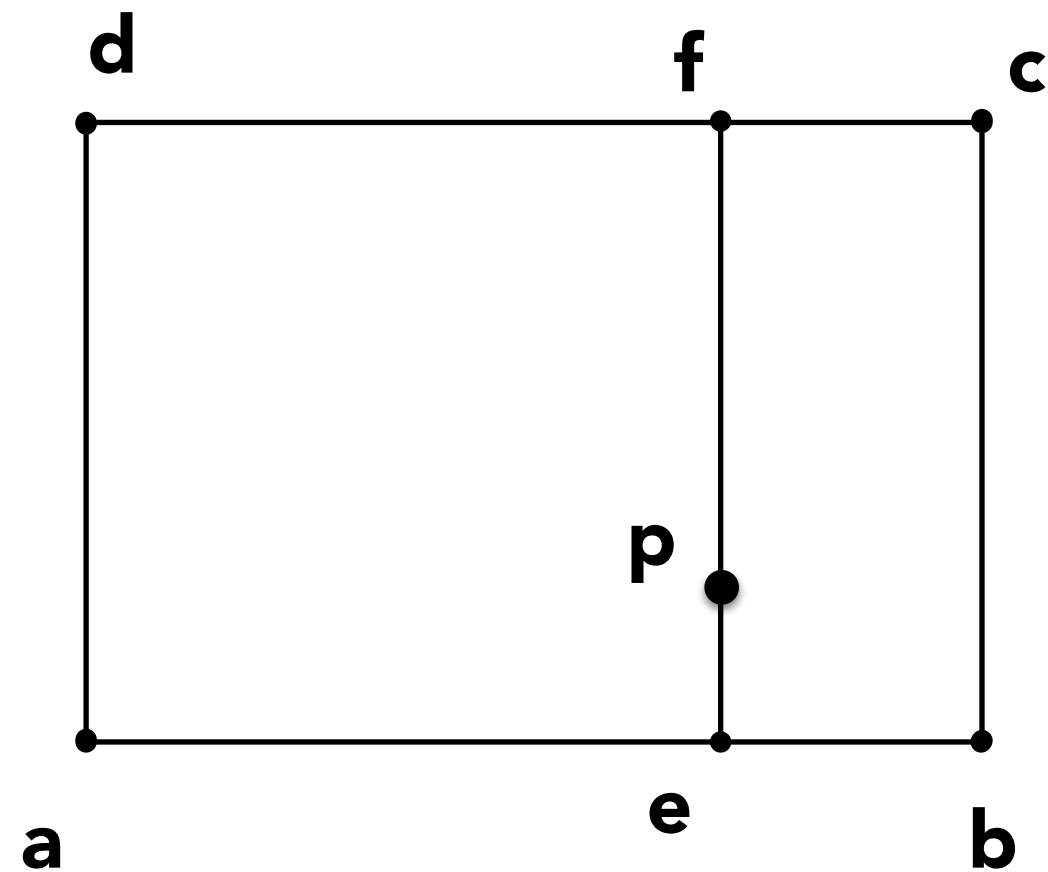
$$u_0 = \text{lerp}(s, u_{00}, u_{10})$$

$$u_1 = \text{lerp}(s, u_{01}, u_{11})$$

Final vertical lerp, to get result:

$$f(x, y) = \text{lerp}(t, u_0, u_1)$$

Bilinear Interpolation

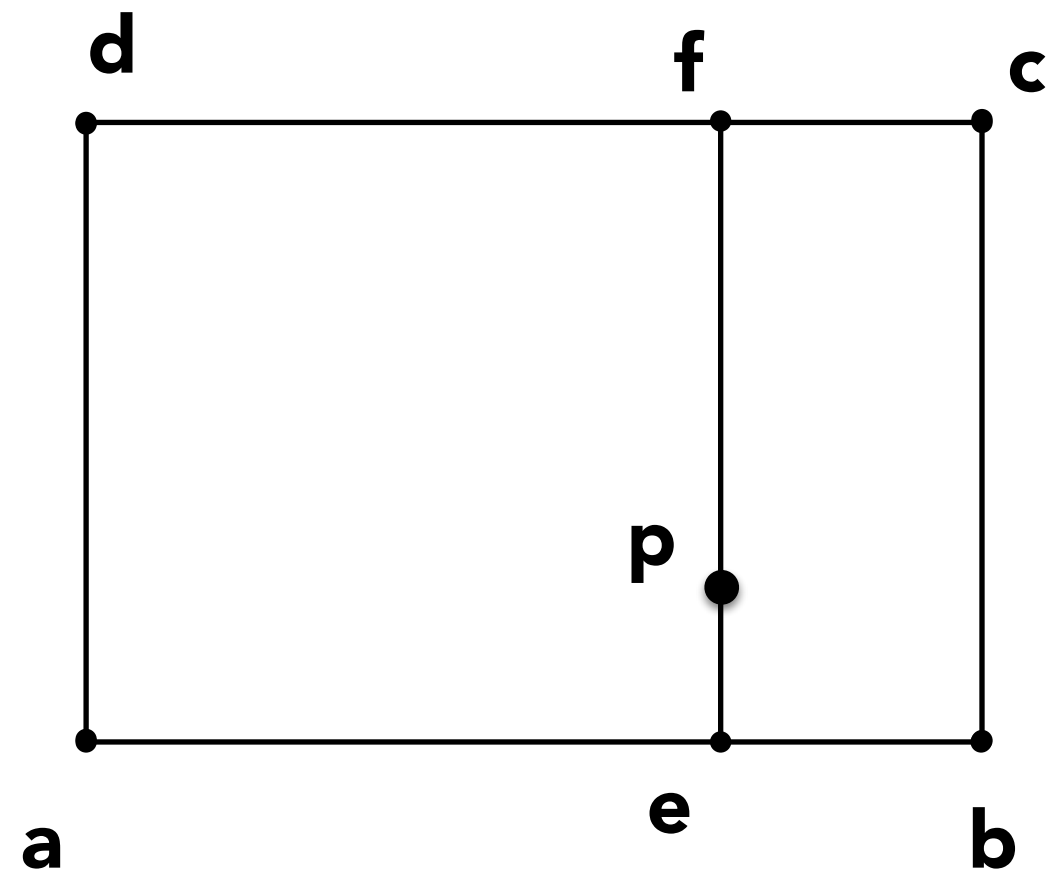


$$\mathbf{e} = \mathbf{a} + \alpha(\mathbf{b} - \mathbf{a})$$

$$\mathbf{f} = \mathbf{d} + \alpha(\mathbf{c} - \mathbf{d})$$

$$\mathbf{p} = \mathbf{e} + \beta(\mathbf{f} - \mathbf{e})$$

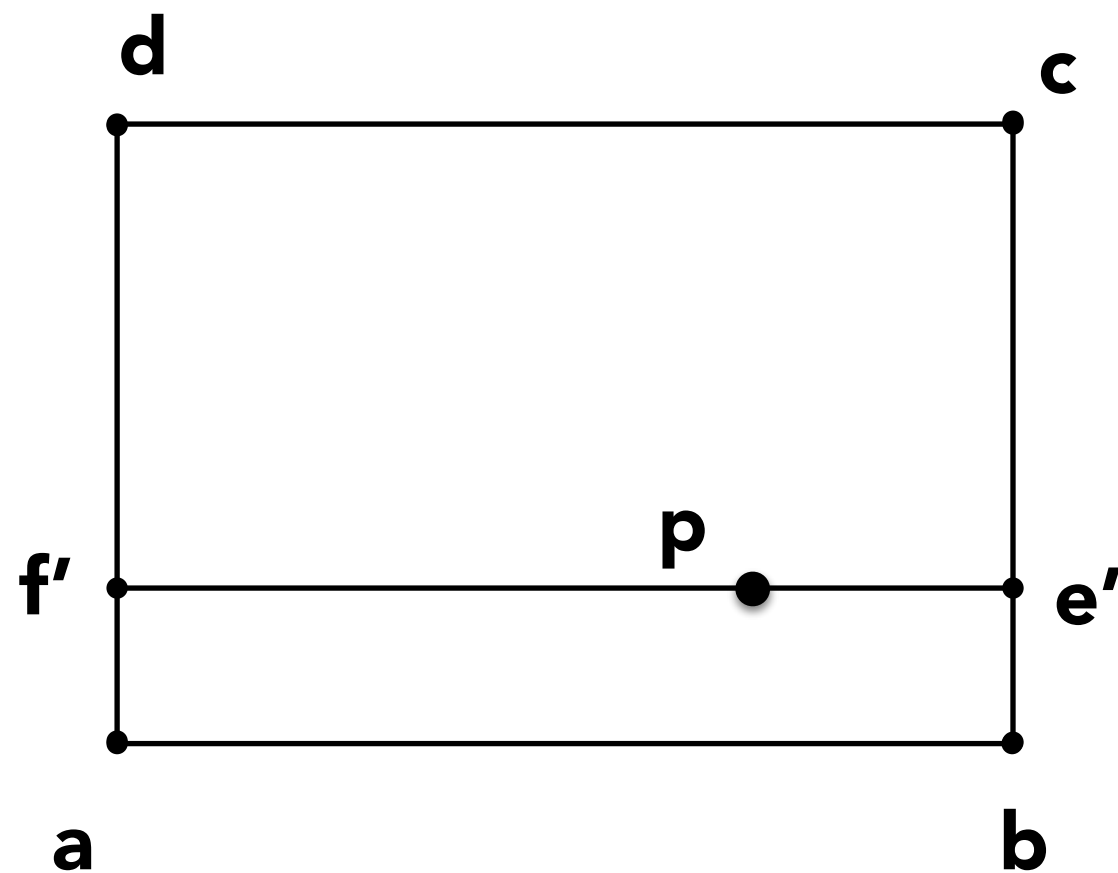
Bilinear Interpolation



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$$\mathbf{p} = \mathbf{e} + \beta(\mathbf{f} - \mathbf{e})$$



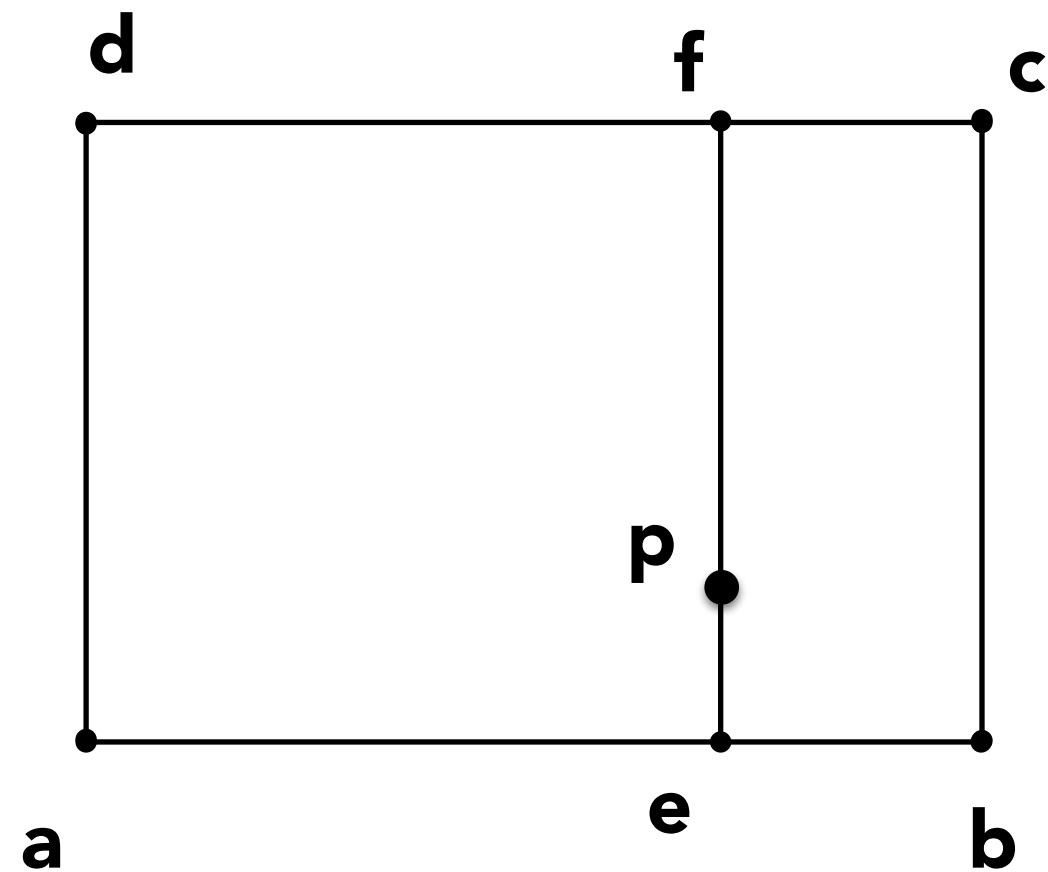
Same answer either way.

$$\mathbf{e}' = \mathbf{b} + \beta(\mathbf{c} - \mathbf{b})$$

$$\mathbf{f}' = \mathbf{a} + \beta(\mathbf{d} - \mathbf{a})$$

$$\mathbf{p} = \mathbf{f}' + \alpha(\mathbf{e}' - \mathbf{f}')$$

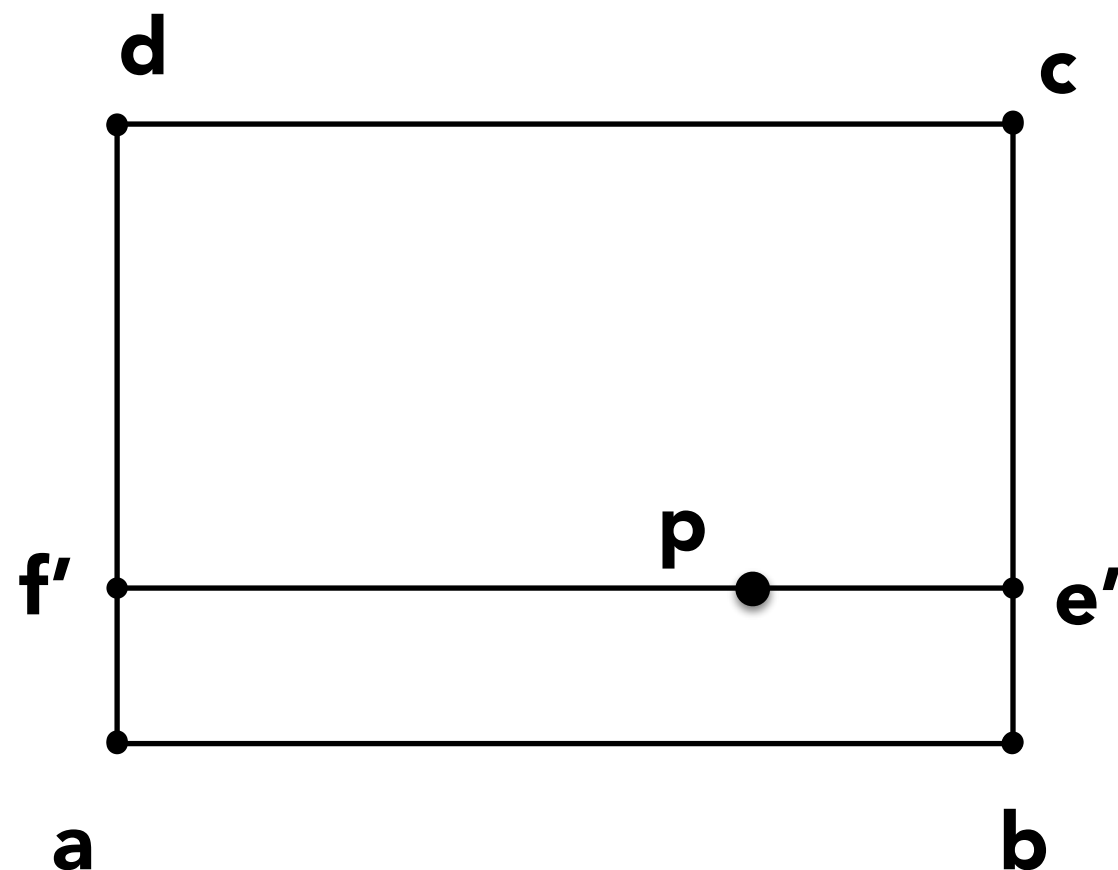
Bilinear Interpolation



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Same answer either way.

$$\mathbf{e}' = \mathbf{b} + \beta(\mathbf{c} - \mathbf{b})$$

$$\mathbf{f}' = \mathbf{a} + \beta(\mathbf{d} - \mathbf{a})$$

$$\mathbf{p} = \mathbf{f}' + \alpha(\mathbf{e}' - \mathbf{f}')$$

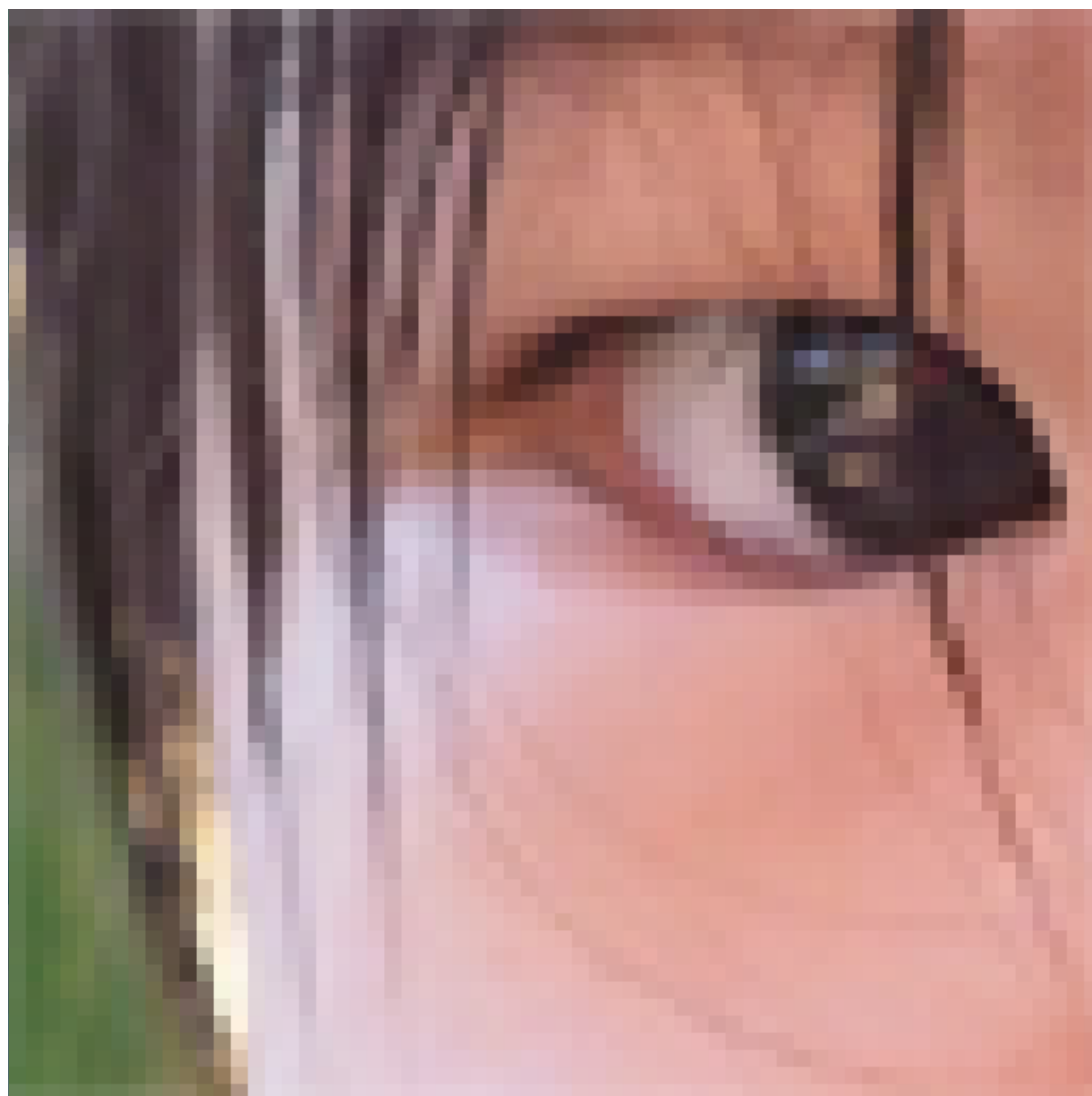
$$\alpha = \frac{||\mathbf{e} - \mathbf{a}||}{||\mathbf{b} - \mathbf{a}||}$$

$$\beta = \frac{||\mathbf{f}' - \mathbf{a}||}{||\mathbf{d} - \mathbf{a}||}$$

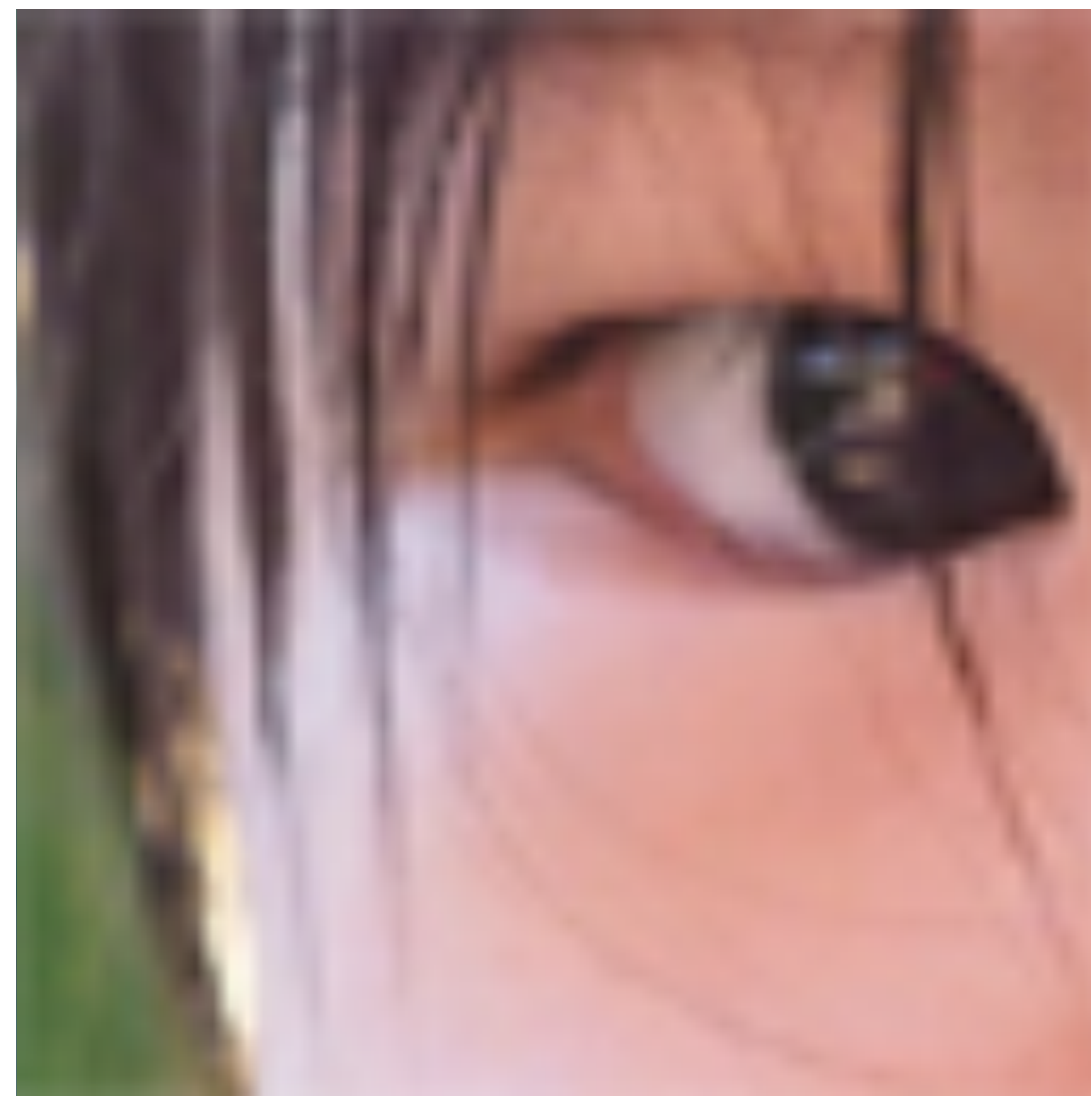
Reconstruction Filter Function

Test your understanding:

- What is the reconstruction filter $k(x,y)$ for bilinear interpolation? Nearest? What is a theoretically ideal filter? What are the pros/cons of each?



Nearest



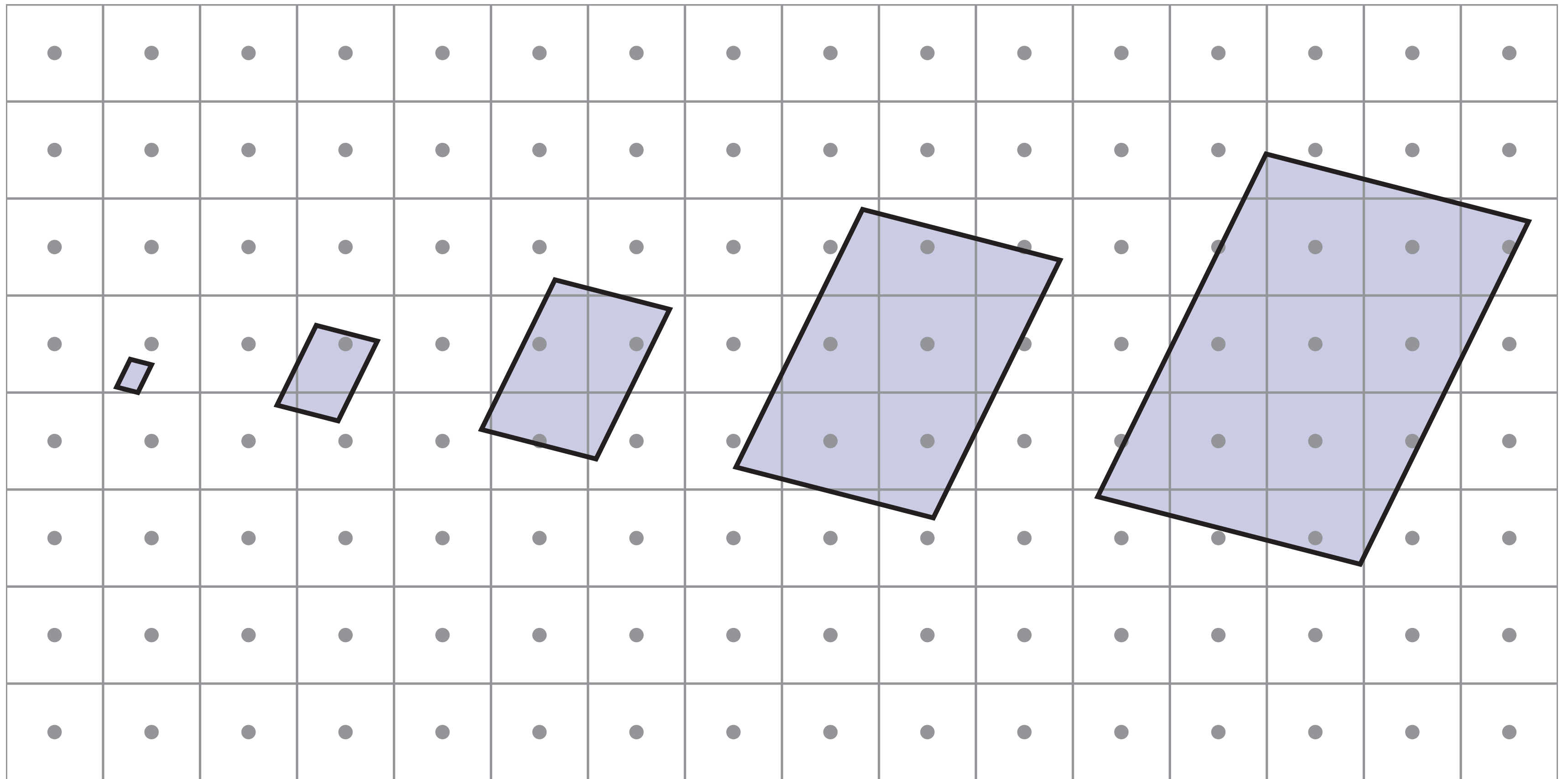
Bilinear



Bicubic

Texture Minification

Screen Pixel Footprint in Texture



**Upsampling
(Magnification)**



**Downsampling
(Minification)**

Texture Minification - Hard Case

Texture Minification - Hard Case

Challenging

Texture Minification - Hard Case

Challenging

- Many texels can contribute to pixel footprint

Texture Minification - Hard Case

Challenging

- Many texels can contribute to pixel footprint
- Shape of pixel footprint can be complex

Texture Minification - Hard Case

Challenging

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- Shape of pixel footprint can be complex

Idea:

Texture Minification - Hard Case

Challenging

- Many texels can contribute to pixel footprint
- Shape of pixel footprint can be complex

Idea:

- Take texture image file, then low-pass filter it (i.e. filter out high frequencies) and downsample it (i.e. sample at a lower resolution) texture file. Do this recursively, and store successively lower resolution, each with successively lower maximum signal frequency.

Texture Minification - Hard Case

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- For each sample, use the texture file whose resolution approximates the screen sampling rate

Texture Minification - Hard Case

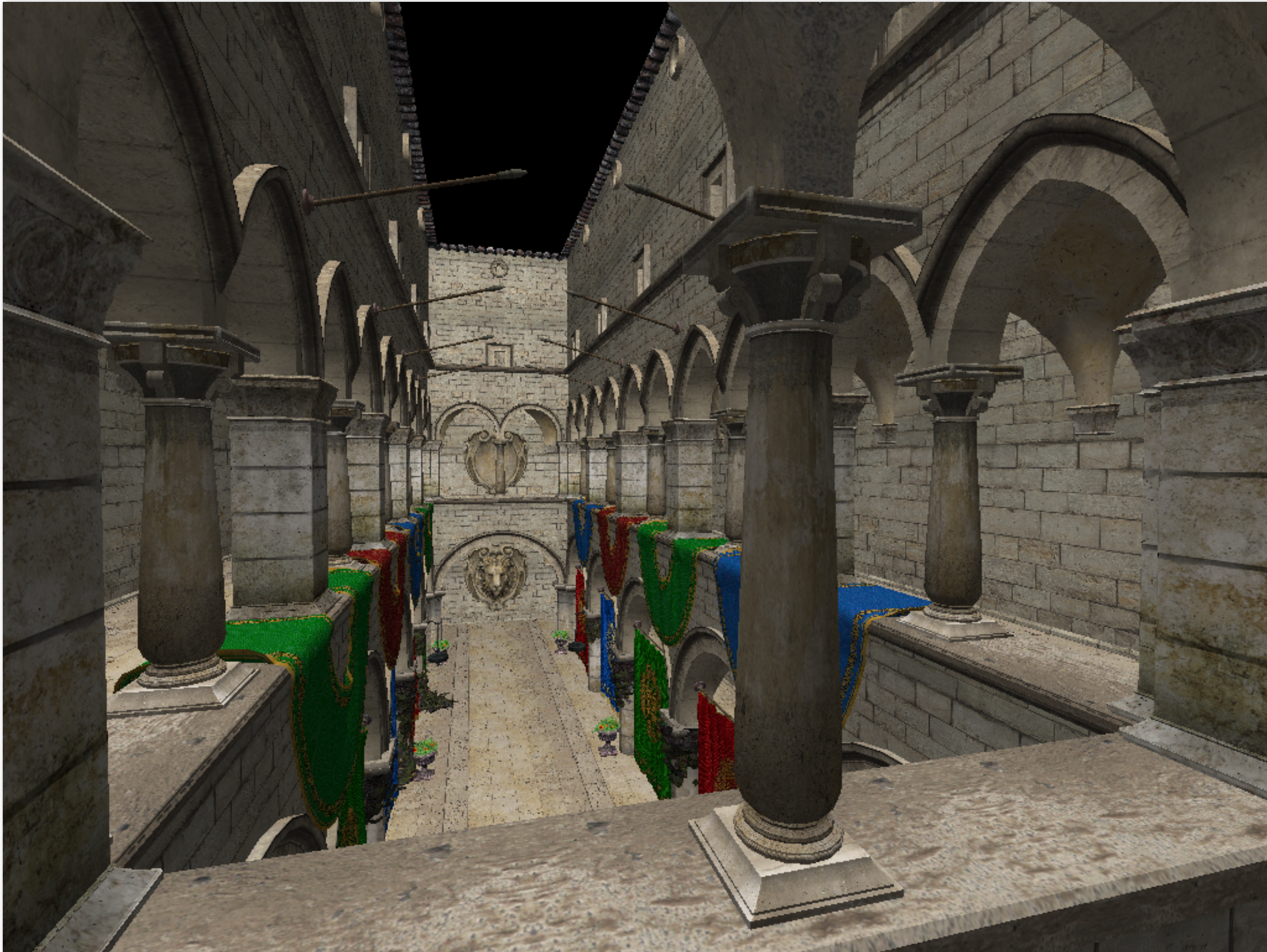
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Level 0 - Full Resolution Texture



Level 0 - Full Resolution Texture



Level 2 - Downsample 4x4



Level 4 - Downsample 16x16



Mipmap (L. Williams 83)



Level 0 = 128x128



Level 1 = 64x64



Level 2 = 32x32



Level 3 = 16x16



Level 4 = 8x8



Level 5 = 4x4



Level 6 = 2x2



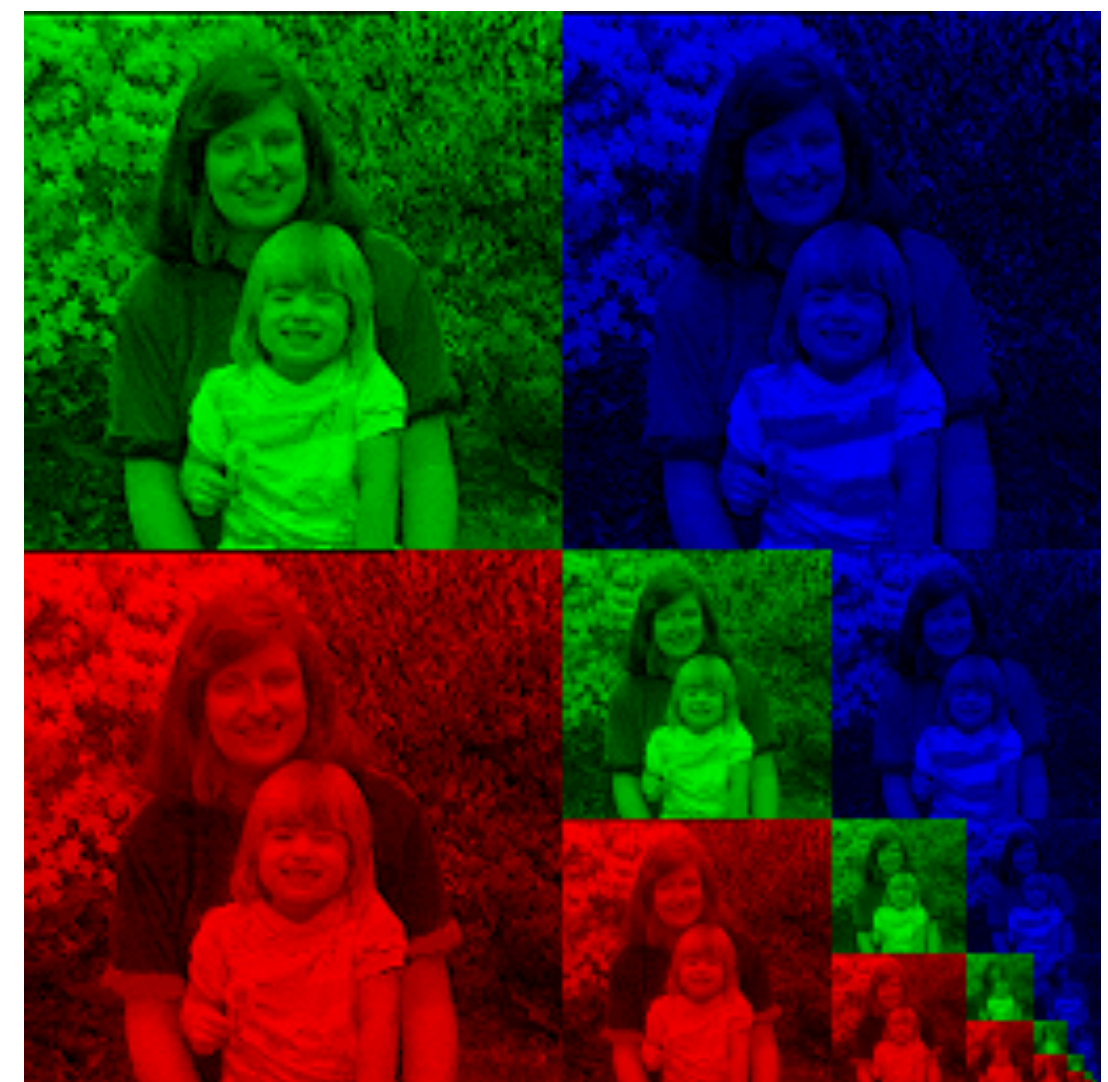
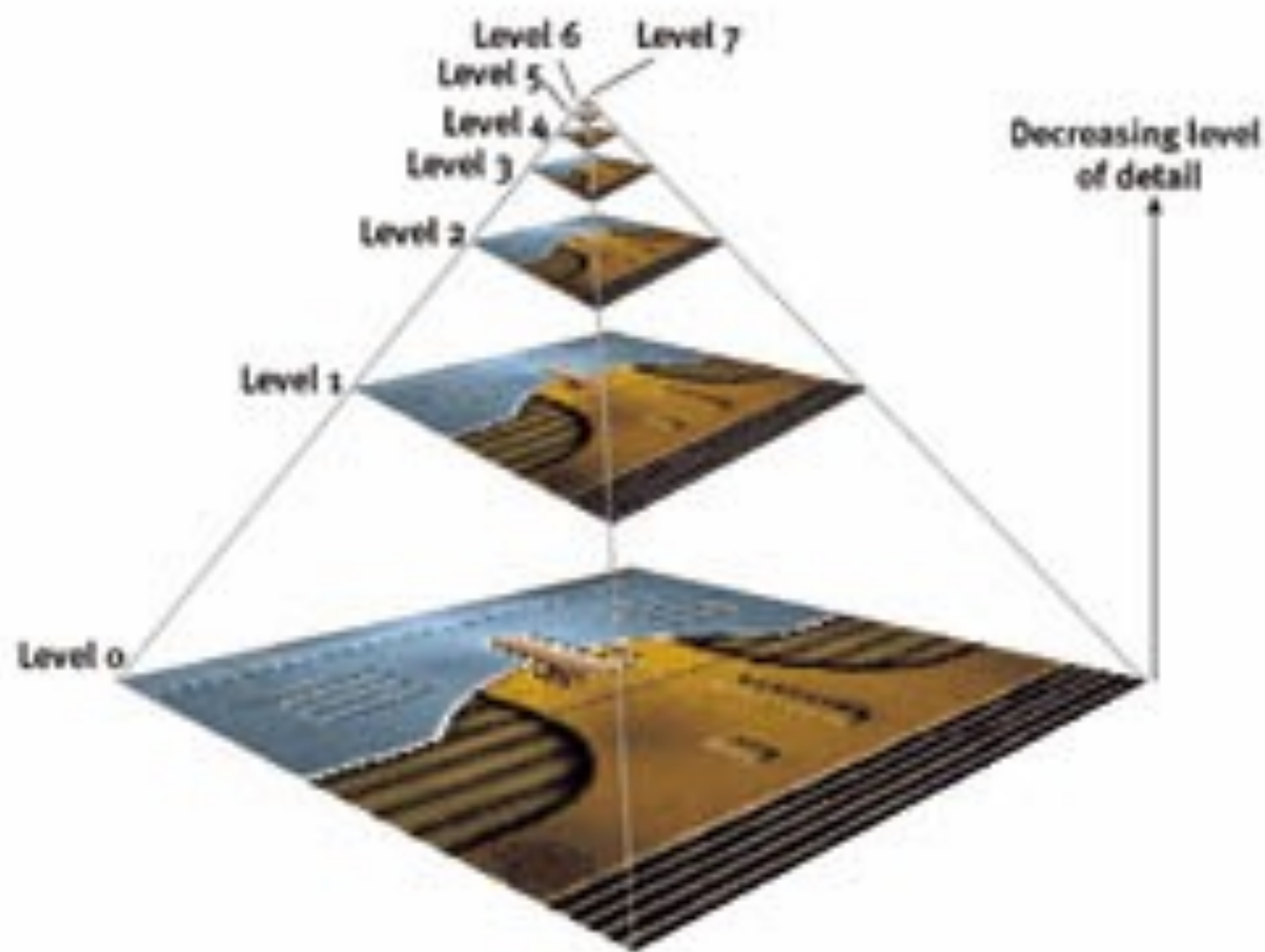
Level 7 = 1x1

"Mip" comes from the Latin "multum in parvo", meaning a multitude in a small space

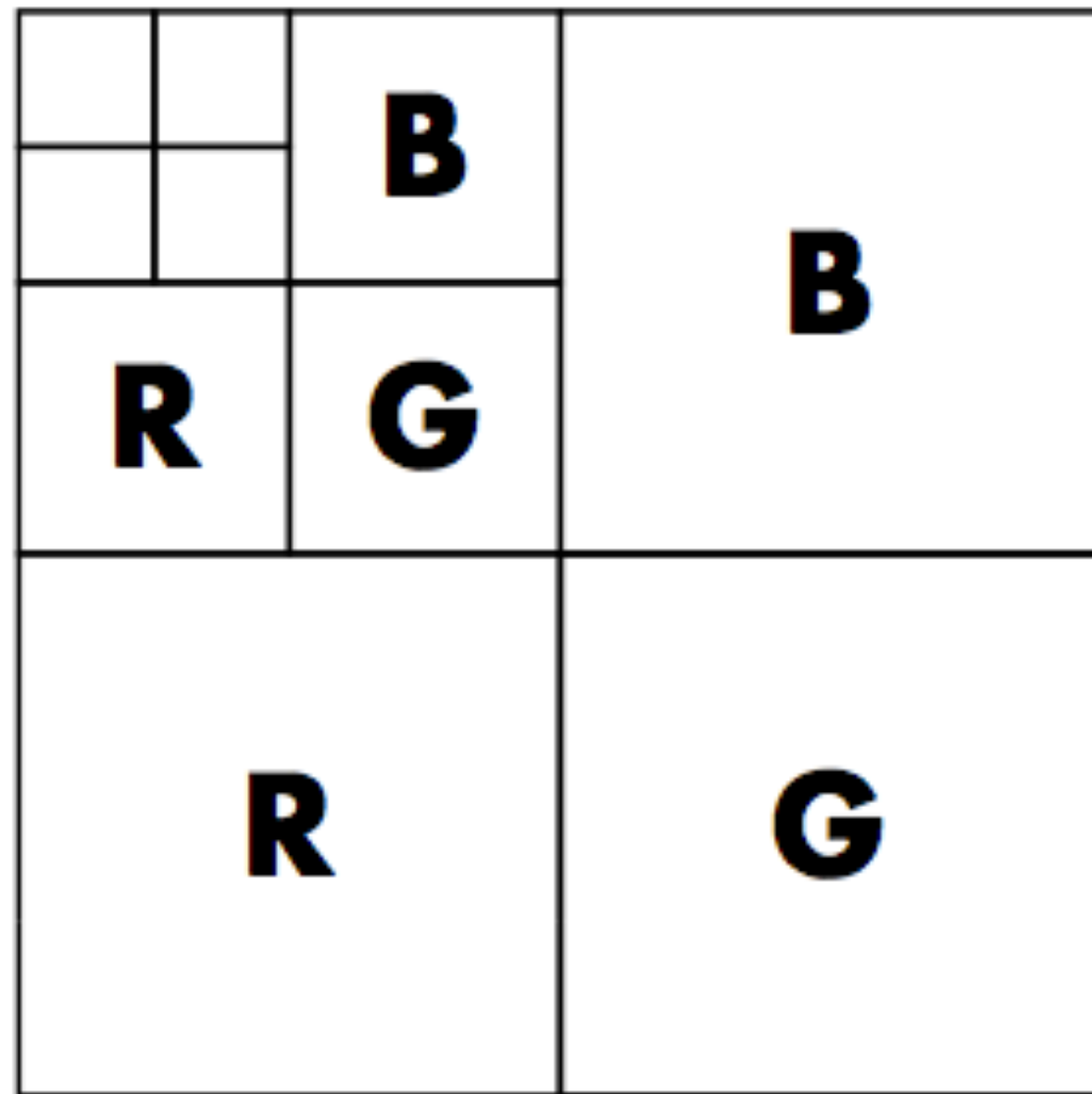
MIP Map

Pre-compute filtered versions of the texture

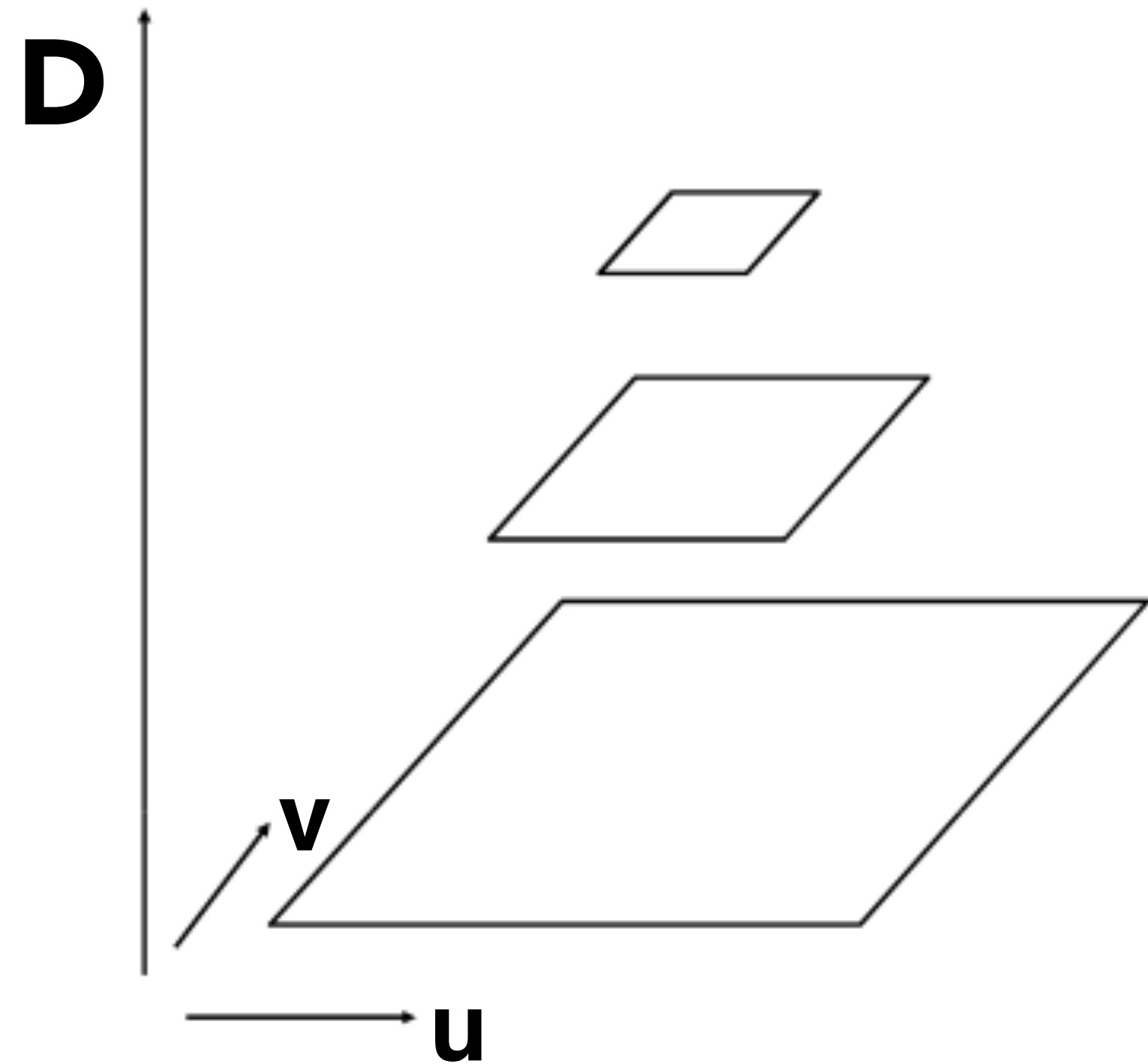
- A given UV rate is some level of the texture
- Tri-linear filtering $UV \times \text{map level}$



Mipmap (L. Williams 83)



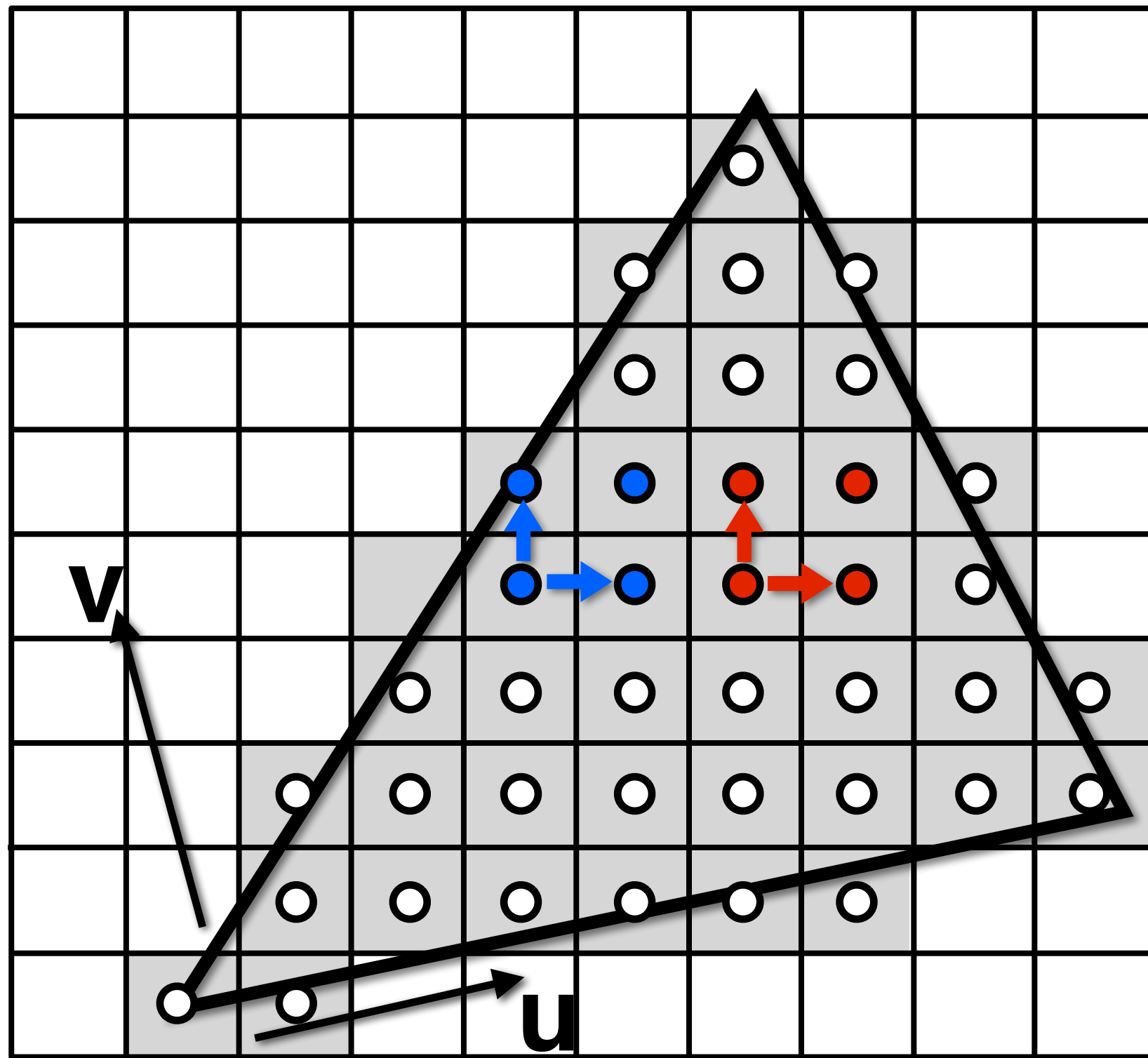
Williams' original
proposed mipmap layout



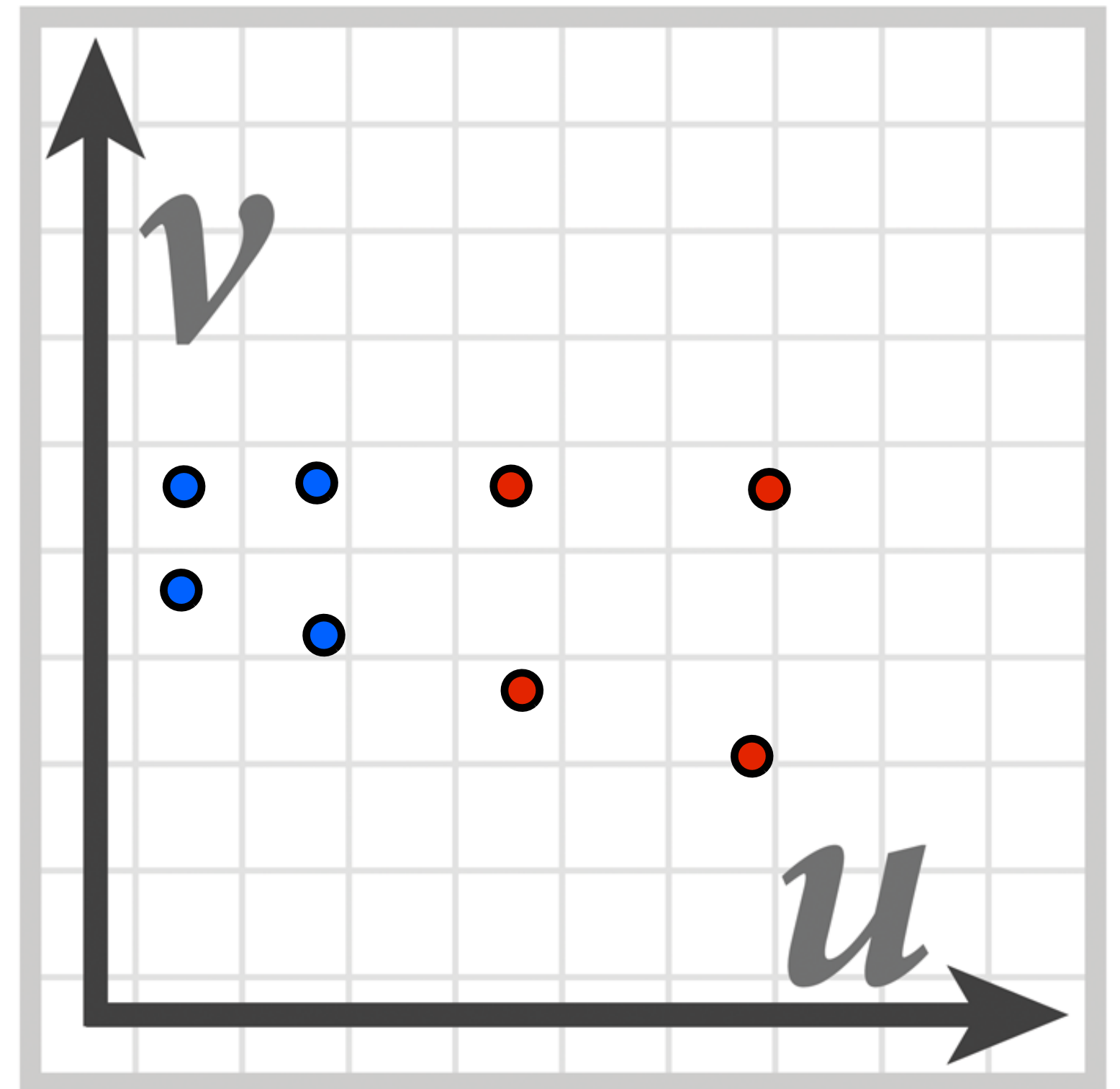
"Mip hierarchy"
level = D

What is the storage overhead of a mipmap?

Computing Mipmap Level D

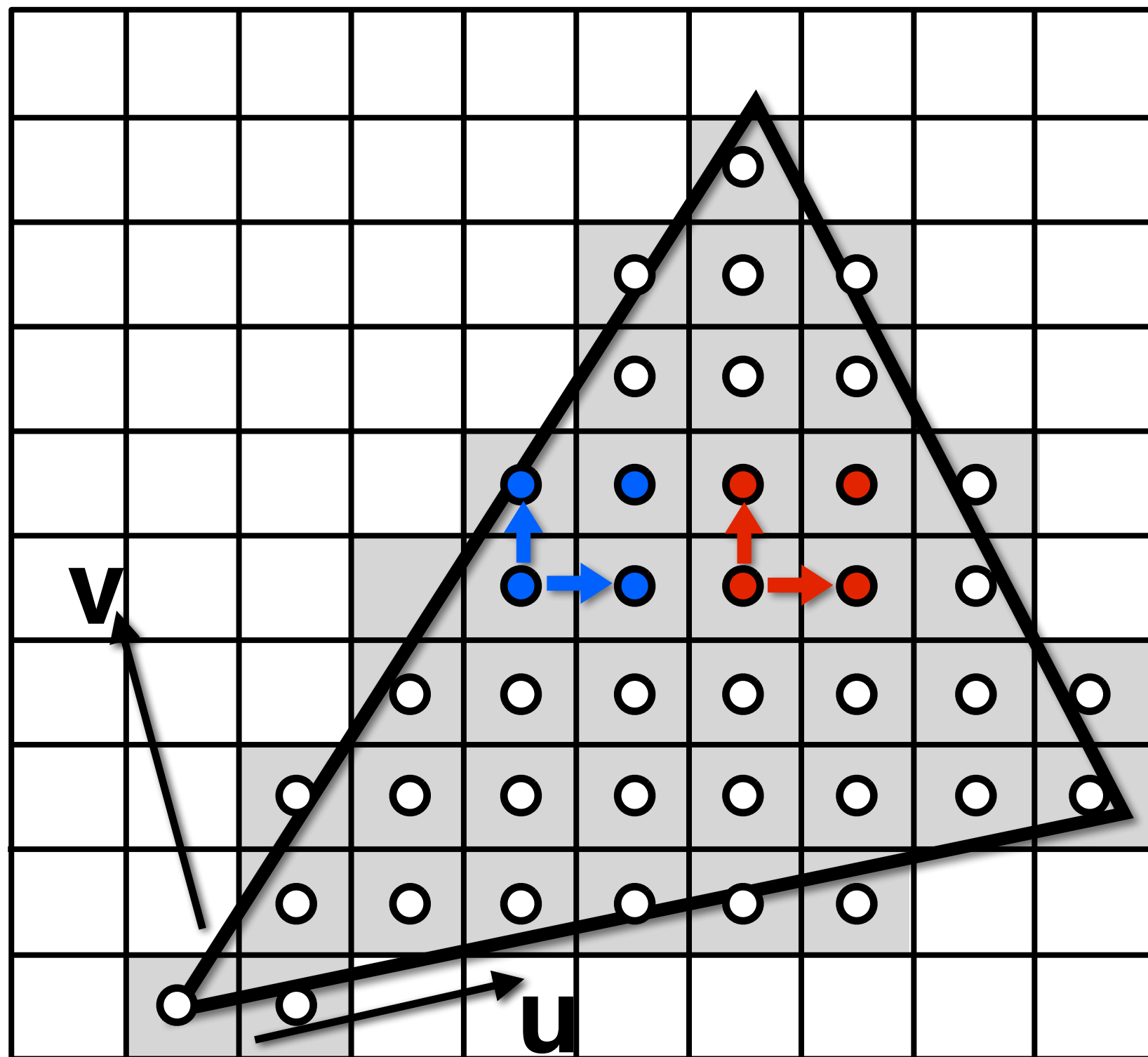


Screen space (x,y)

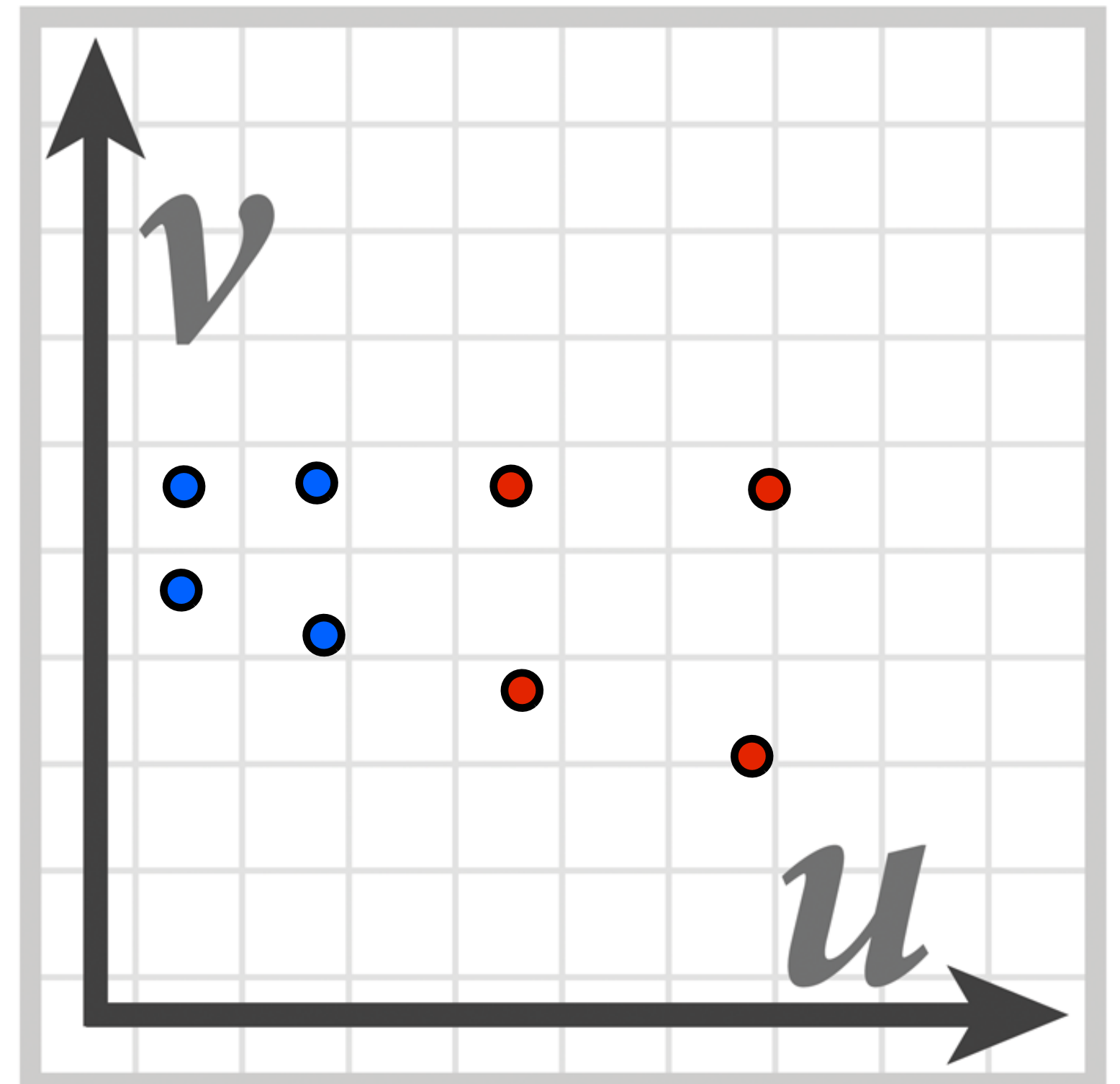


Texture space (u,v)

Computing Mipmap Level D



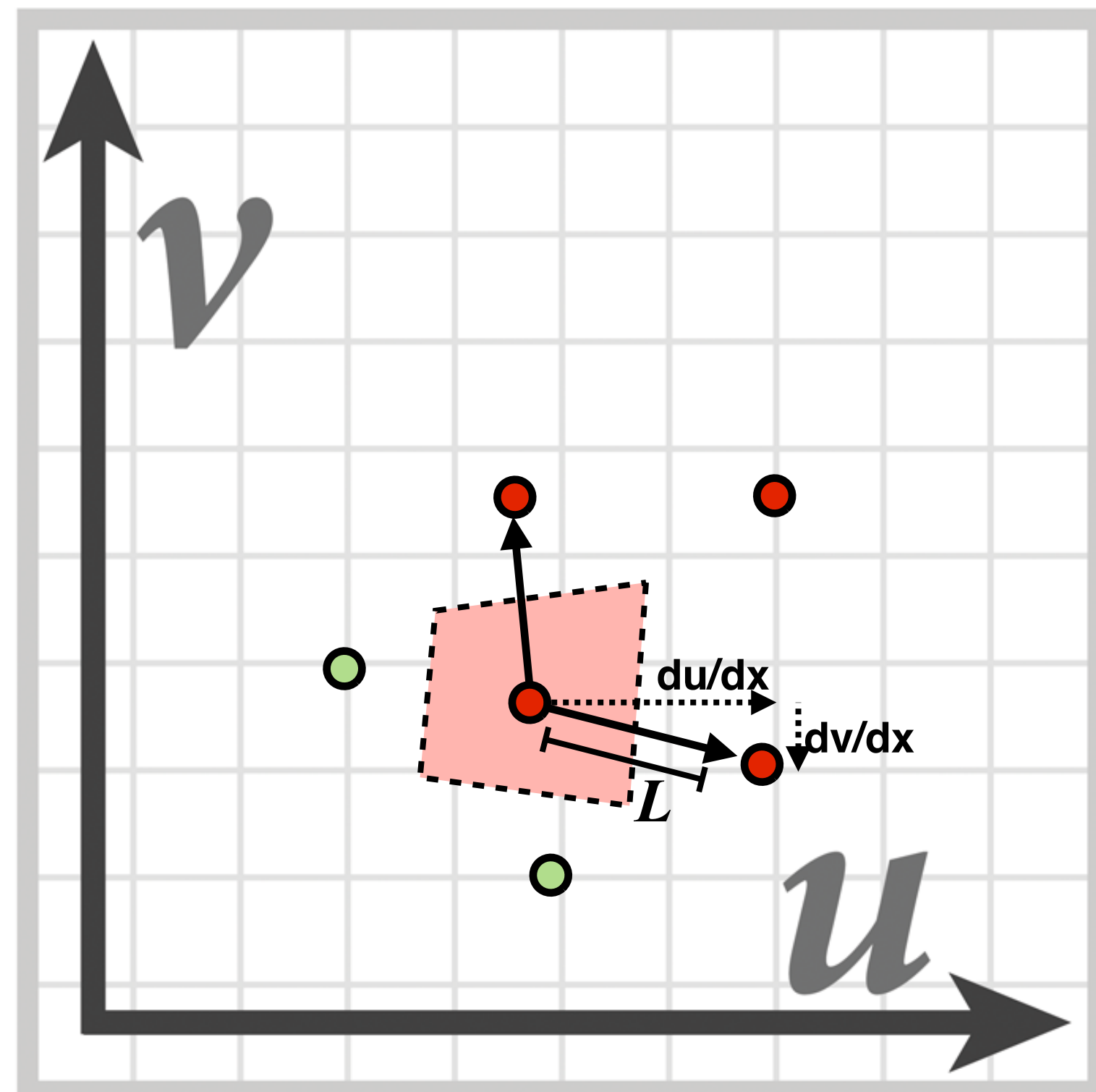
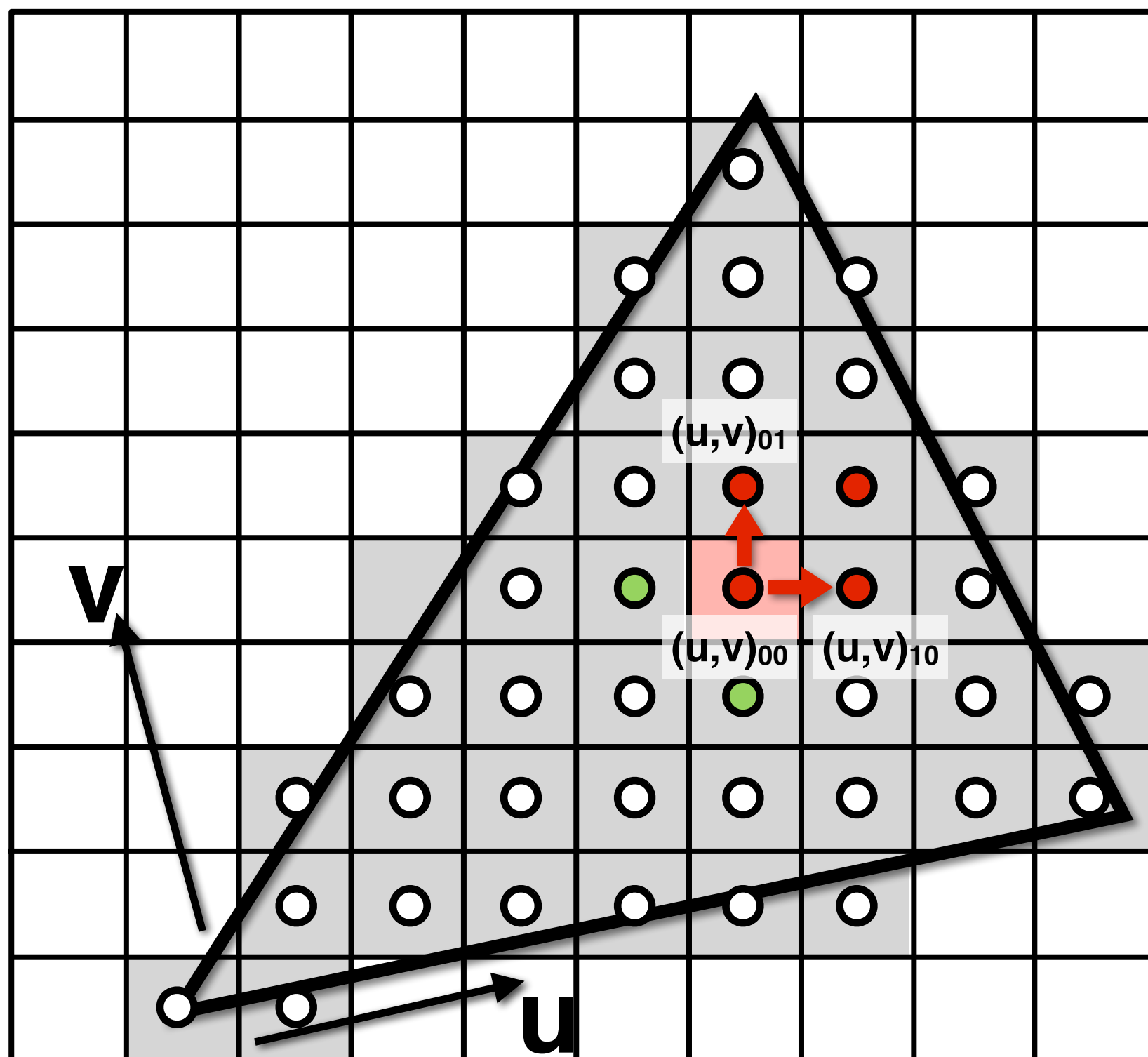
Screen space (x,y)



Texture space (u,v)

Estimate texture footprint using texture coordinates of neighboring screen samples

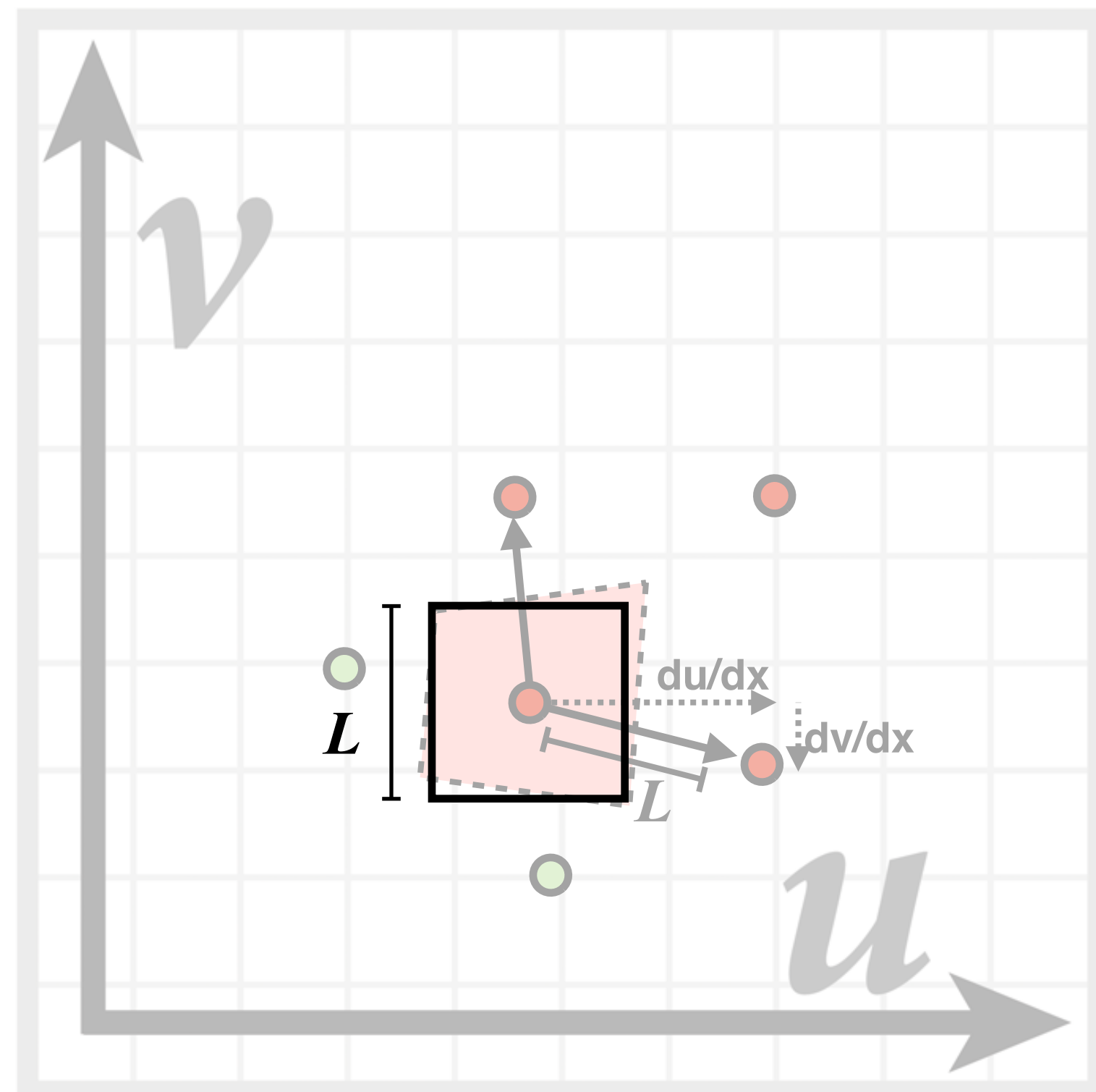
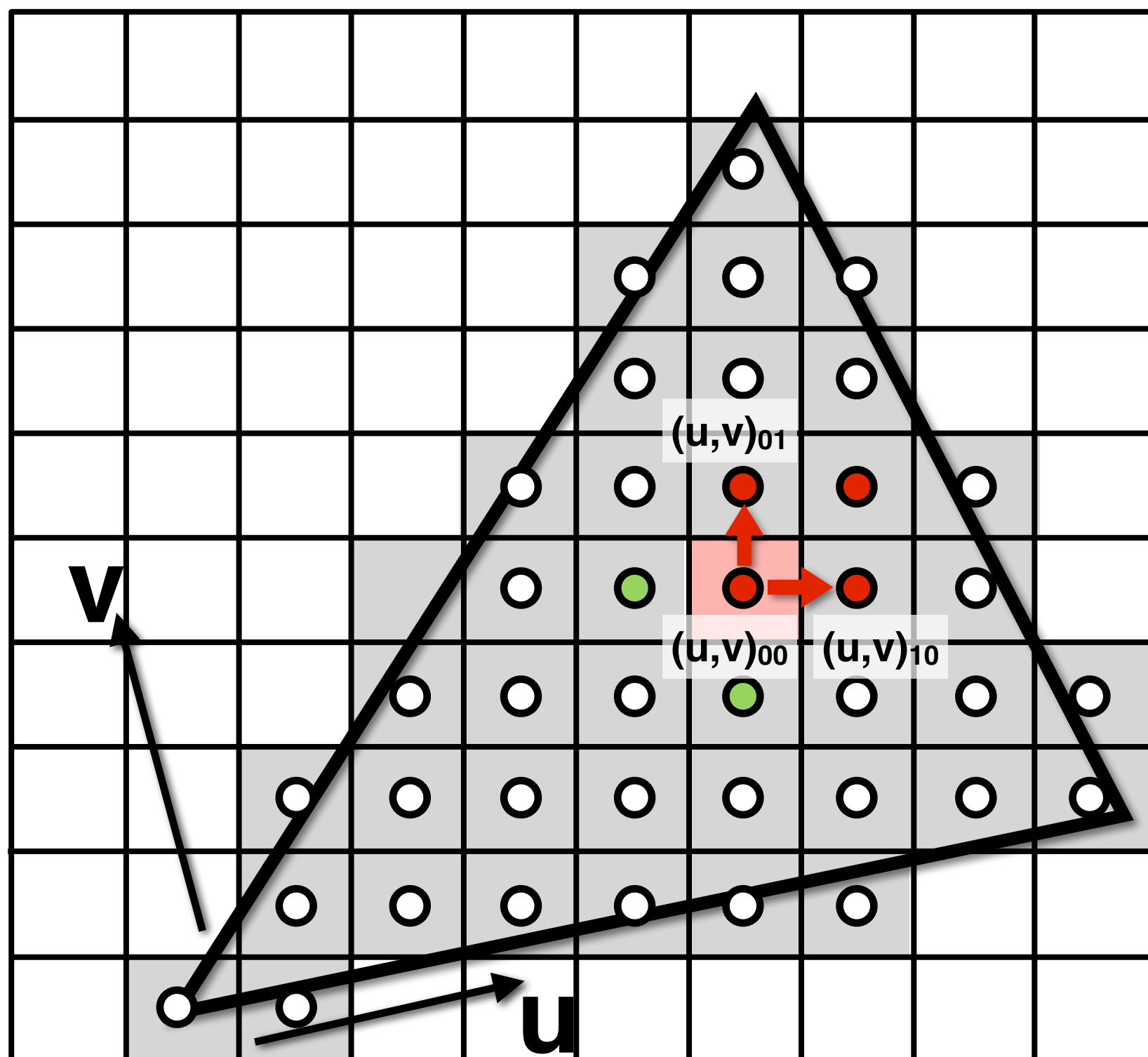
Computing Mipmap Level D



$$D = \log_2 L$$

$$L = \max \left(\sqrt{\left(\frac{du}{dx} \right)^2 + \left(\frac{dv}{dx} \right)^2}, \sqrt{\left(\frac{du}{dy} \right)^2 + \left(\frac{dv}{dy} \right)^2} \right)$$

Computing Mipmap Level D

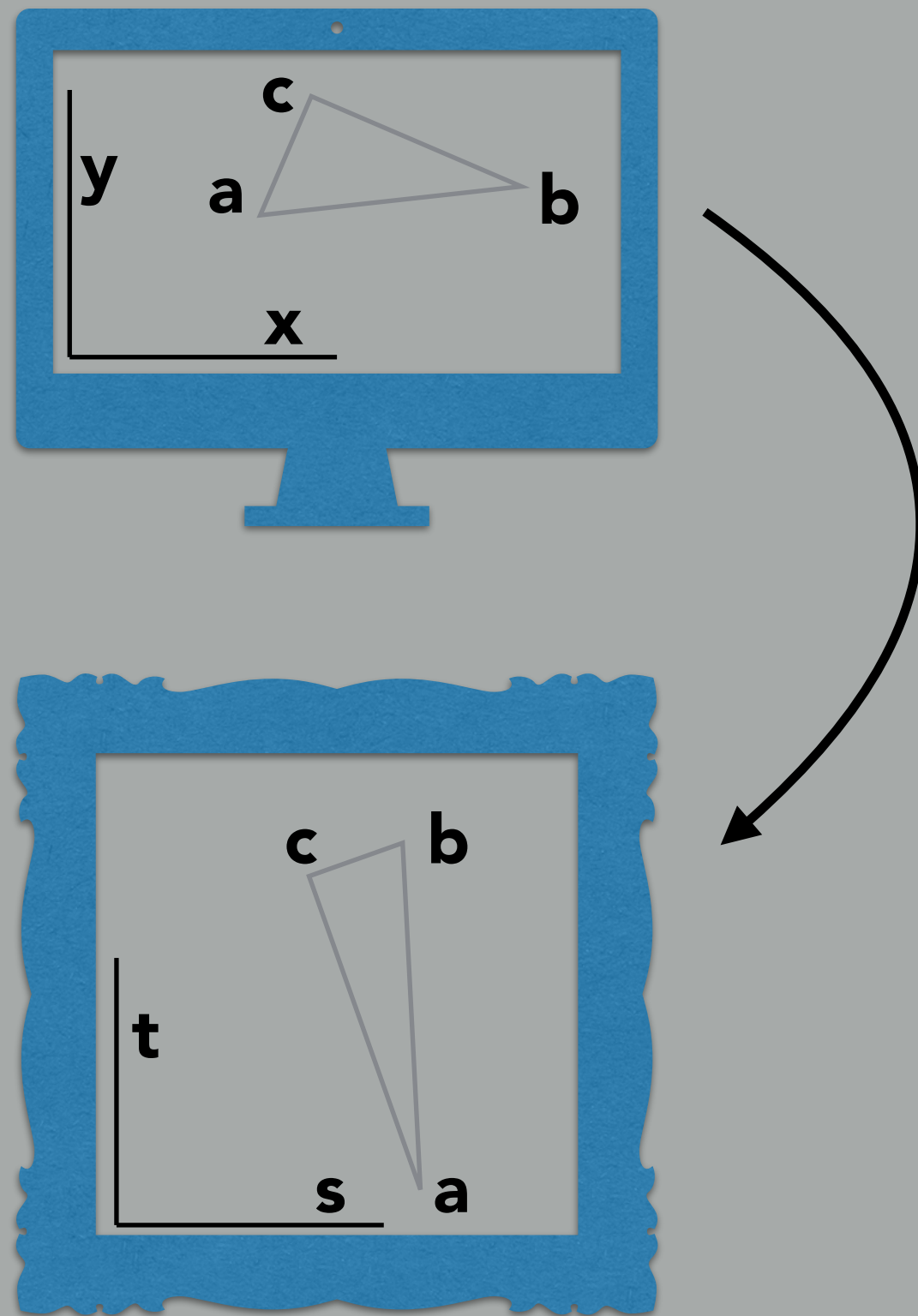


$$D = \log_2 L$$

$$L = \max \left(\sqrt{\left(\frac{du}{dx}\right)^2 + \left(\frac{dv}{dx}\right)^2}, \sqrt{\left(\frac{du}{dy}\right)^2 + \left(\frac{dv}{dy}\right)^2} \right)$$

Mipmap Level, Direct Derivative

Linear Algebra View



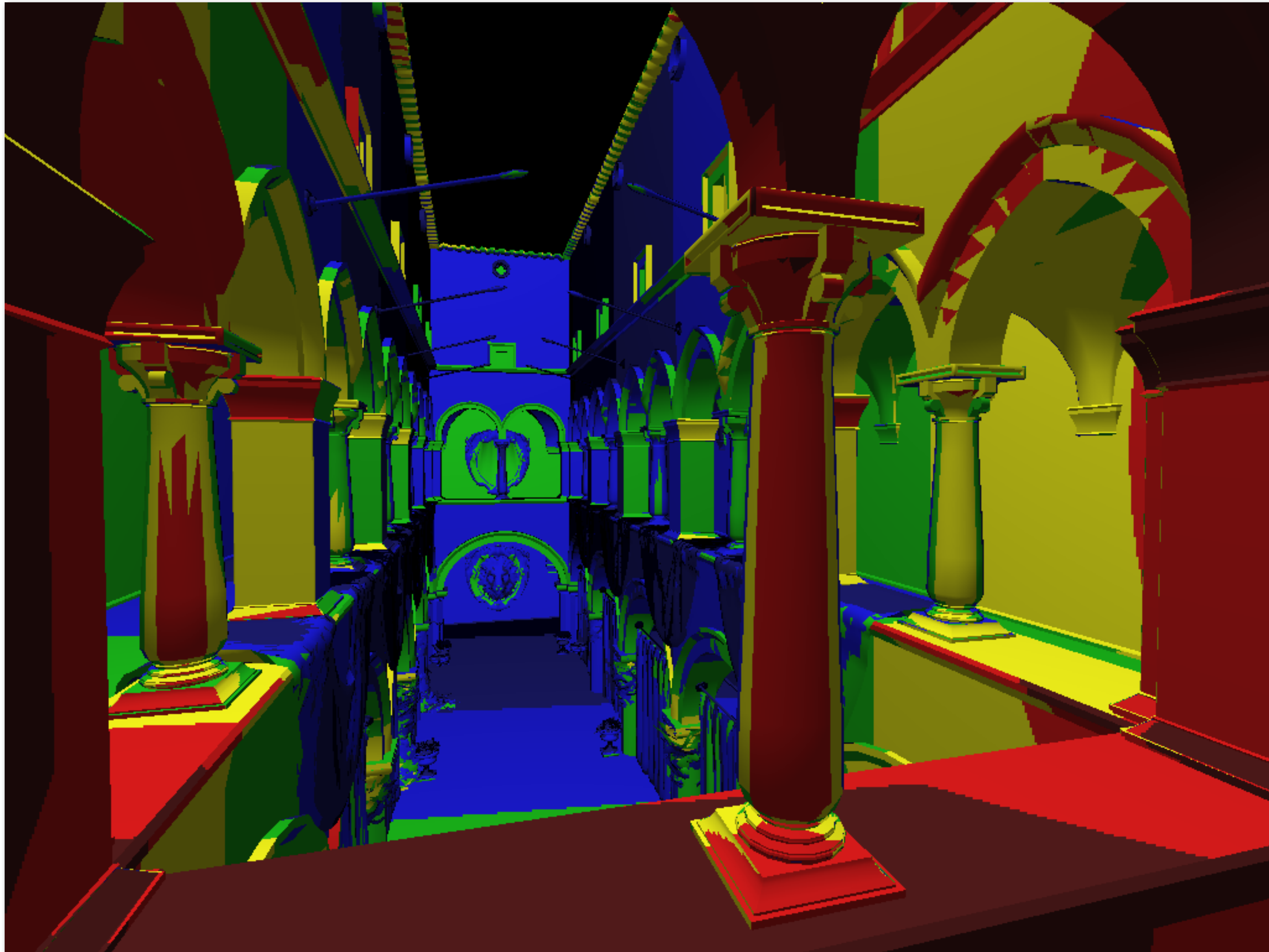
$$\begin{bmatrix} s \\ t \\ 1 \end{bmatrix} = M_{\text{texture}} M_{\text{screen}}^{-1} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

This function is linear so $\frac{\partial s}{\partial x}$ would be const if no depth distortion.

$$a_1 = h_2 h_3 b_1 / (h_2 h_3 b_1 + h_1 h_3 b_2 + h_1 h_2 b_3)$$

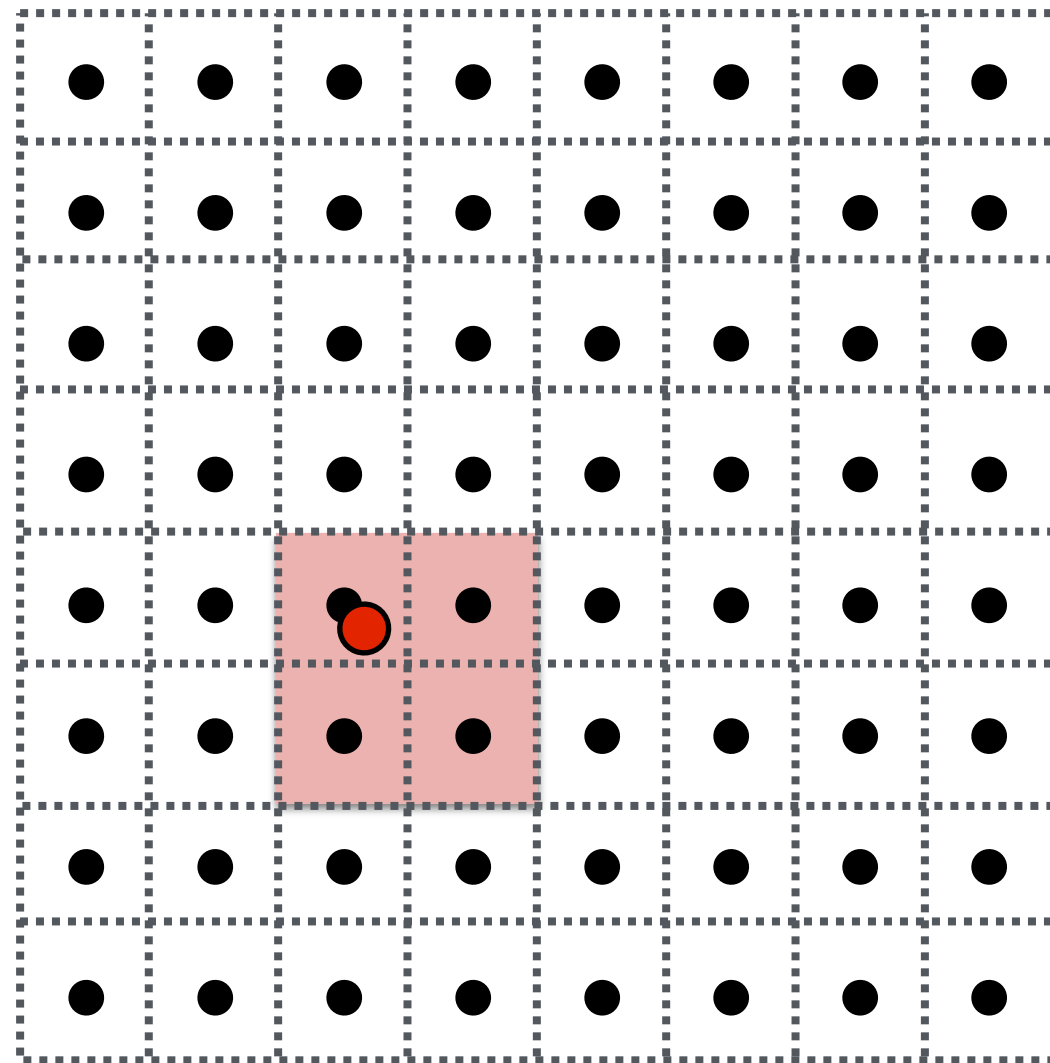
Accounting for depth distortion creates non-constant derivatives. It adds a nonlinear operation between matrices.

Visualization of Mipmap Level

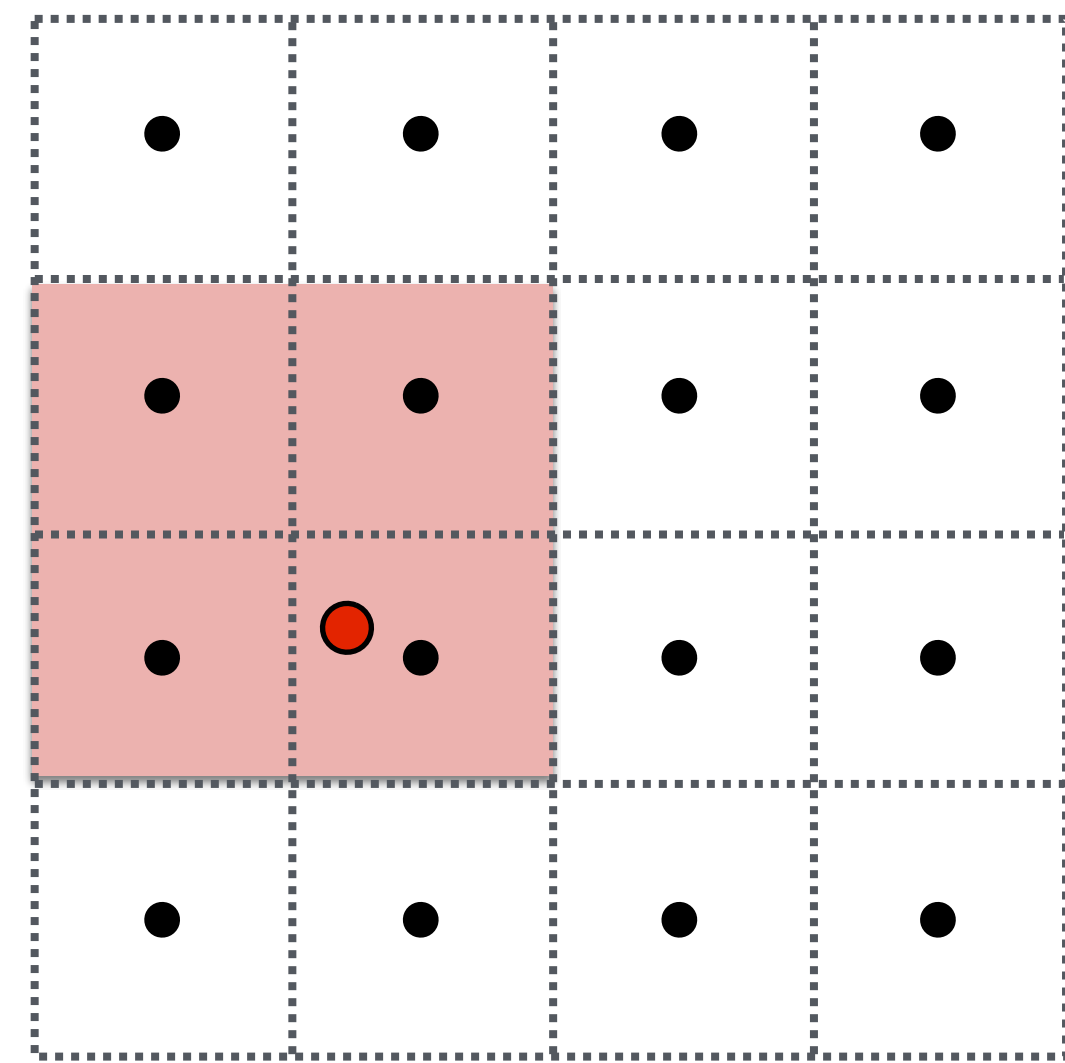


D rounded to nearest integer level

Trilinear Filtering

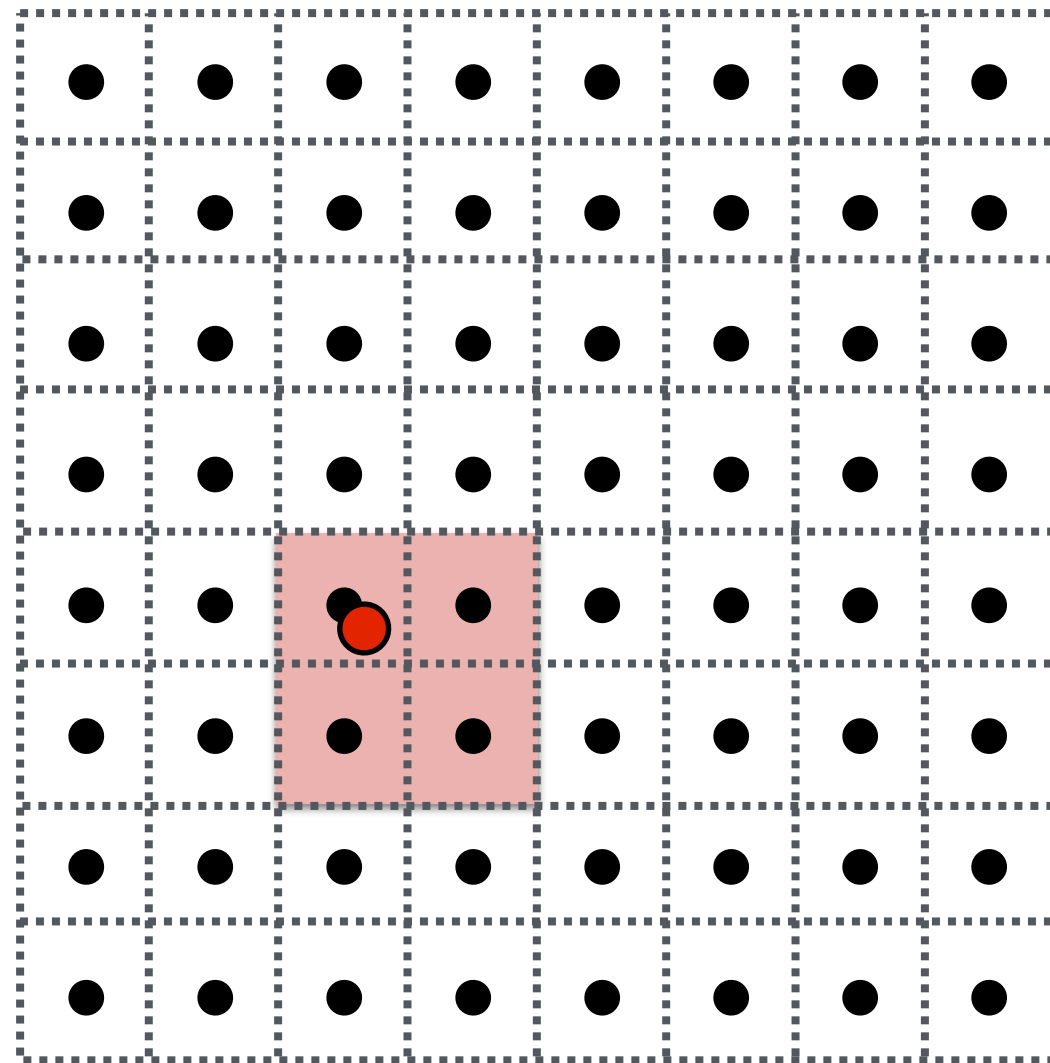


Mipmap Level D

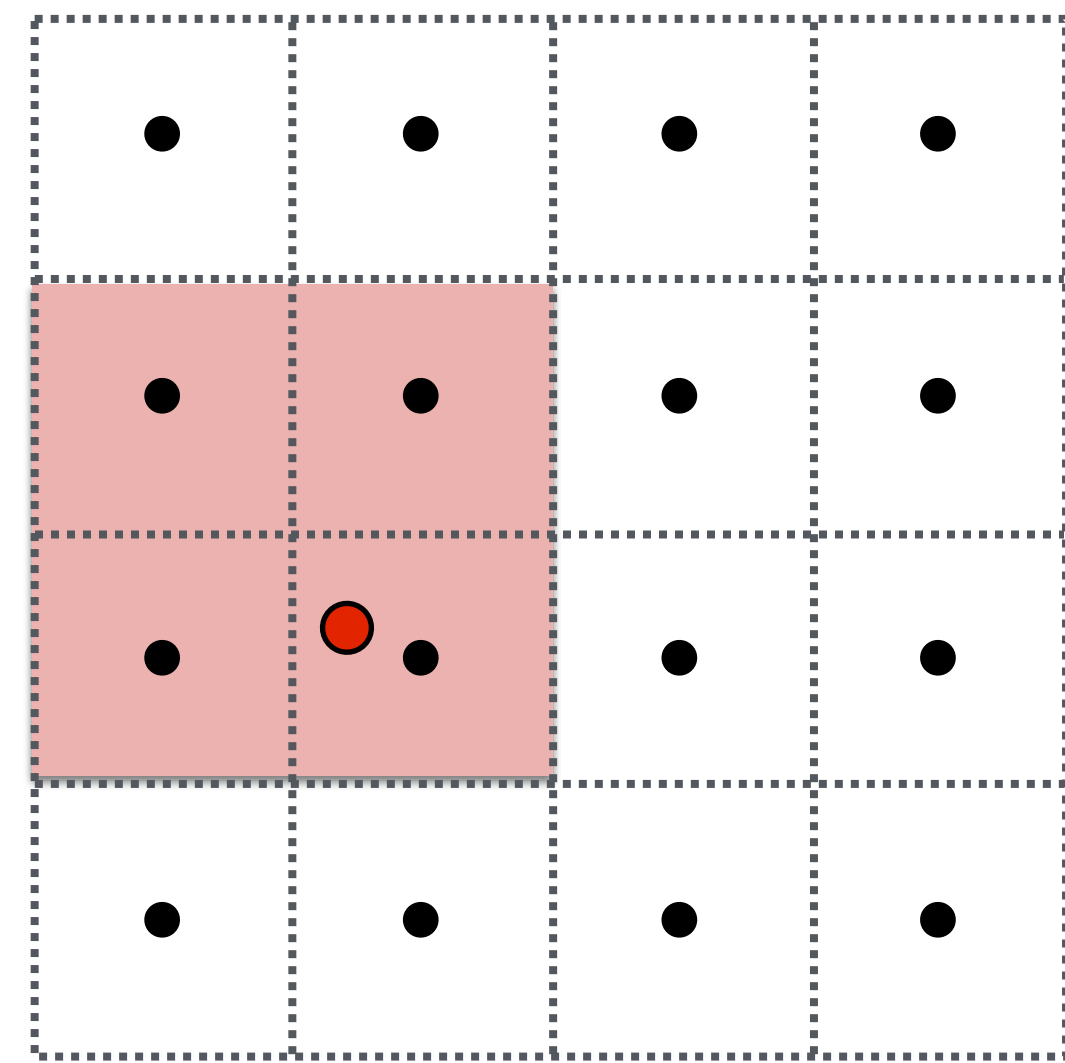


Mipmap Level D+1

Trilinear Filtering



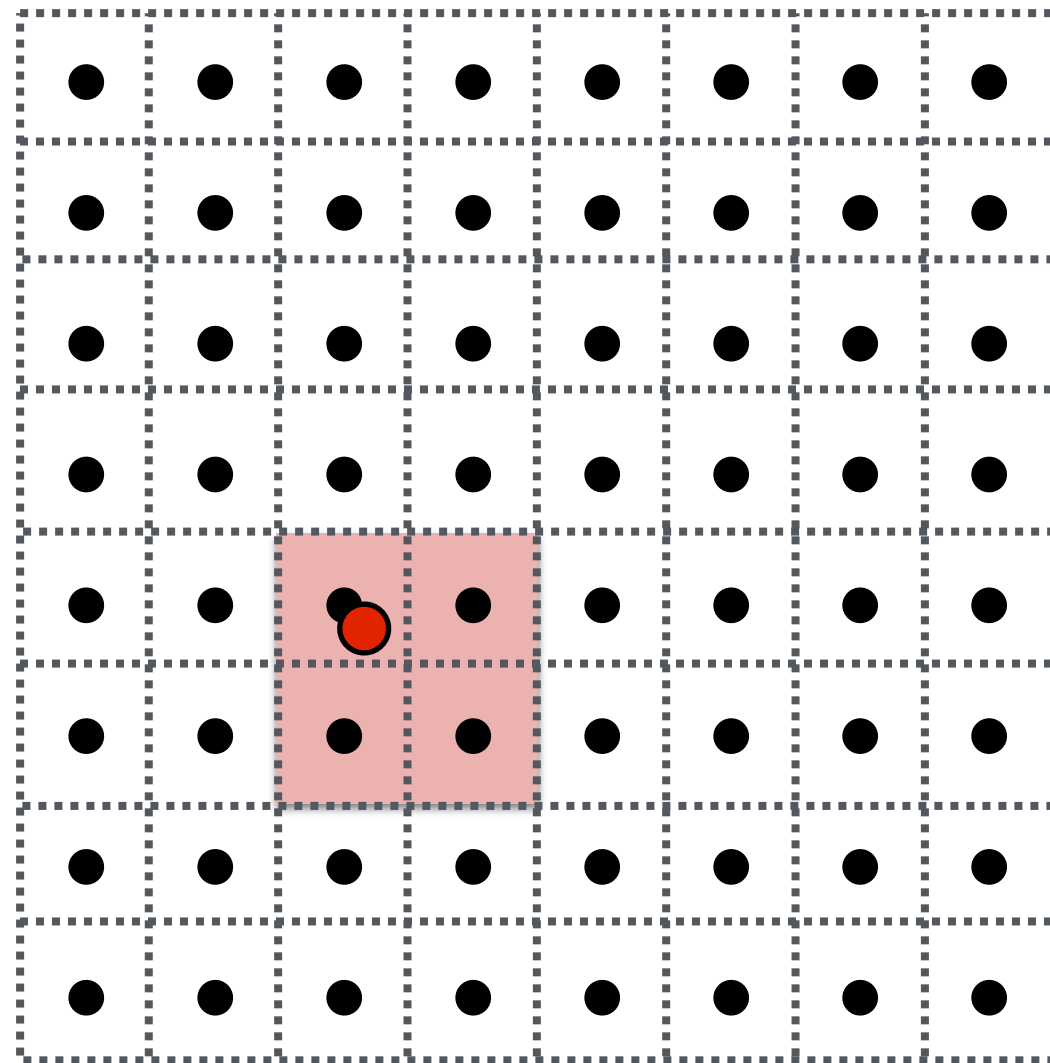
Mipmap Level D



Mipmap Level D+1

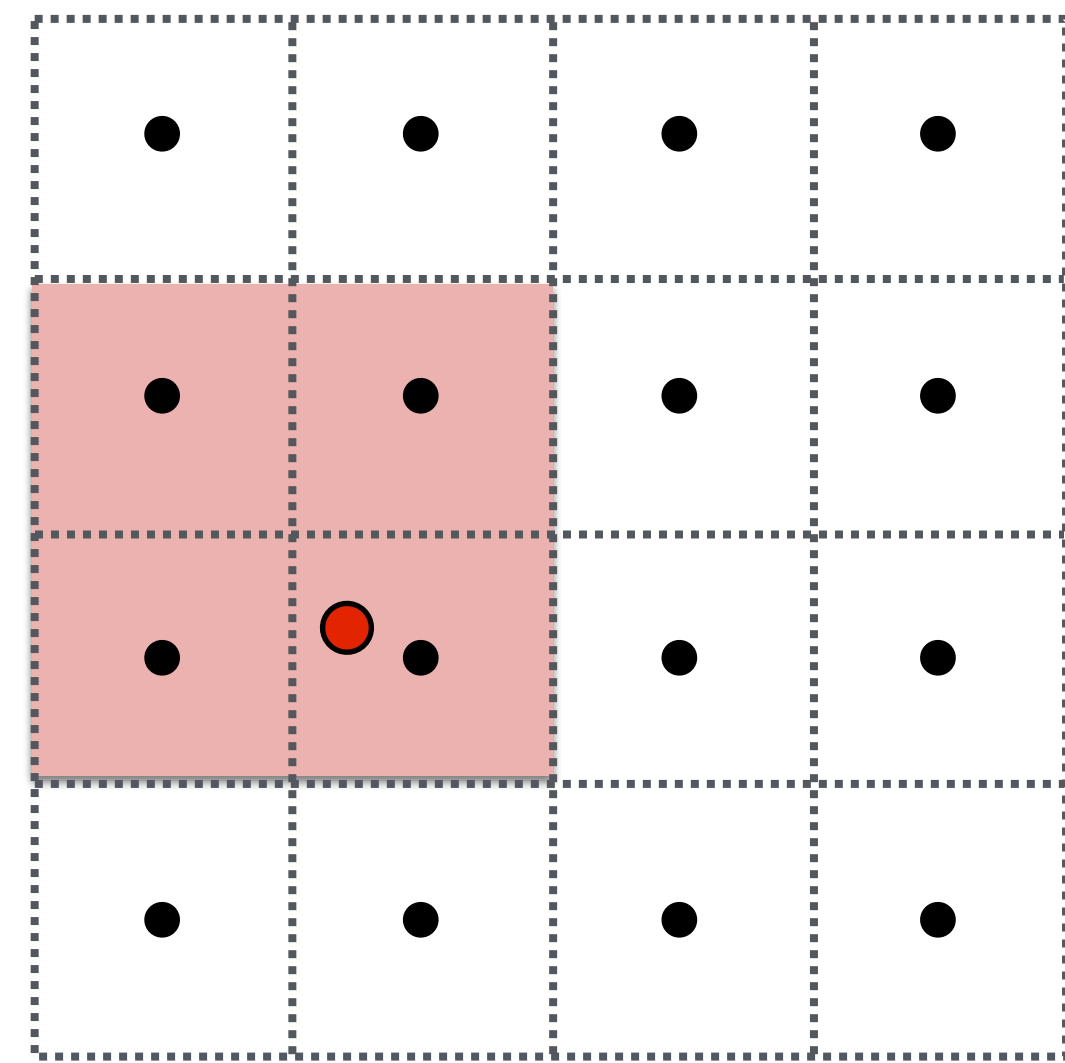
Bilinear result

Trilinear Filtering



Mipmap Level D

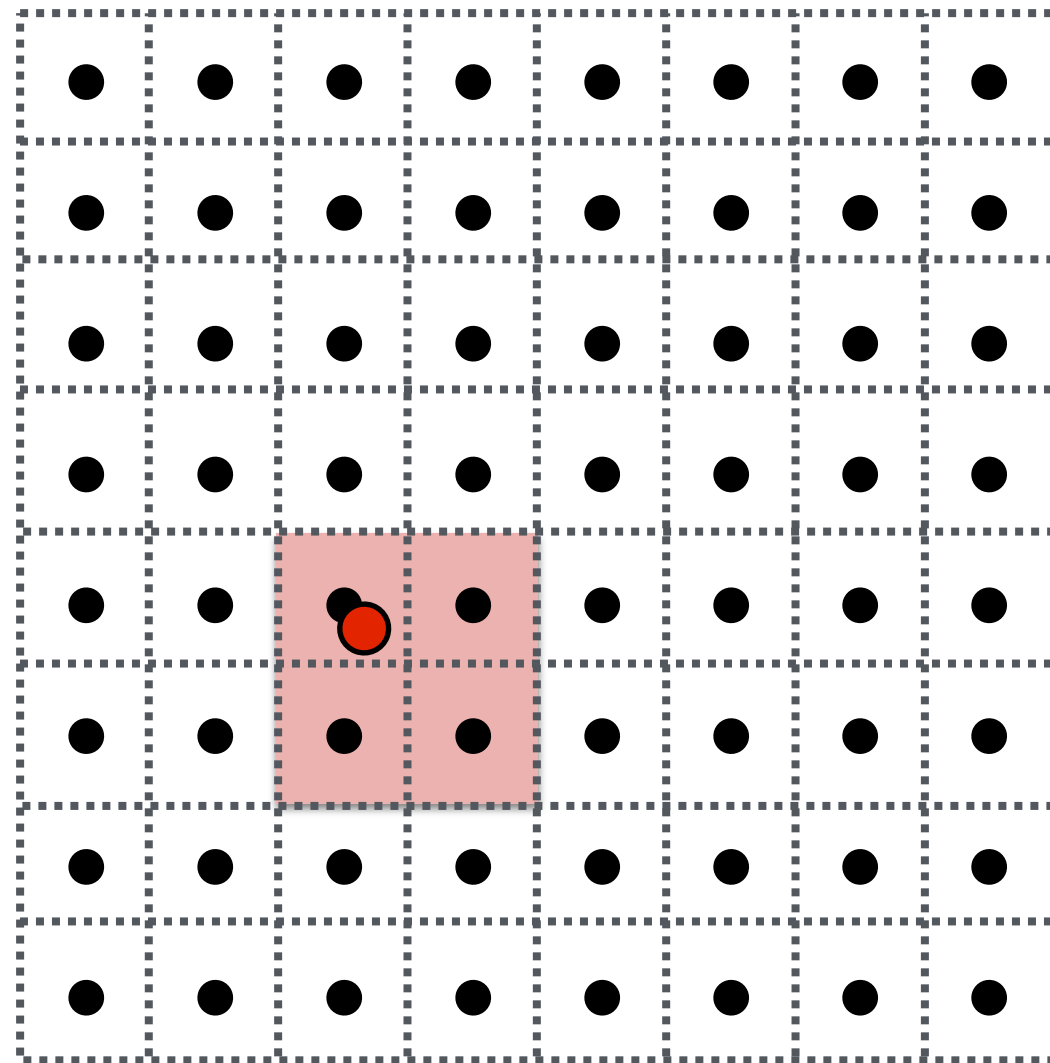
Bilinear result



Mipmap Level D+1

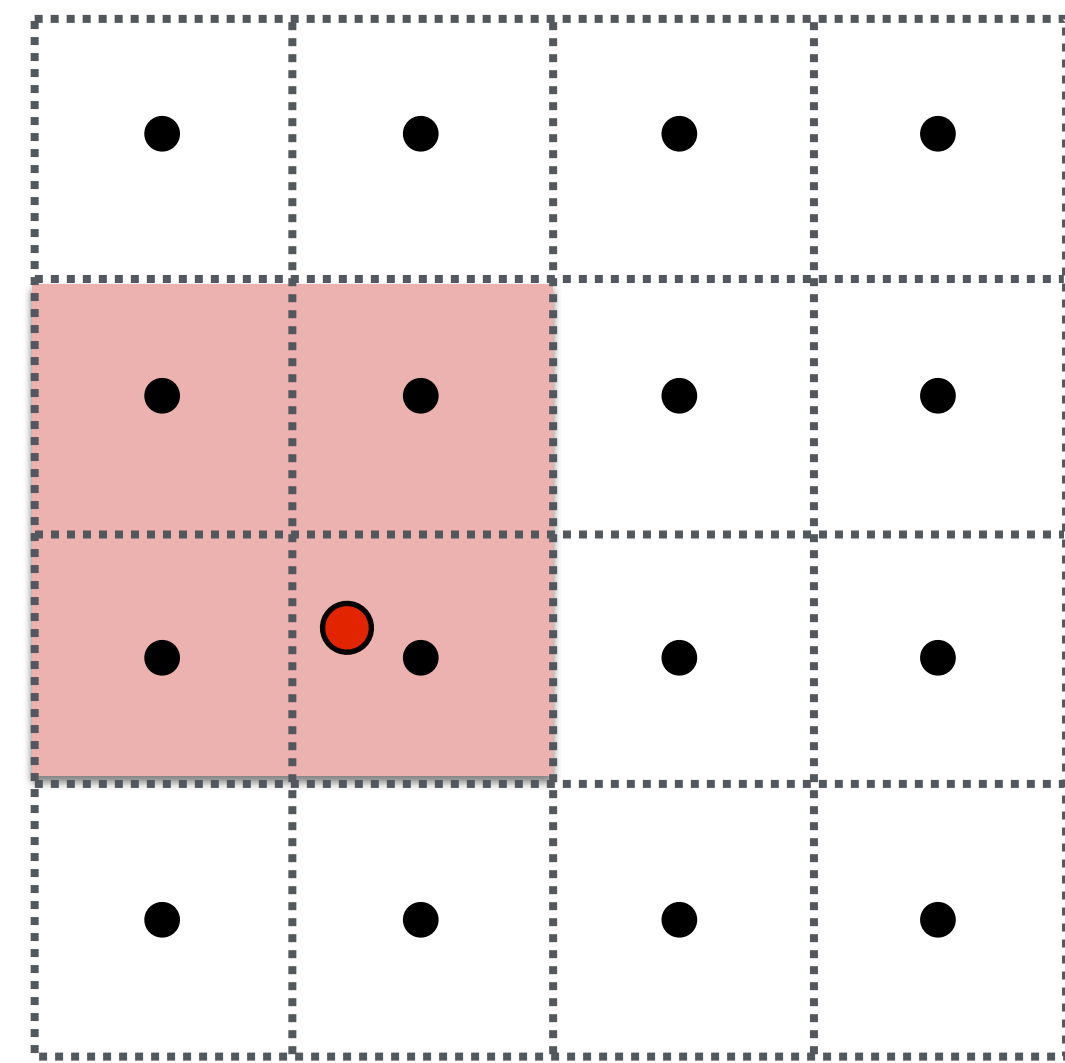
Bilinear result

Trilinear Filtering



Mipmap Level D

Bilinear result

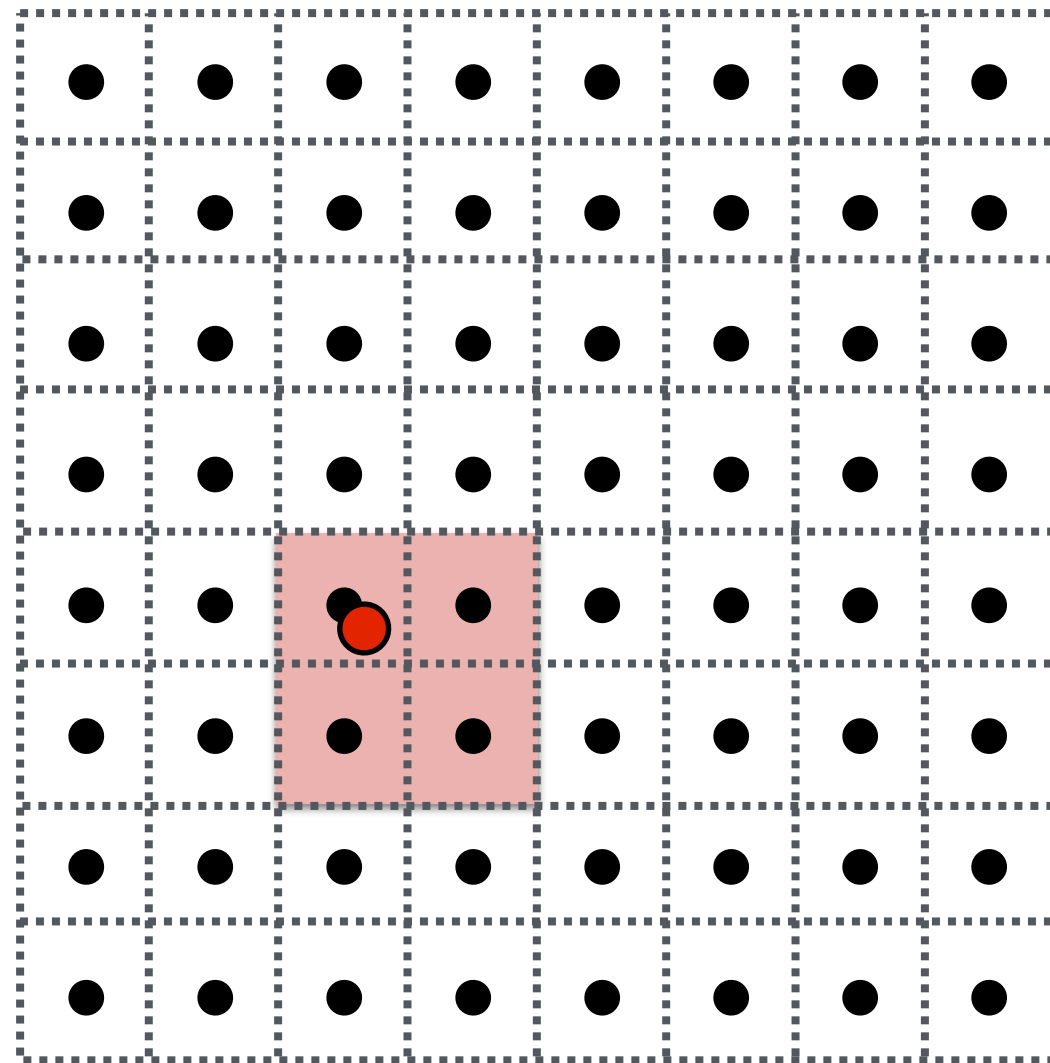


Mipmap Level D+1

Bilinear result

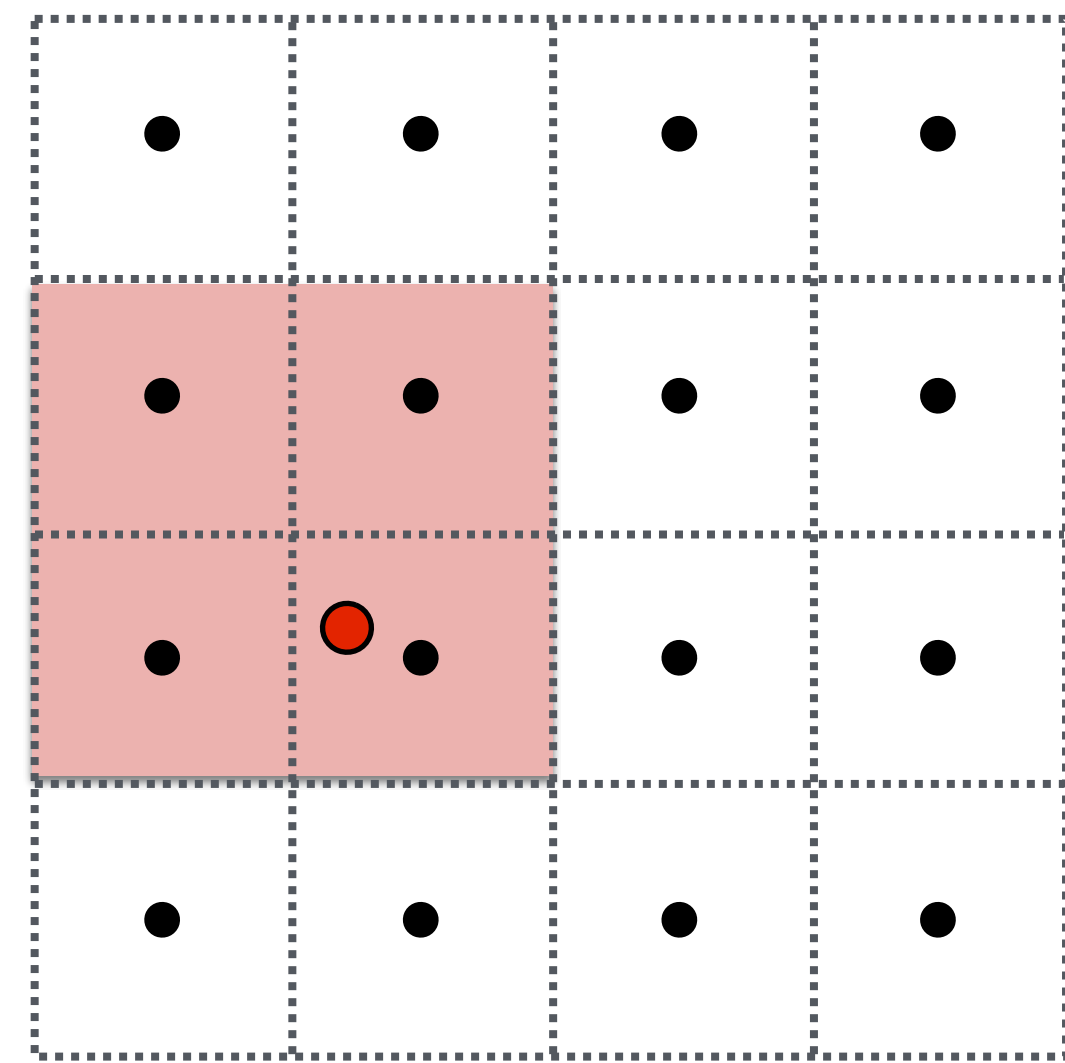


Trilinear Filtering



Mipmap Level D

Bilinear result

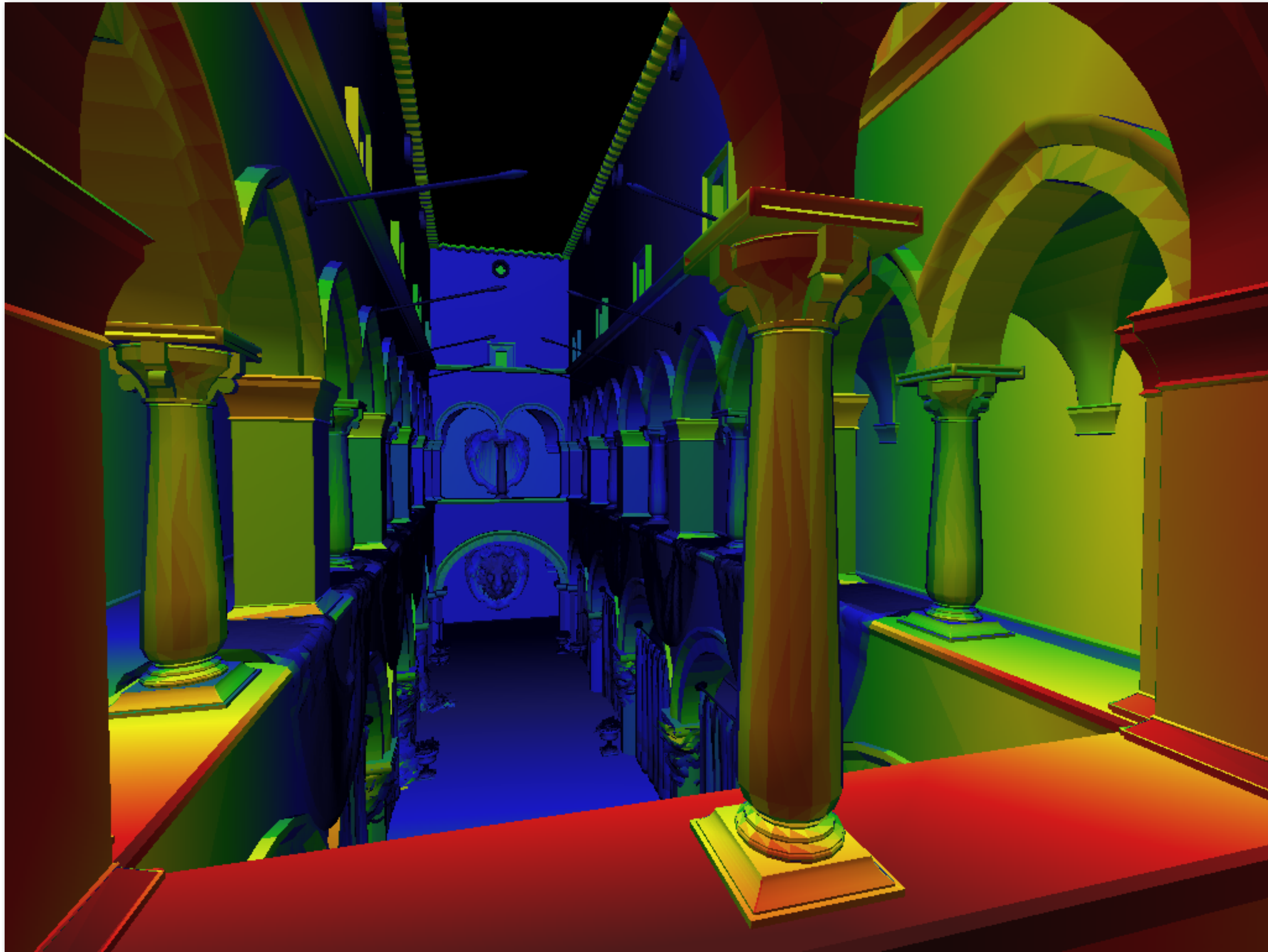


Mipmap Level D+1

Bilinear result

Linear interpolation based on continuous D value

Visualization of Mipmap Level



Trilinear filtering: visualization of continuous D

Bilinear vs Trilinear Filtering Cost

Bilinear resampling:

- 4 texel reads
- 3 lerps (3 mul + 6 add)

Trilinear resampling:

- 8 texel reads
- 7 lerps (7 mul + 14 add)

Texture Filtering in Assignment

Image resampling choices

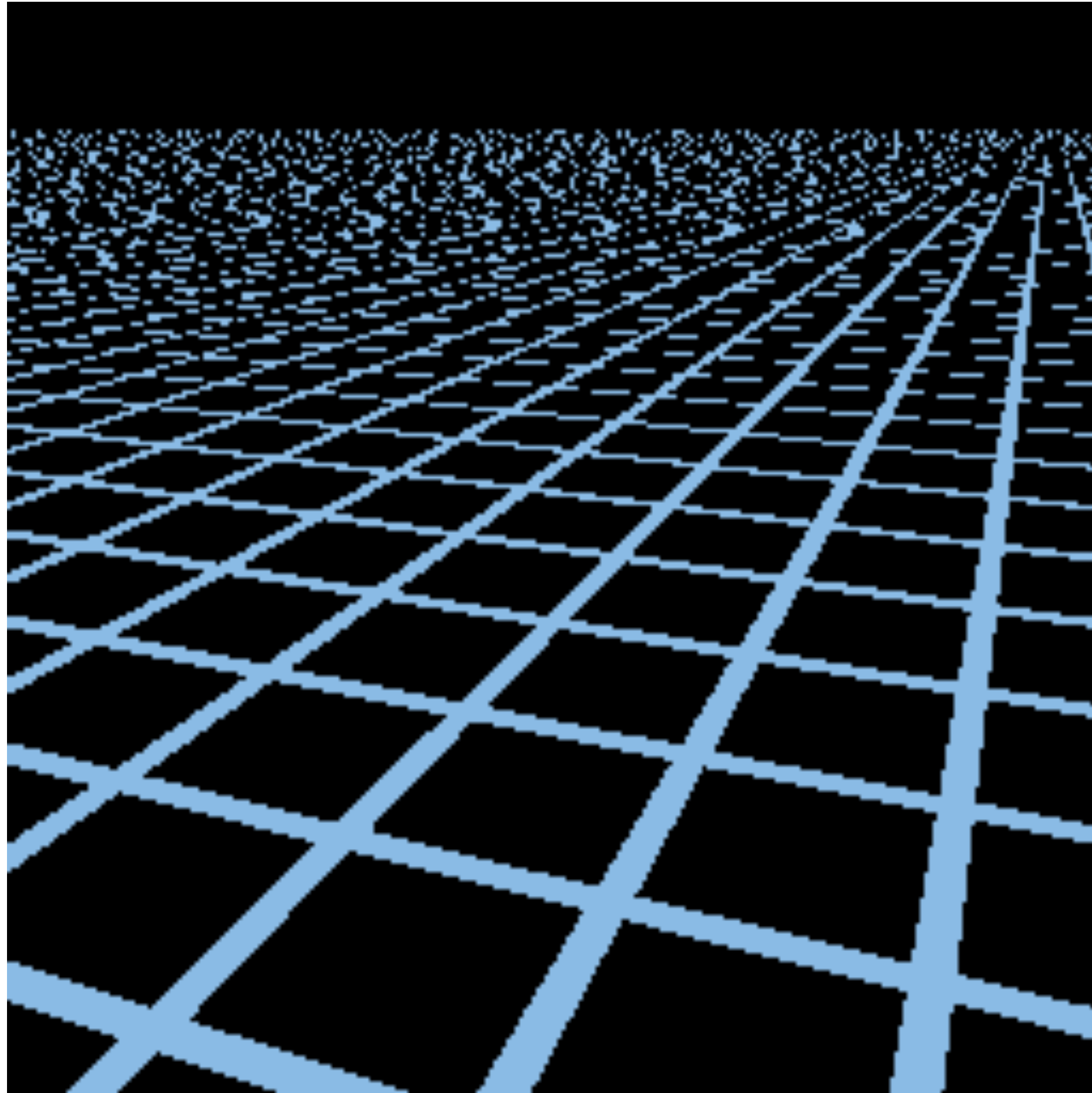
- Nearest
- Bilinear interpolation

Mipmap level resampling choices

- Always level 0
- Nearest D
- Linear interpolation

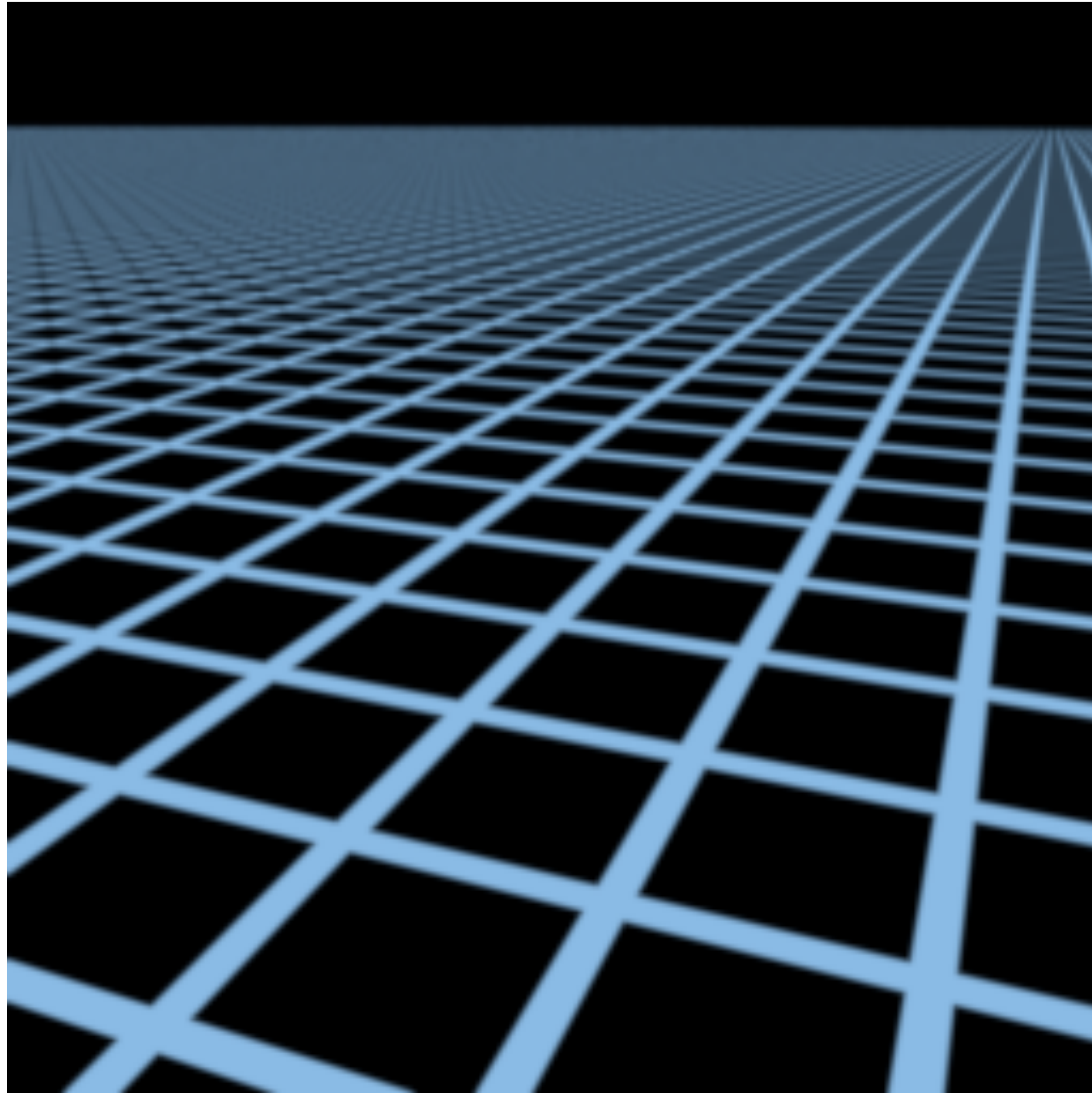
$2 \times 3 = 6$ choices

Mipmap Limitations



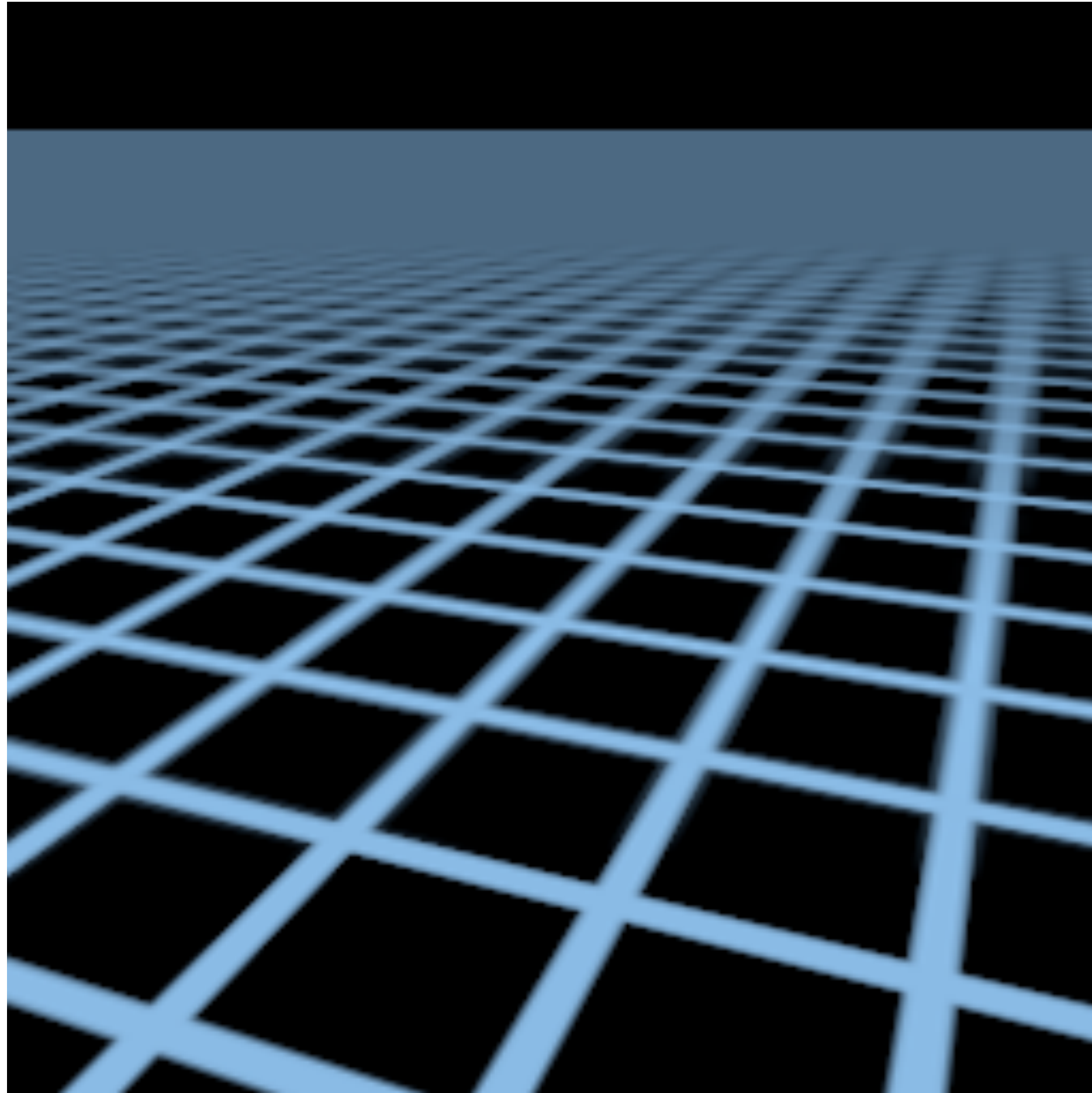
Point sampling

Mipmap Limitations



Supersampling 512x

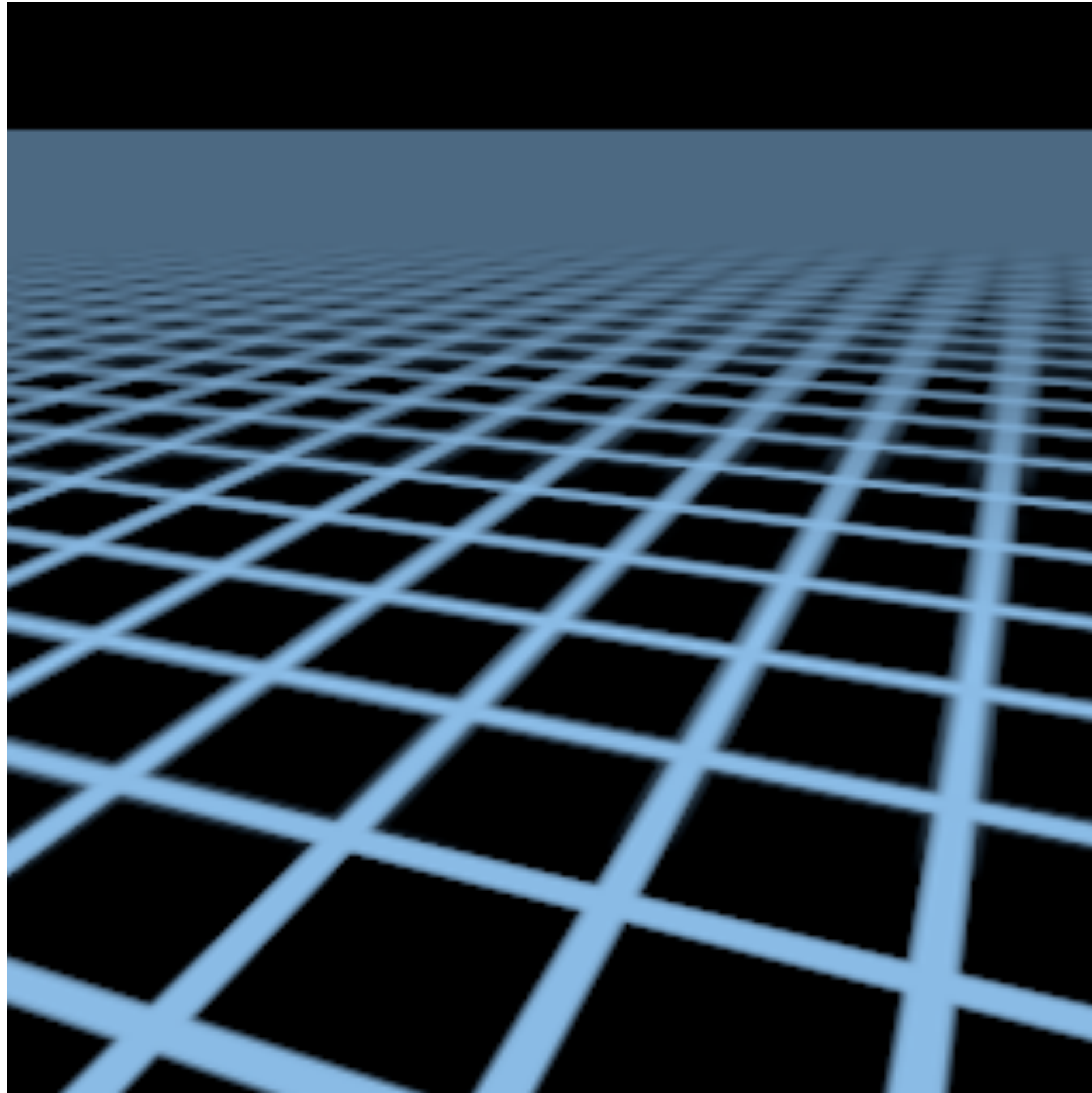
Mipmap Limitations



Mipmap trilinear sampling

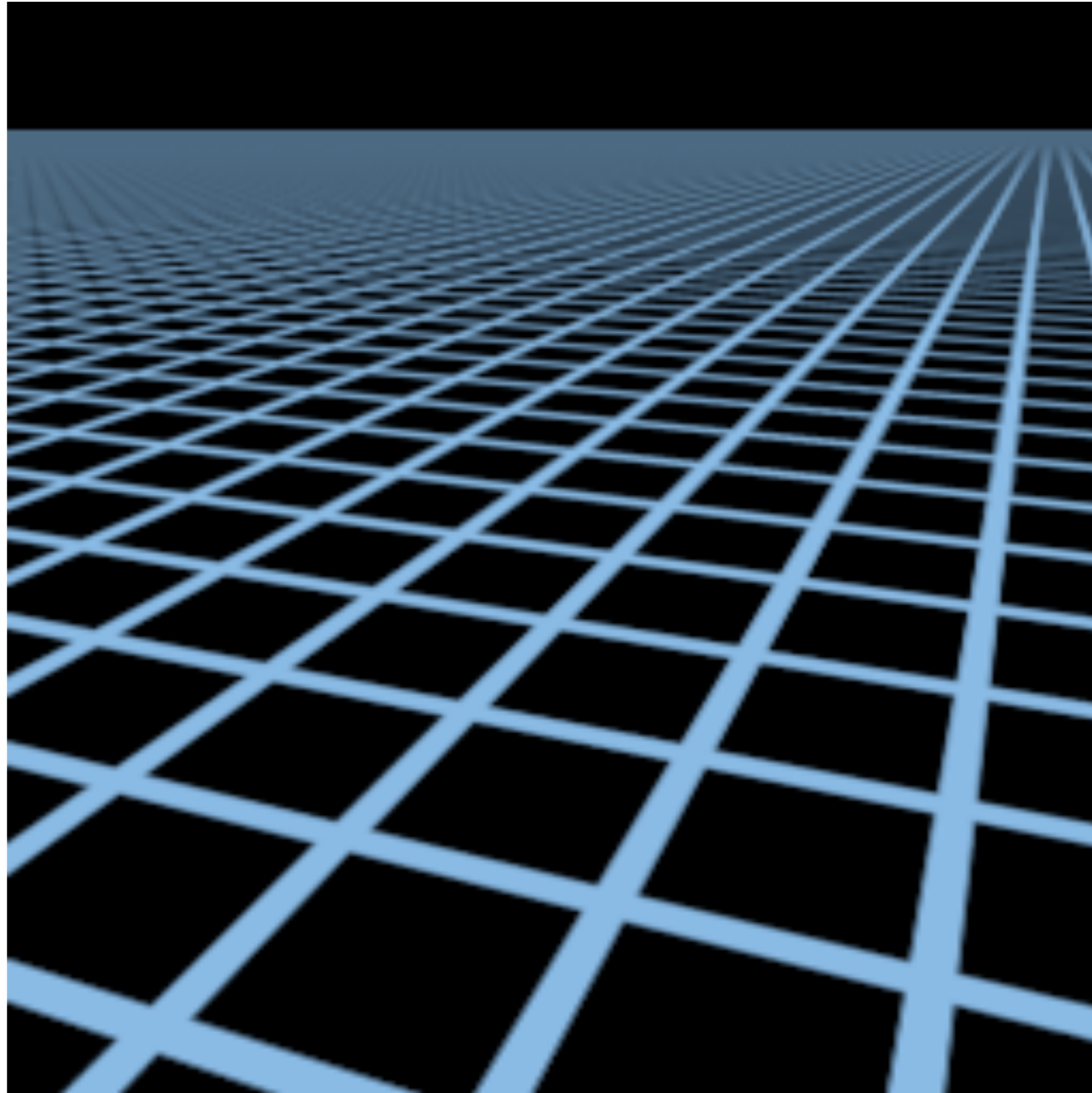
Mipmap Limitations

Overblur
Why?



Mipmap trilinear sampling

Anisotropic Filtering



Elliptical weighted average (EWA) filtering

Anisotropic Filtering

Ripmaps and summed area tables

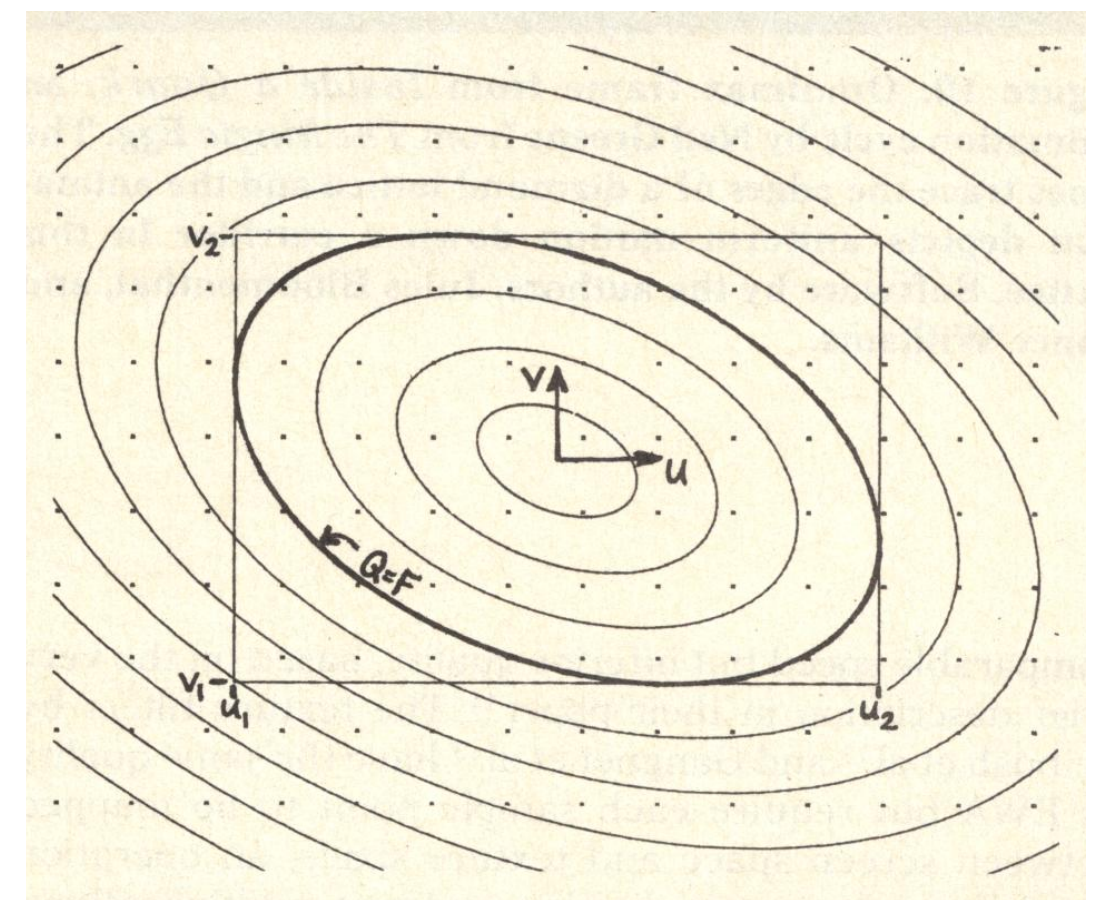
- Can look up axis-aligned rectangular zones
- Diagonal footprints still a problem



Wikipedia

EWA filtering

- Use multiple lookups
- Weighted average
- Mipmap hierarchy still helps



Greene & Heckbert '86

Advanced Texturing Methods

Many, Many Uses for Texturing

In modern GPUs, texture = memory + filtering

- General method to bring data to fragment calculations

Many applications

- Environment lighting
- Store microgeometry
- Procedural textures
- Solid modeling
- Volume rendering
- ...

Environment Map

A function from the sphere to colors,
stored as a texture.



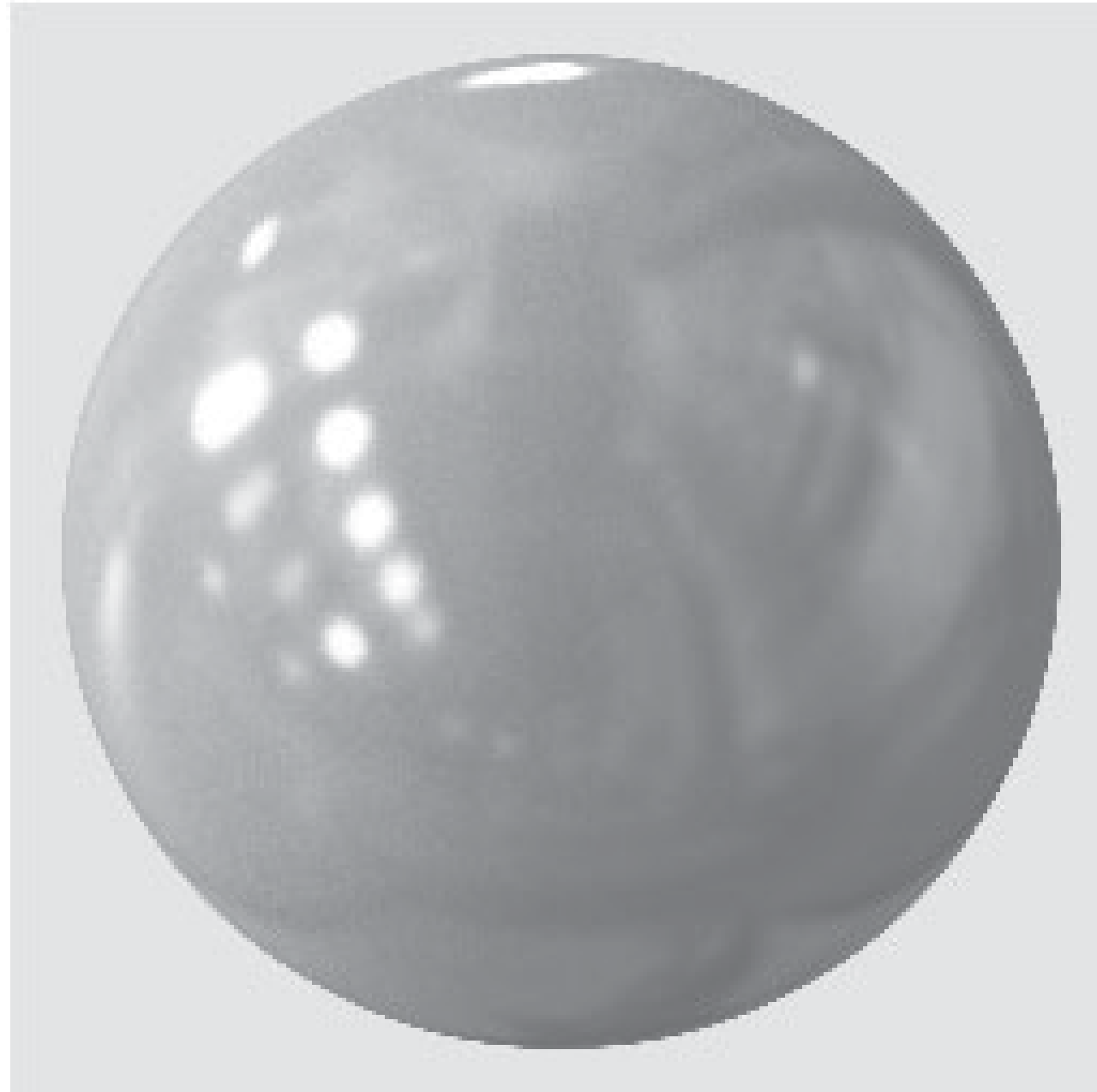
Lat / long texture map



Reflection vector indexes into texture map

[Blinn & Newell 1976]

Environment Map



With environment map



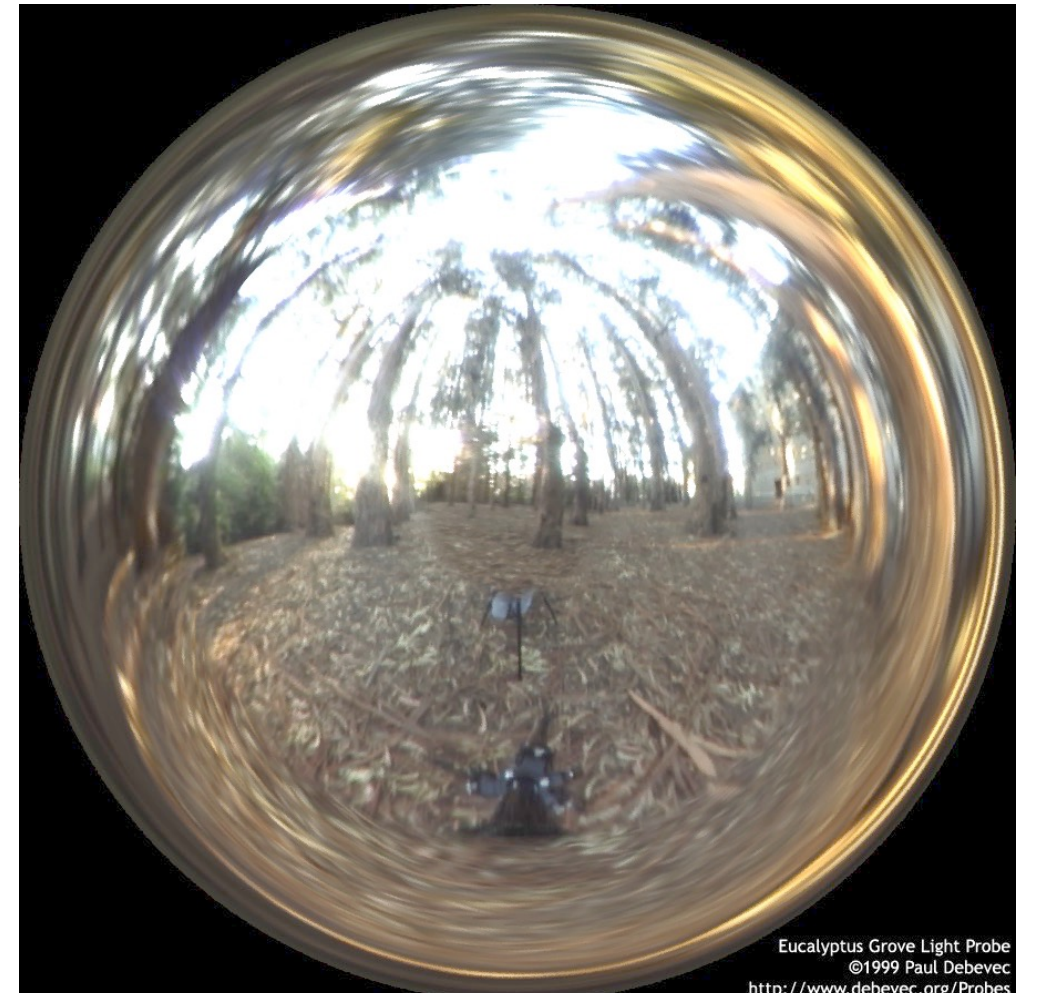
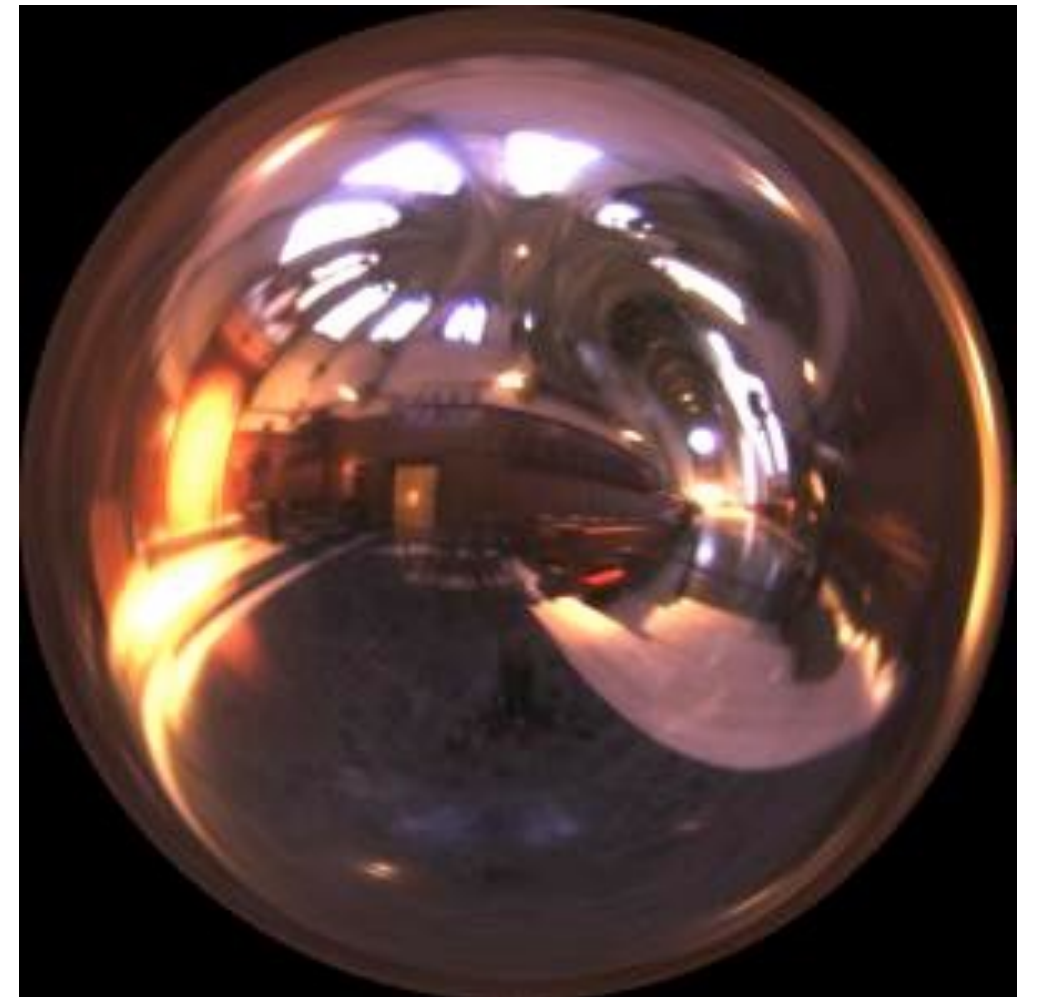
Without environment map

[Dror, Willsky, & Adelson 2004]

Spherical Environment Map



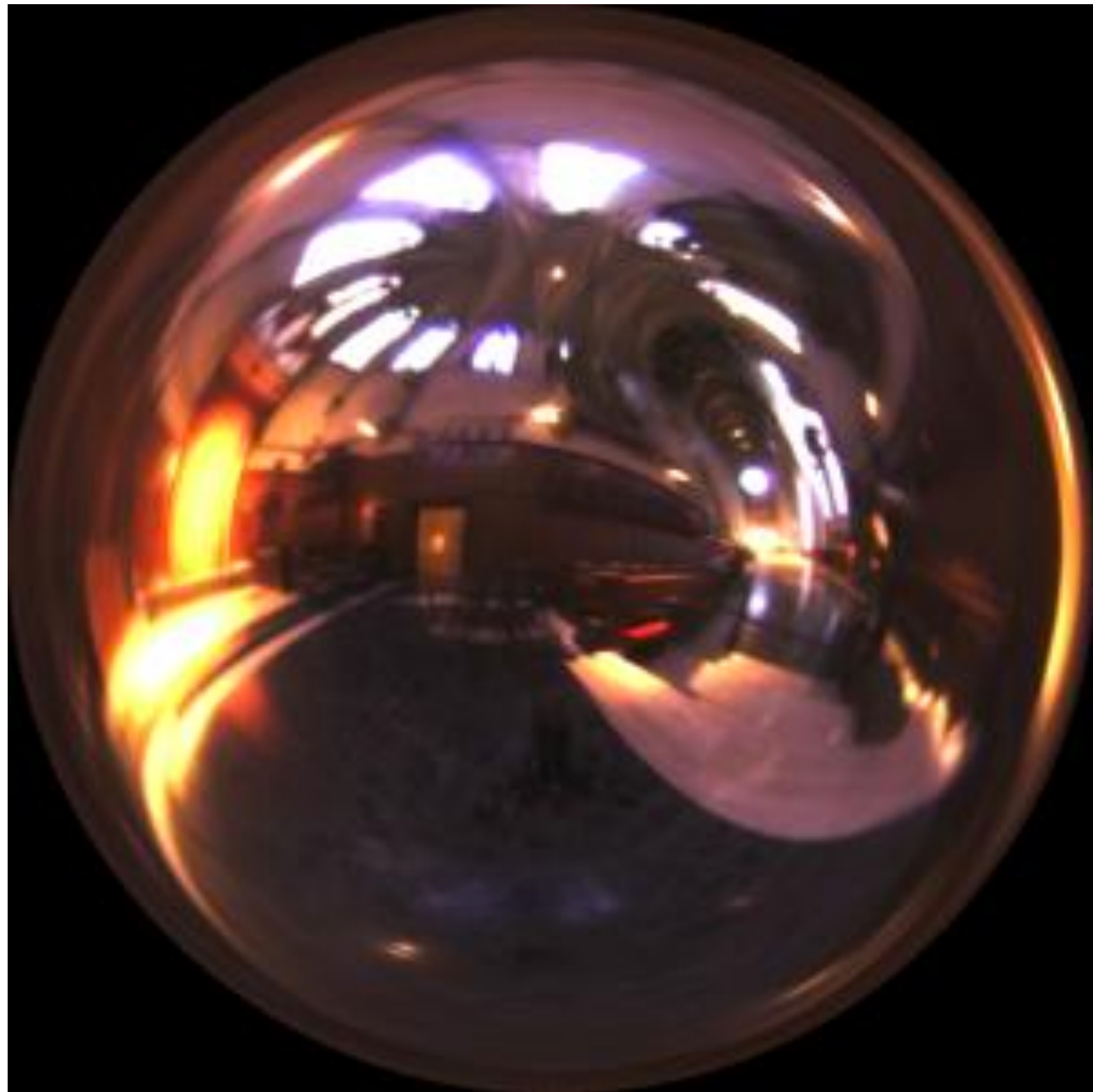
Hand with Reflecting Sphere. M. C. Escher, 1935. lithograph



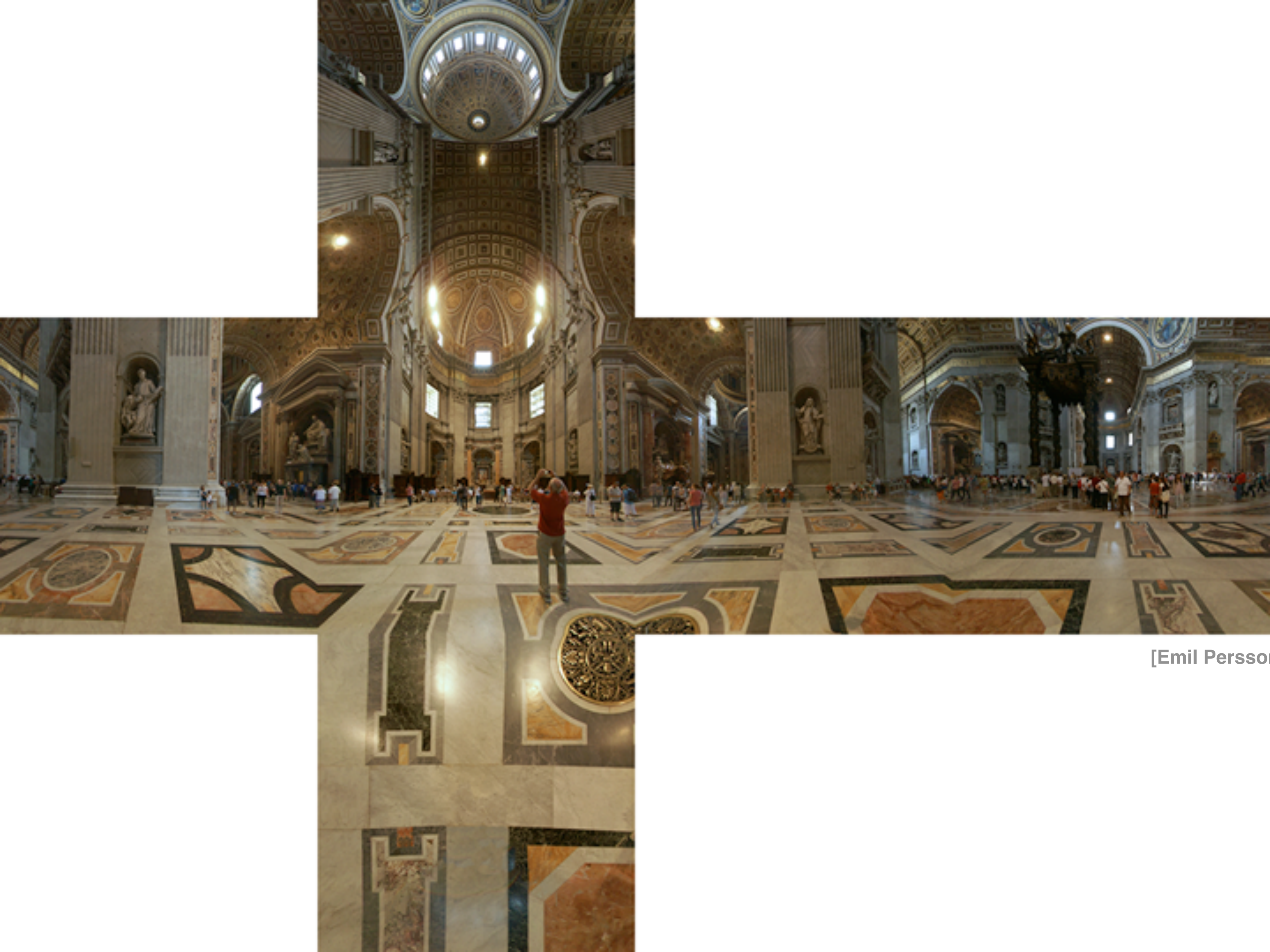
Eucalyptus Grove Light Probe
©1999 Paul Debevec
<http://www.debevec.org/Probes>

Light Probes, Paul Debevec

Environmental Lighting

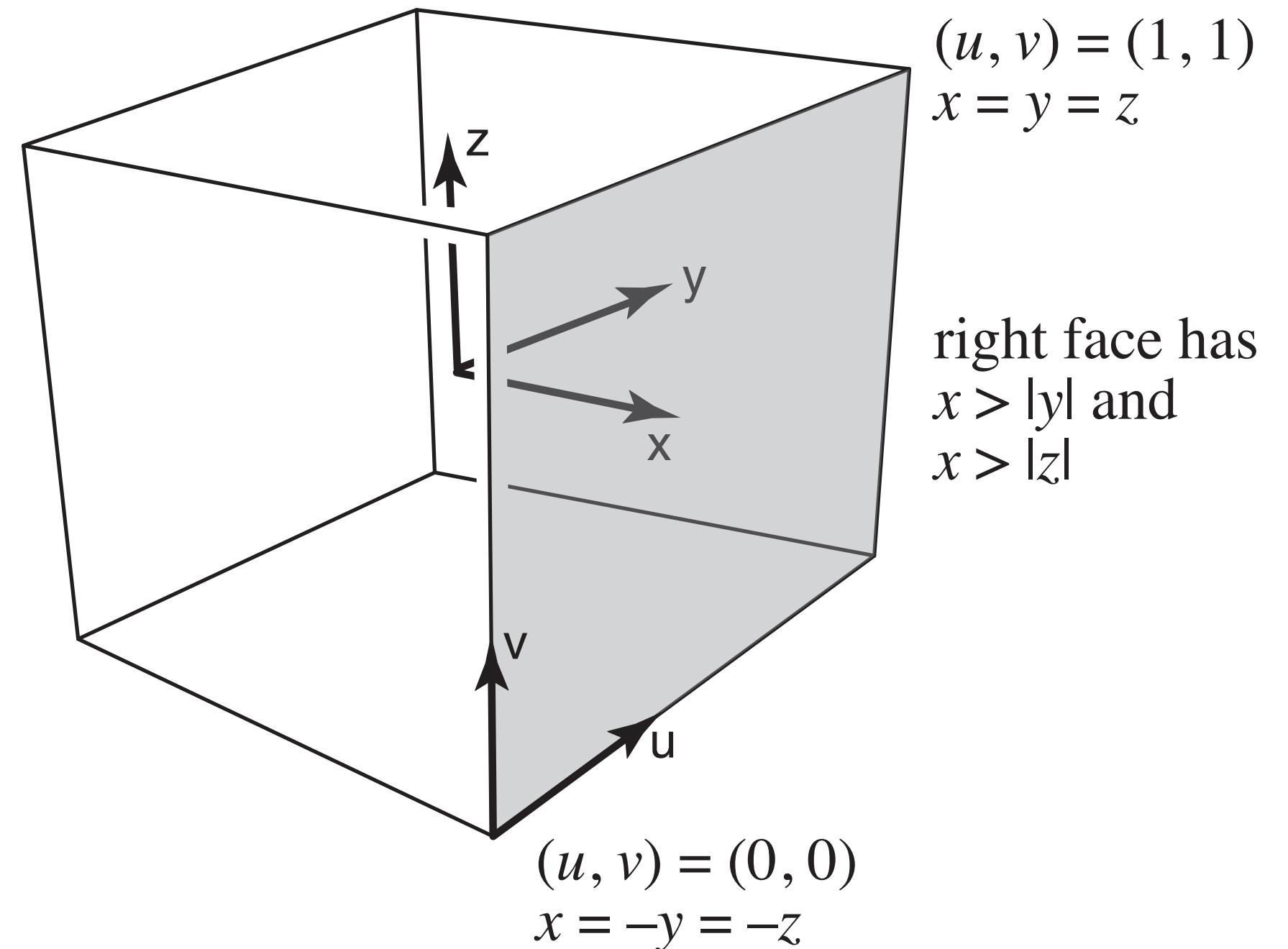
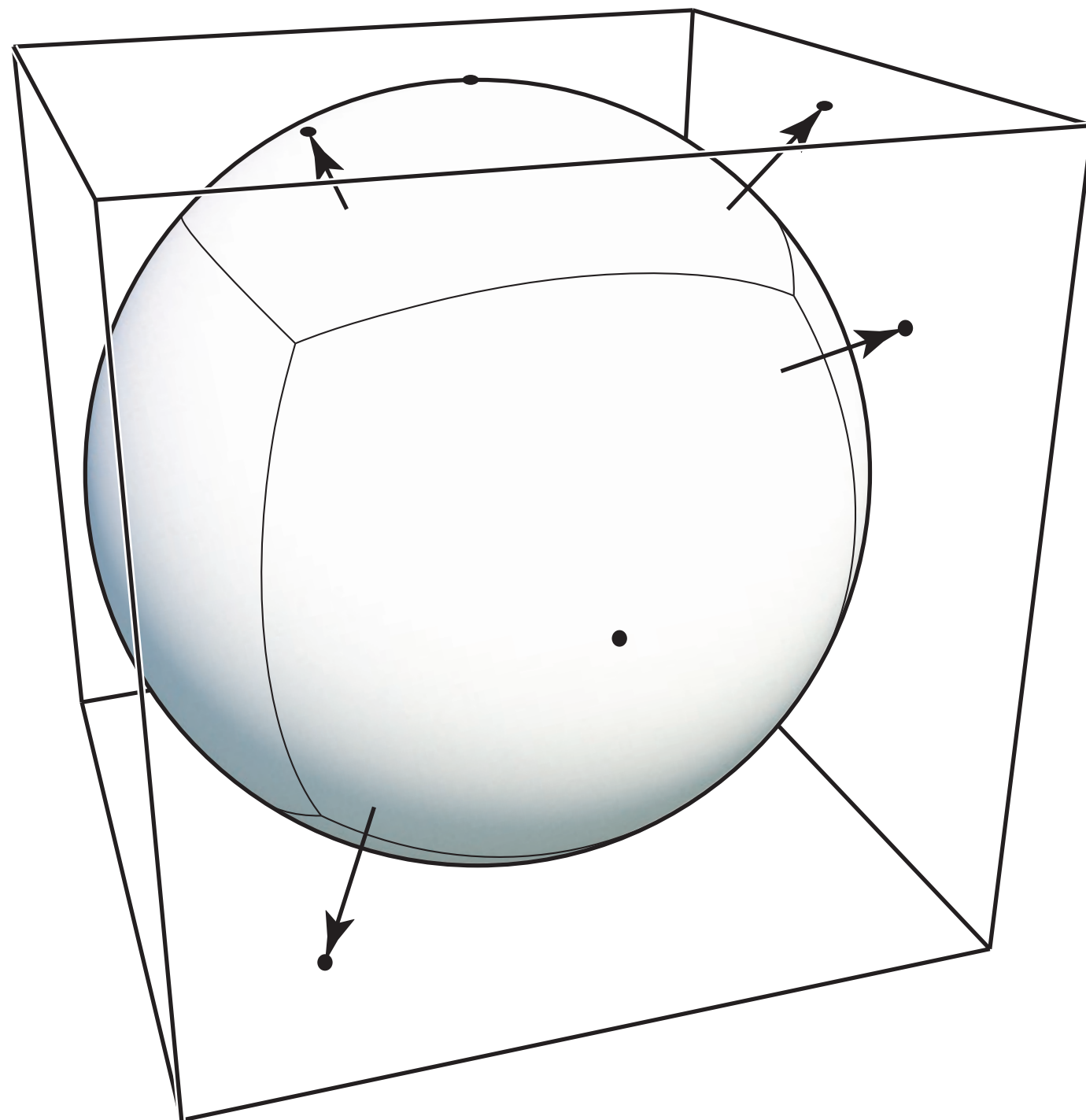


Environment map (left) used to render realistic lighting



[Emil Persson]

Cube Map

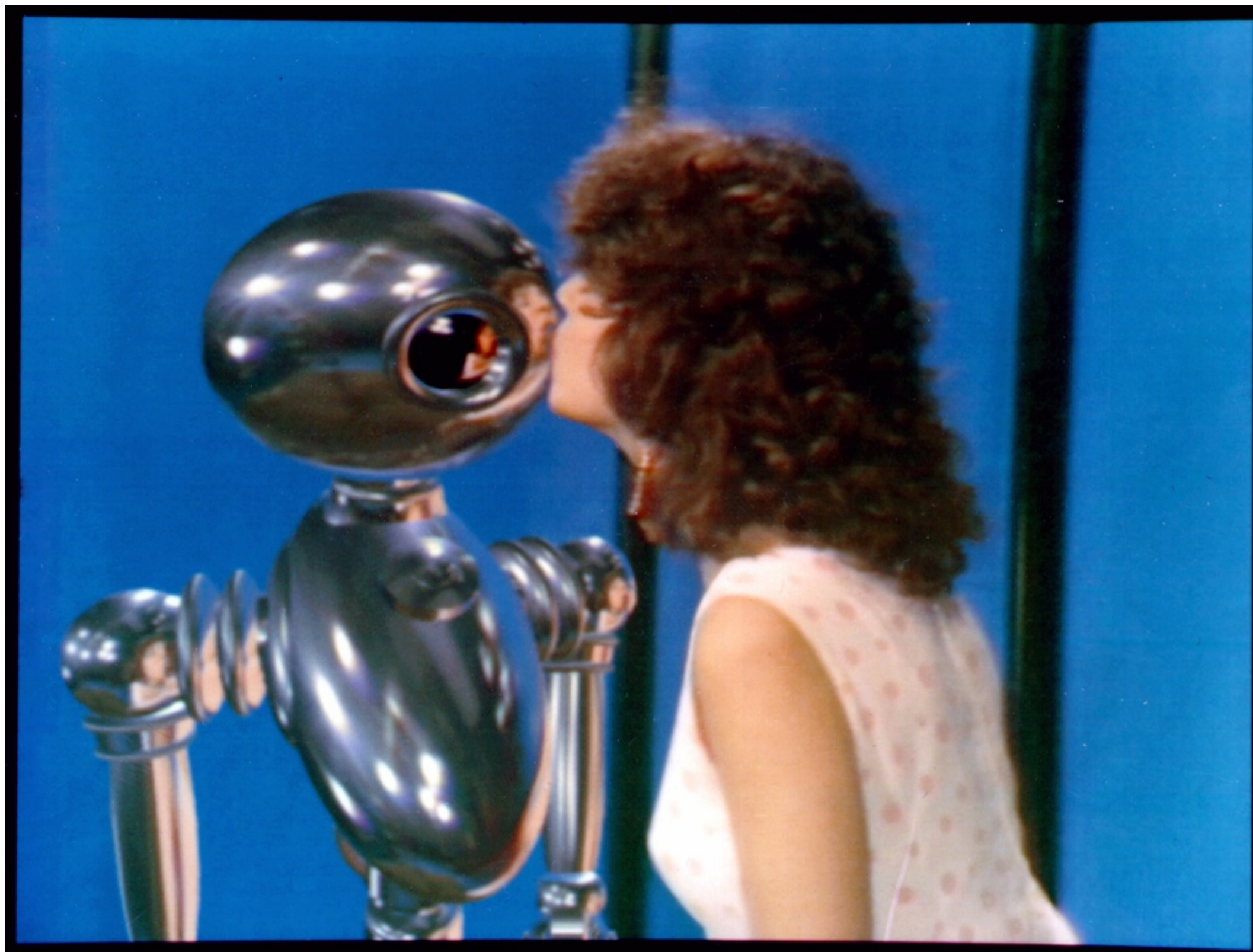


**A vector maps to cube point along that direction.
The cube is textured with 6 square texture maps.**

Environment Maps

Used in 1985 in movie *Interface*

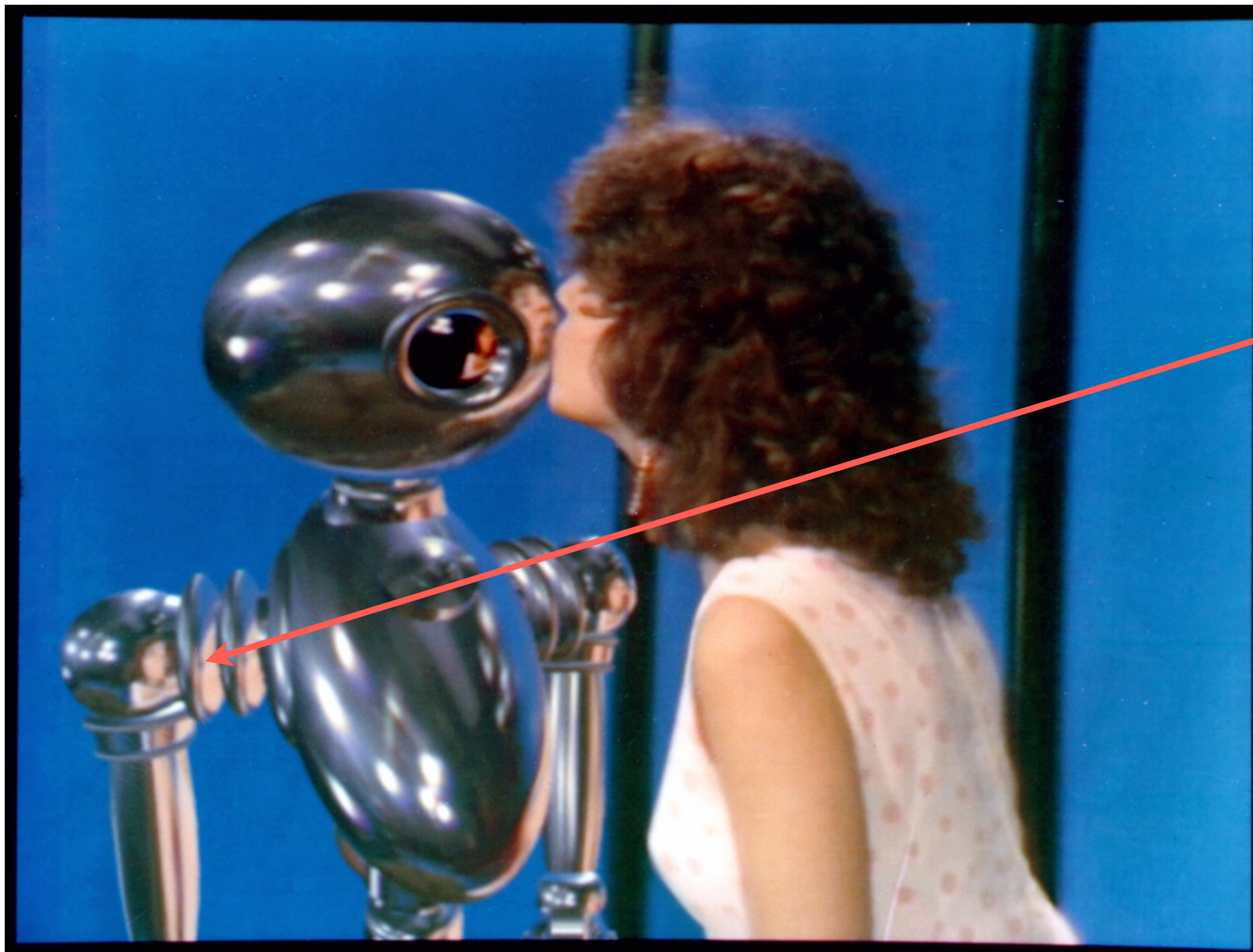
- Lance Williams from the New York Institute of Technology



Environment Maps

Used in 1985 in movie *Interface*

- Lance Williams from the New York Institute of Technology

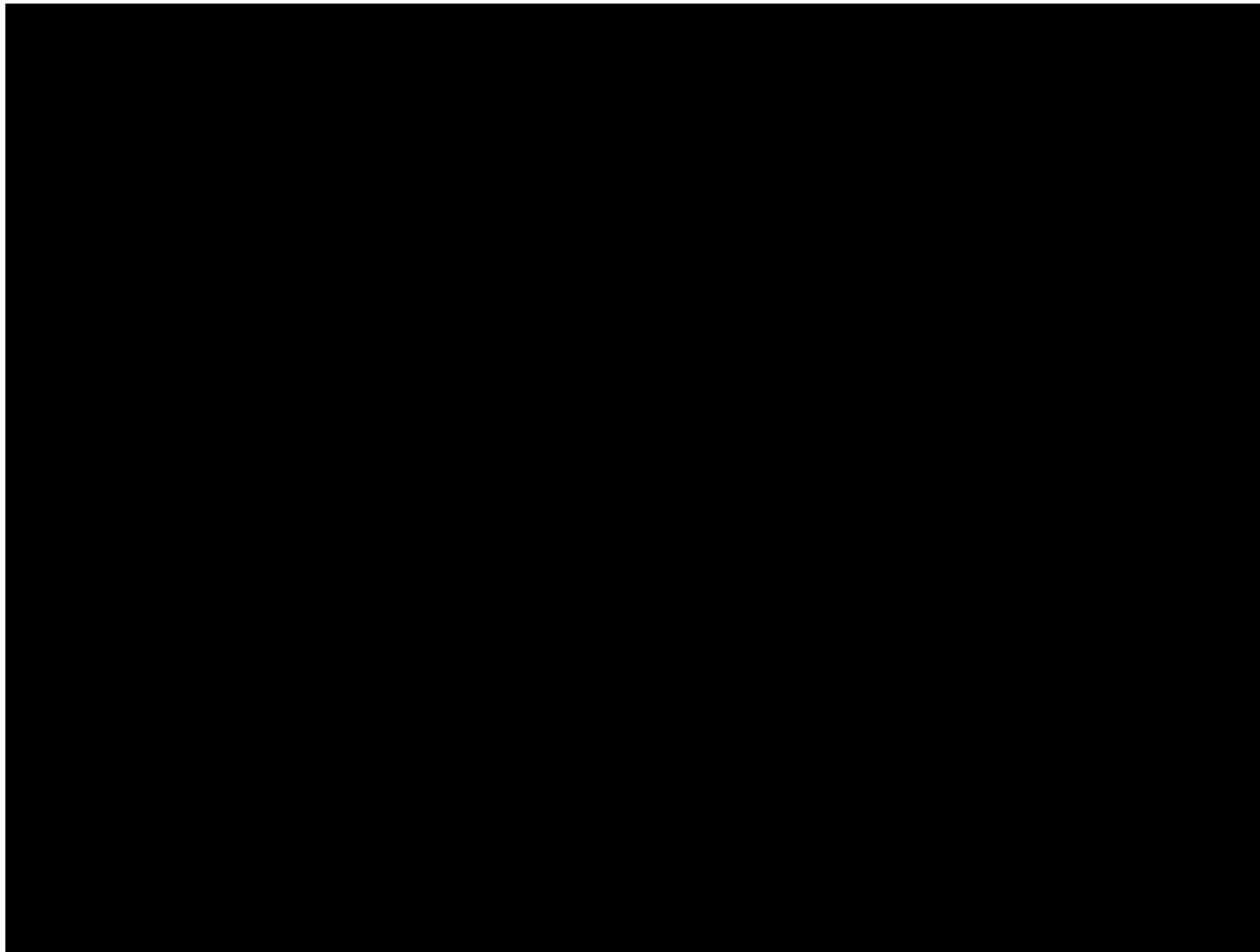


Note errors

Environment Maps

Used in 1985 in movie *Interface*

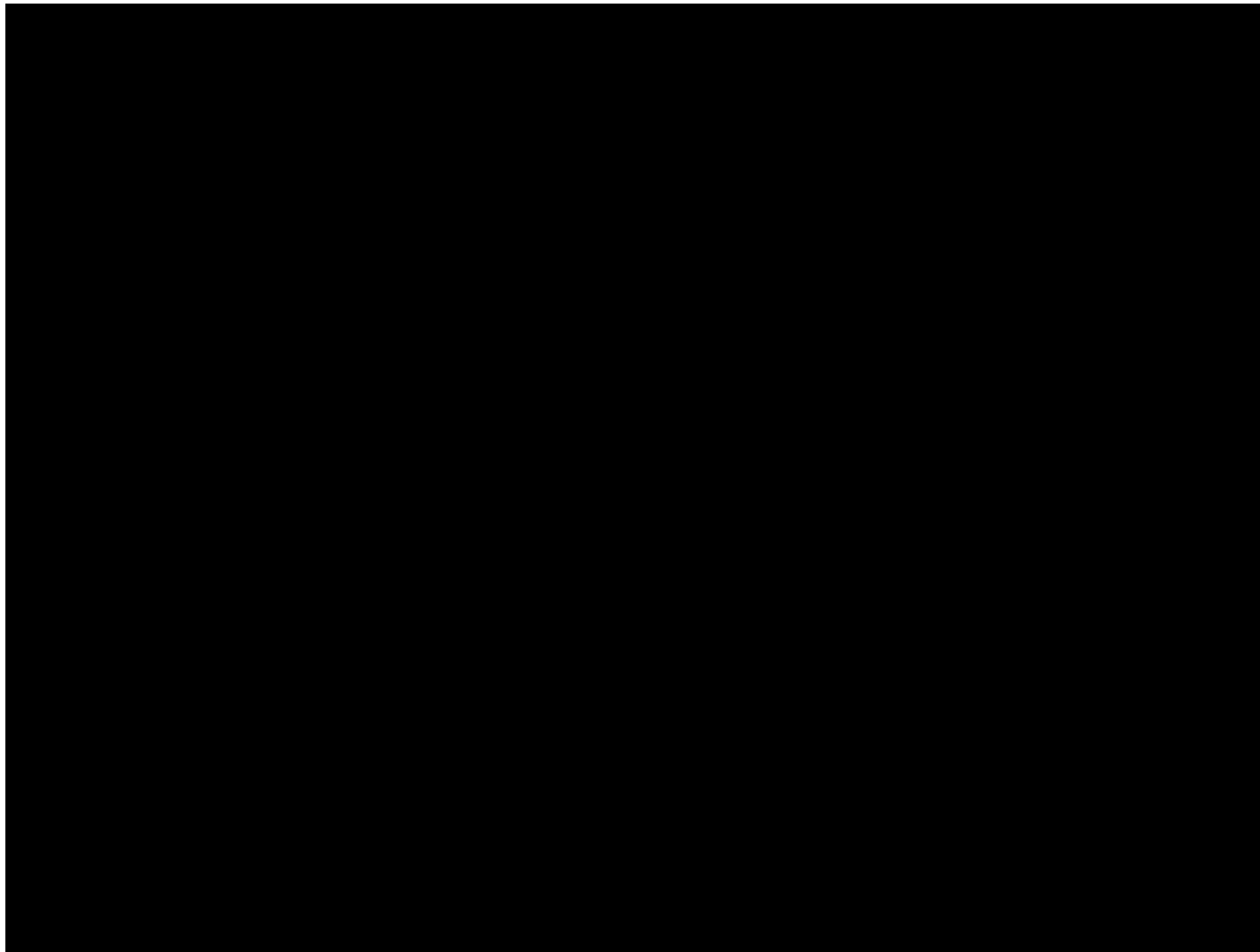
- Lance Williams from the New York Institute of Technology



Environment Maps

Used in 1985 in movie *Interface*

- Lance Williams from the New York Institute of Technology



Displacement Mapping

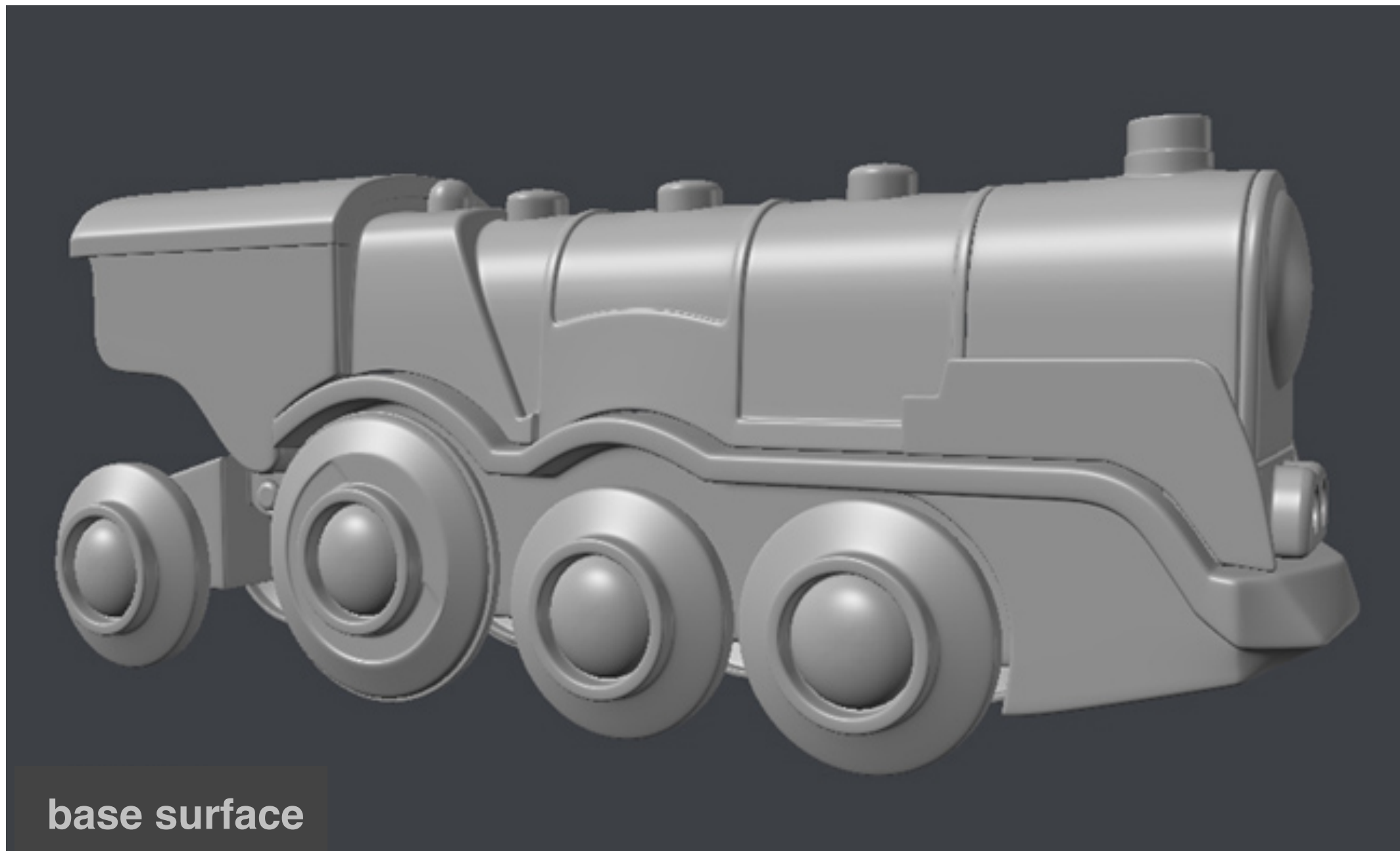
Texture stores perturbation to surface position



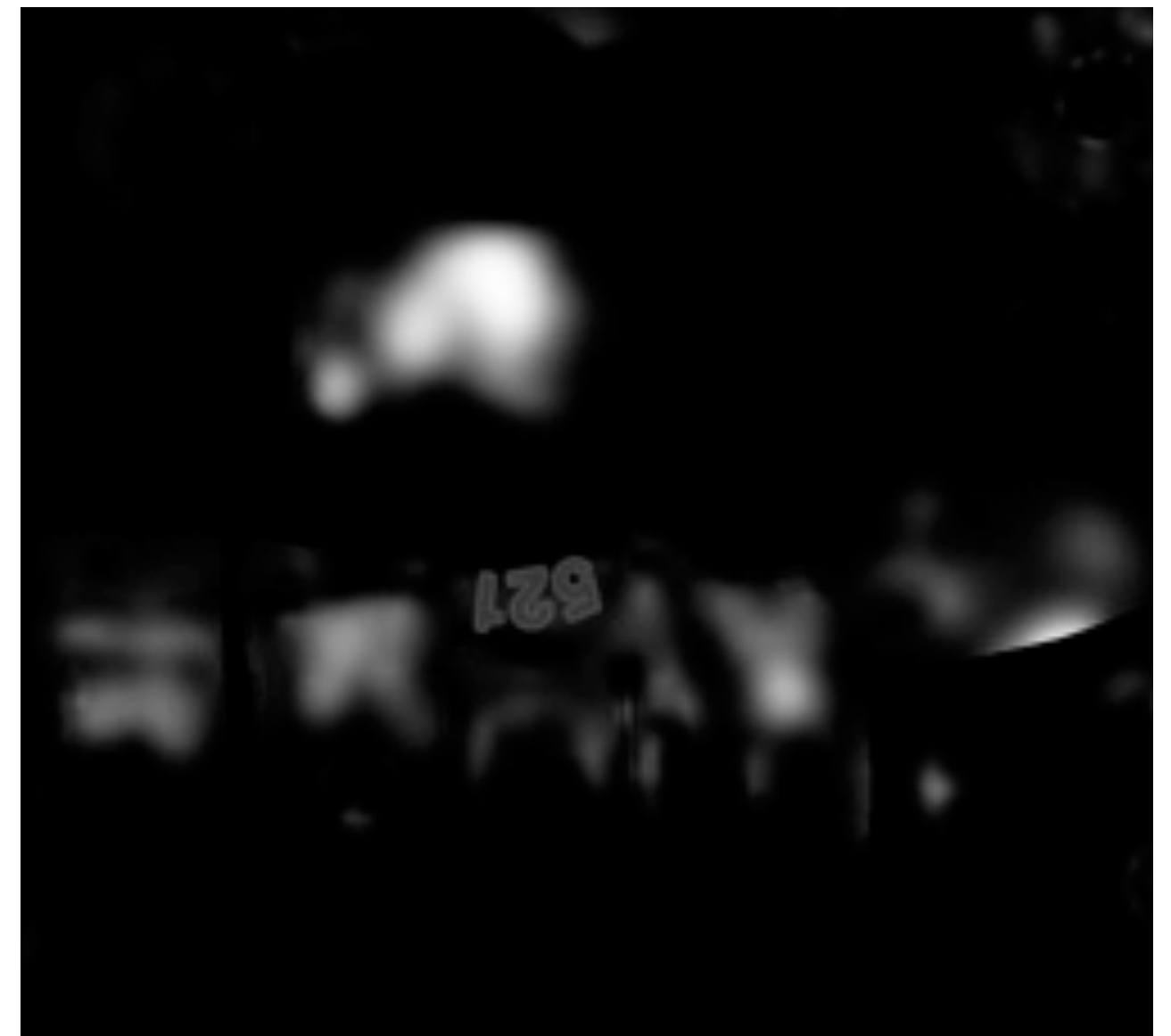
fryrender

physically-based render engine

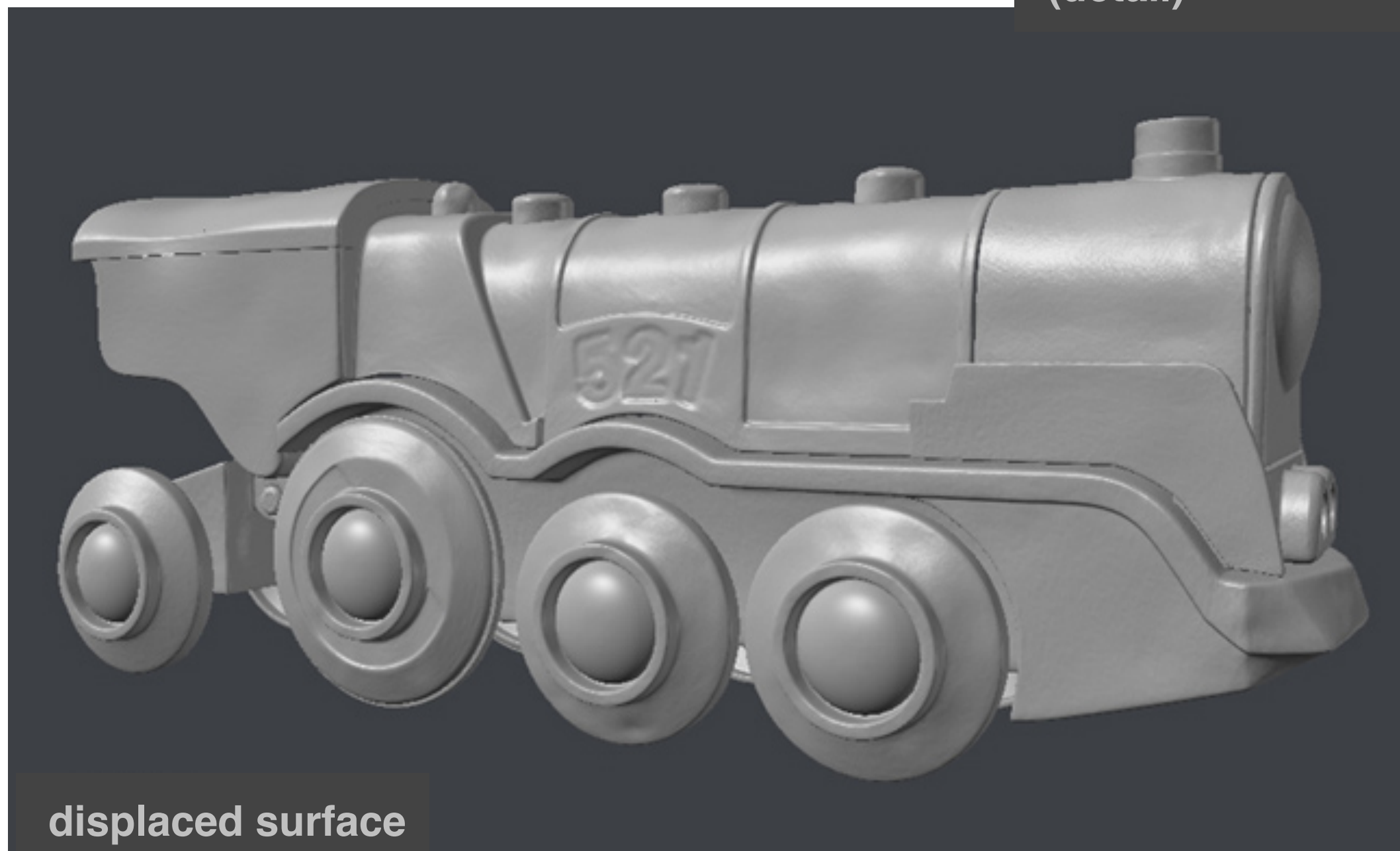
©2007 Paweł Filip



base surface

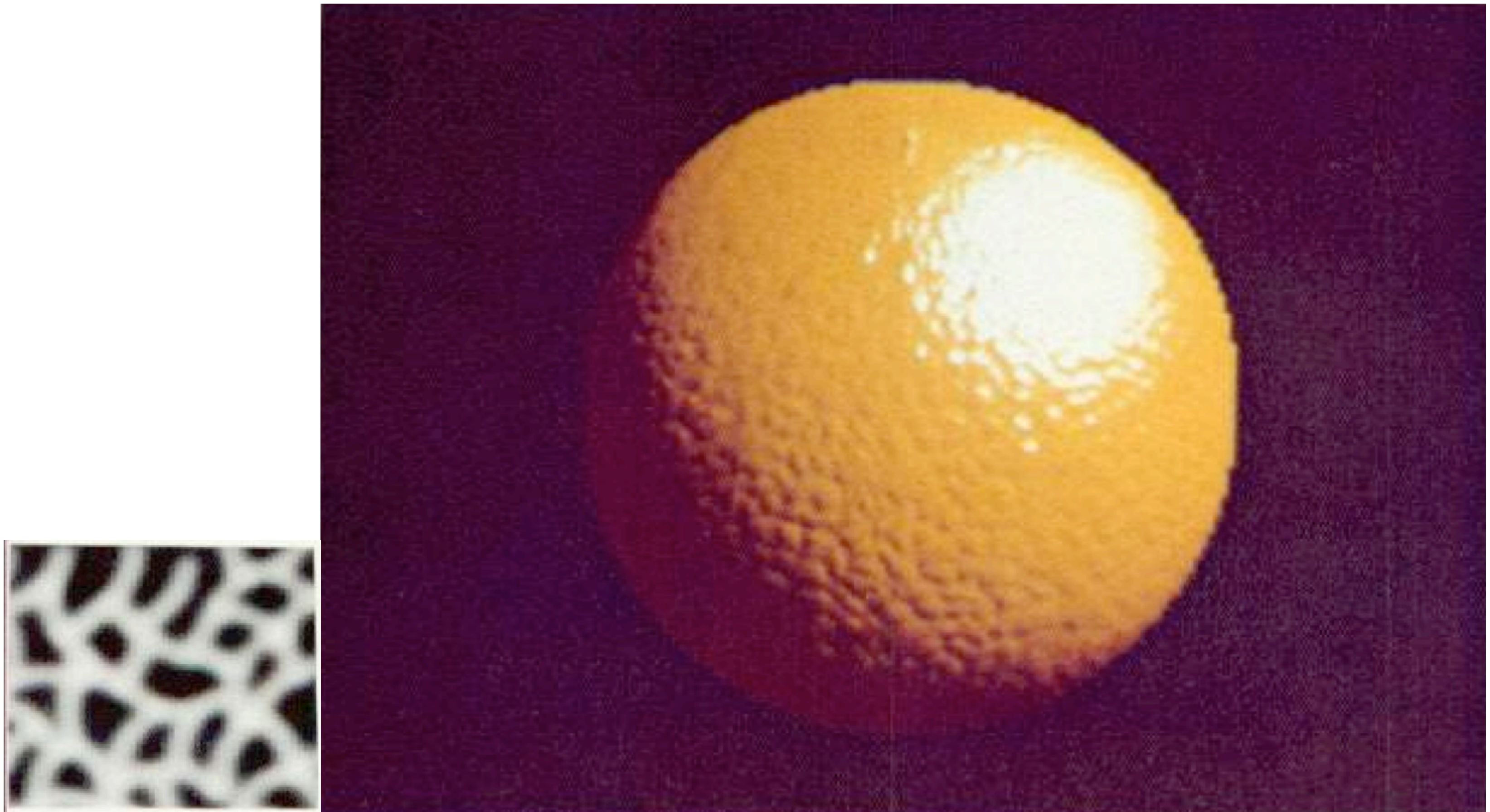


hand-painted displacement map
(detail)



displaced surface

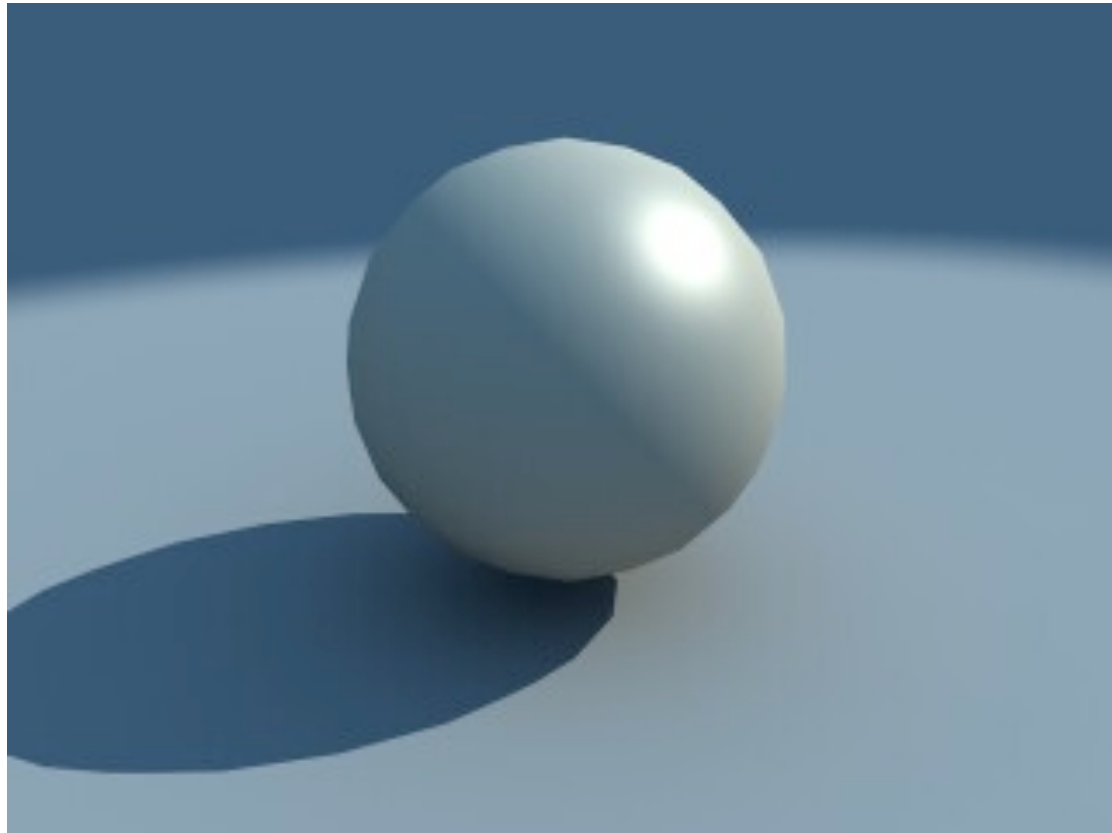
Bump Mapping



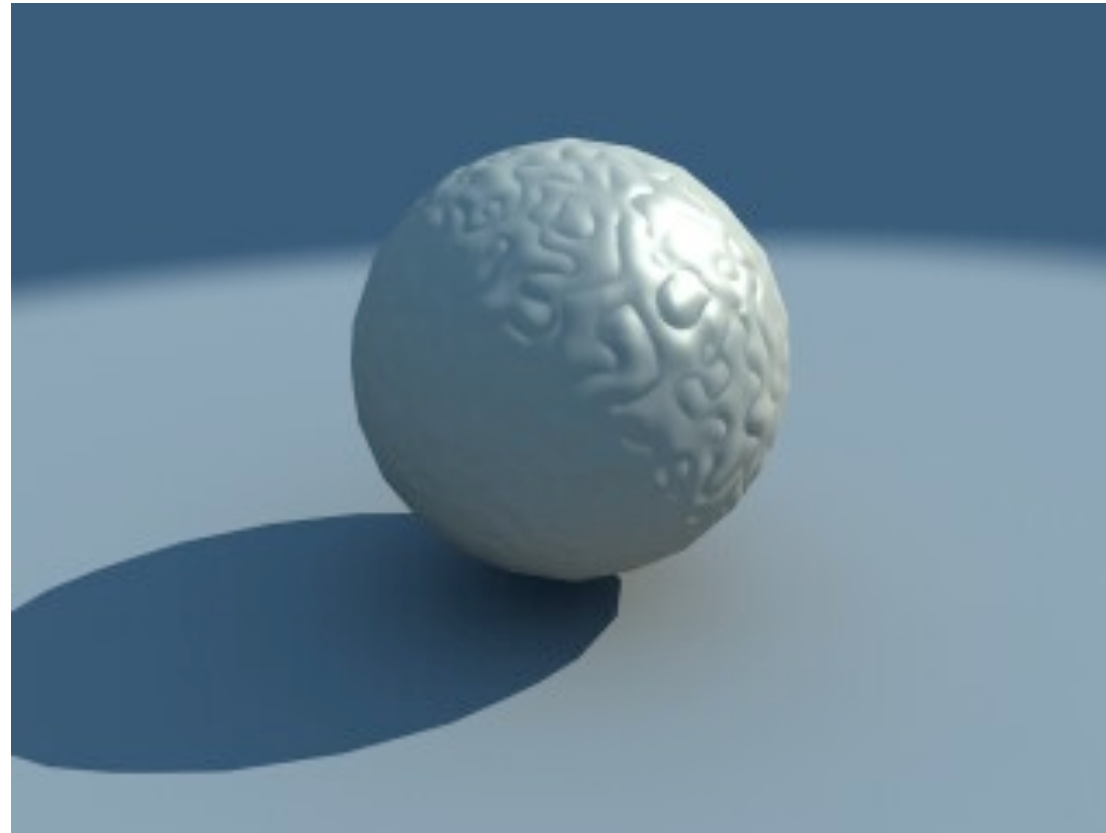
[Blinn 1978]

Texture stores perturbation to surface normal

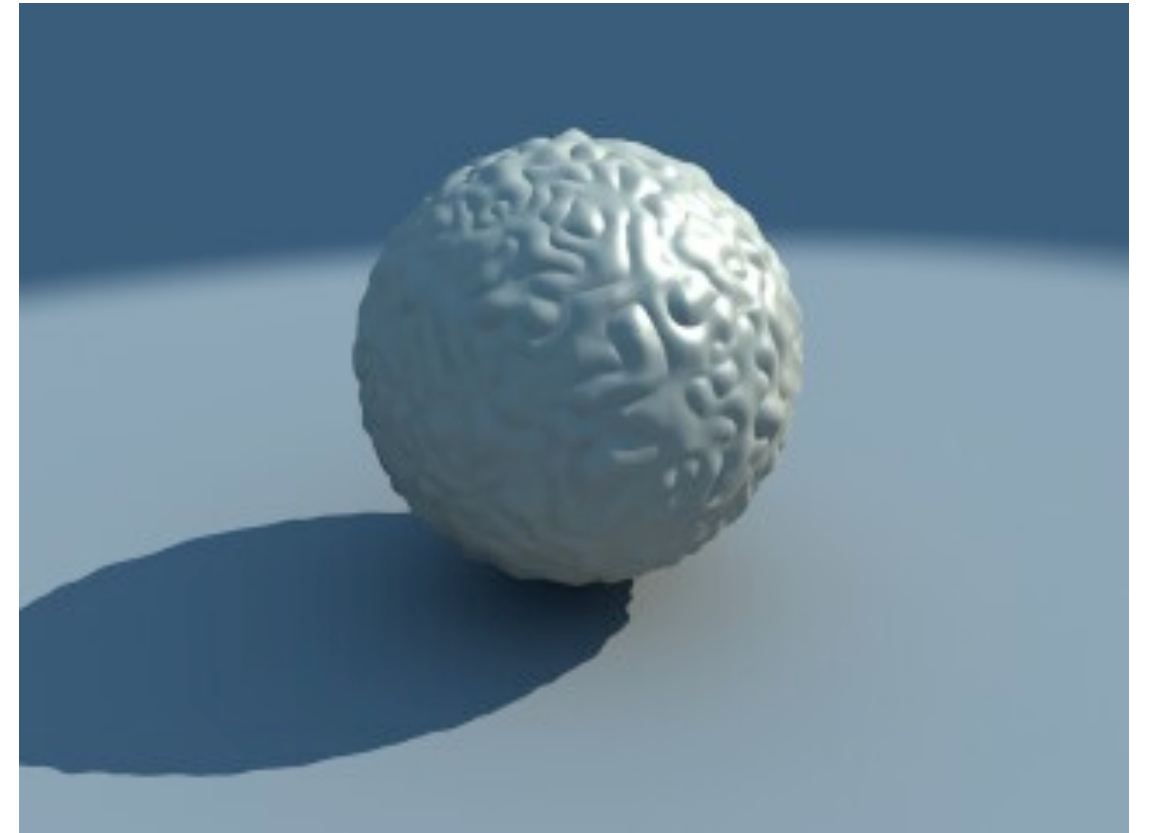
Bump Mapping



Geometry



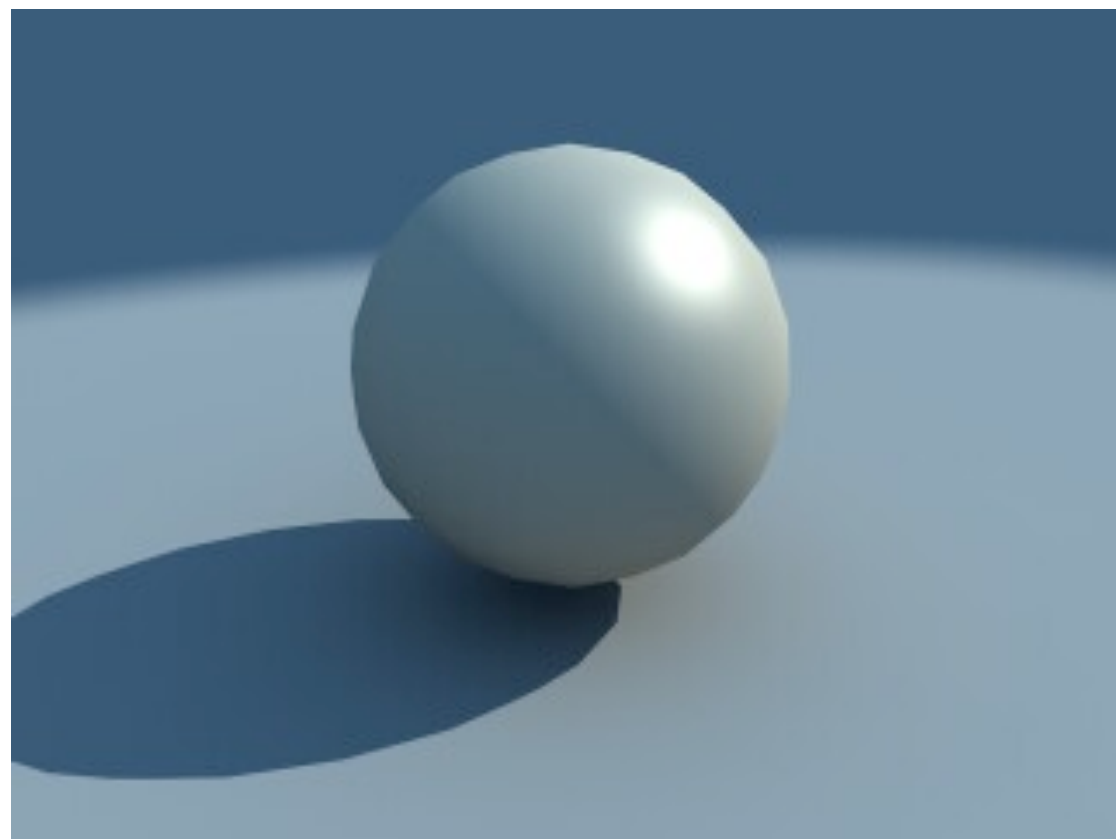
Bump mapping



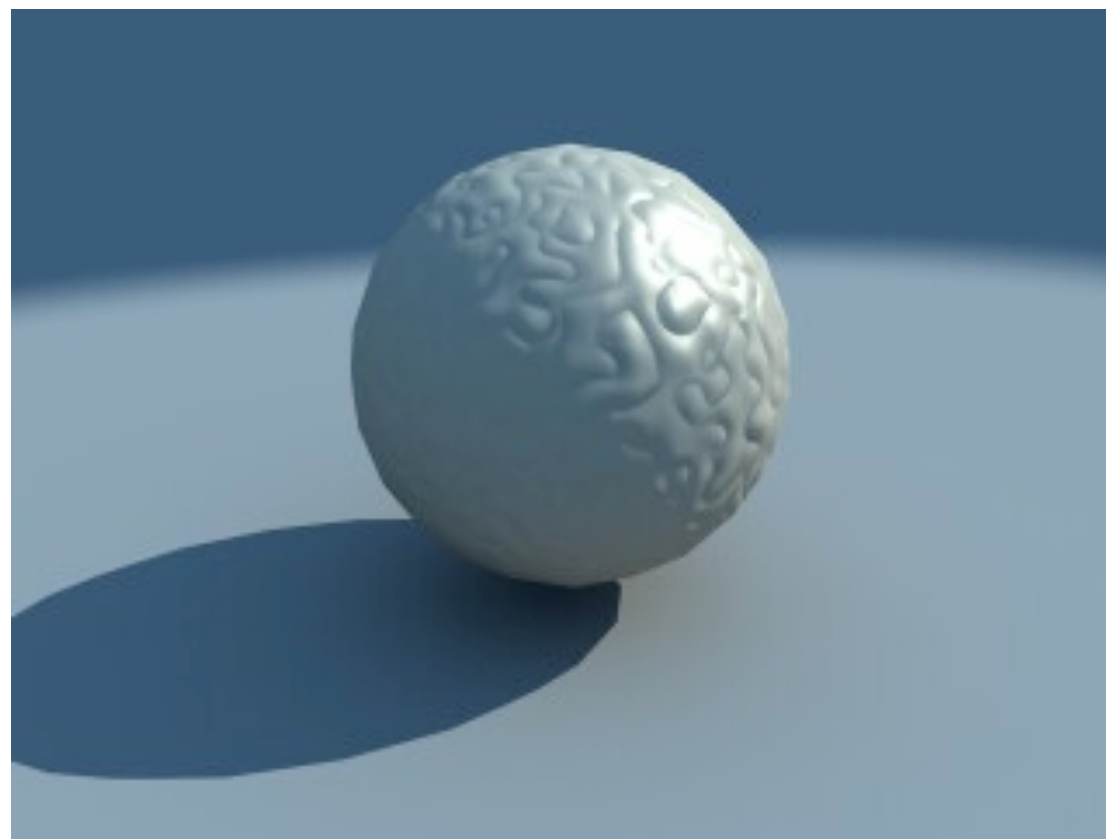
Displacement mapping

Bump Mapping

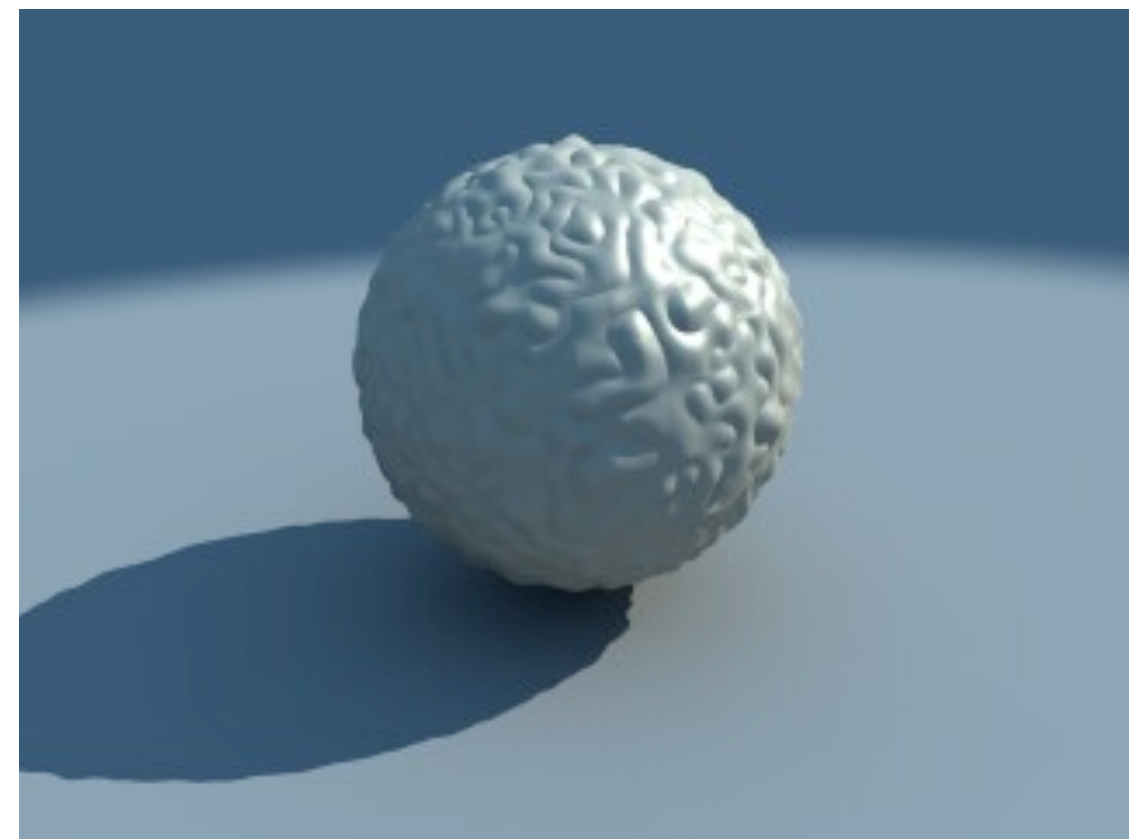
Where is the difference most noticeable?



Geometry



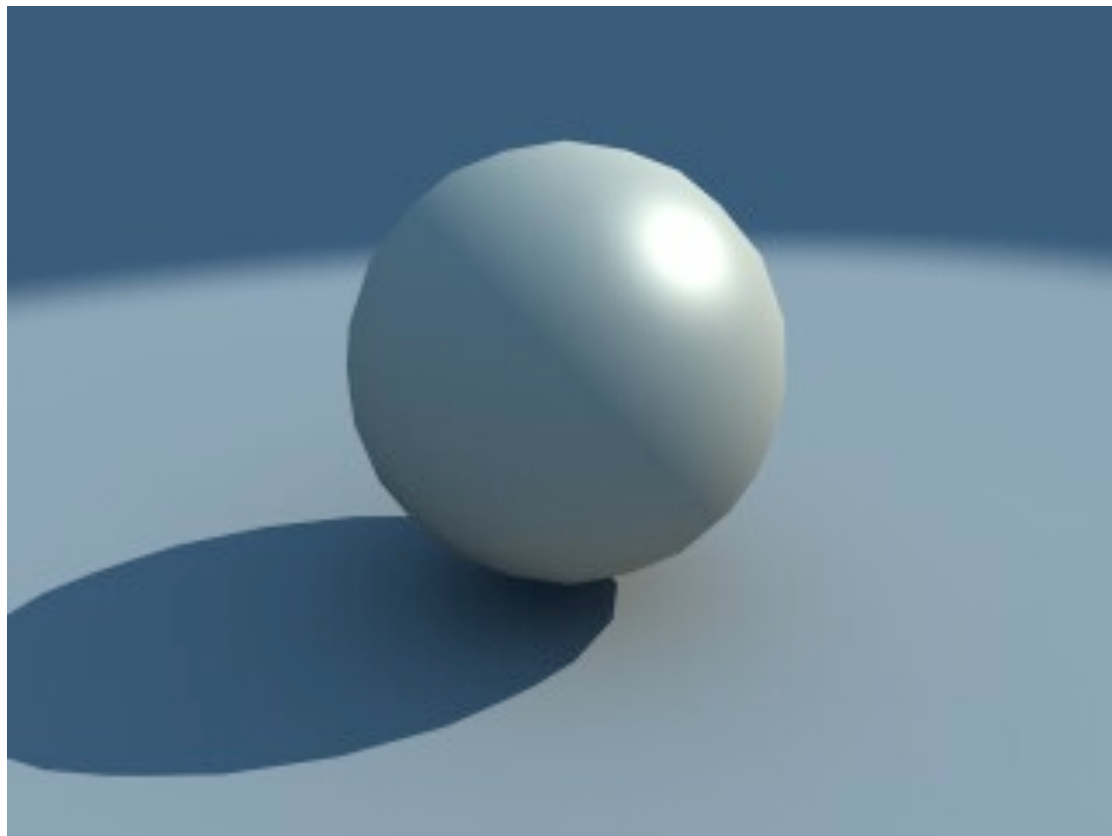
Bump mapping



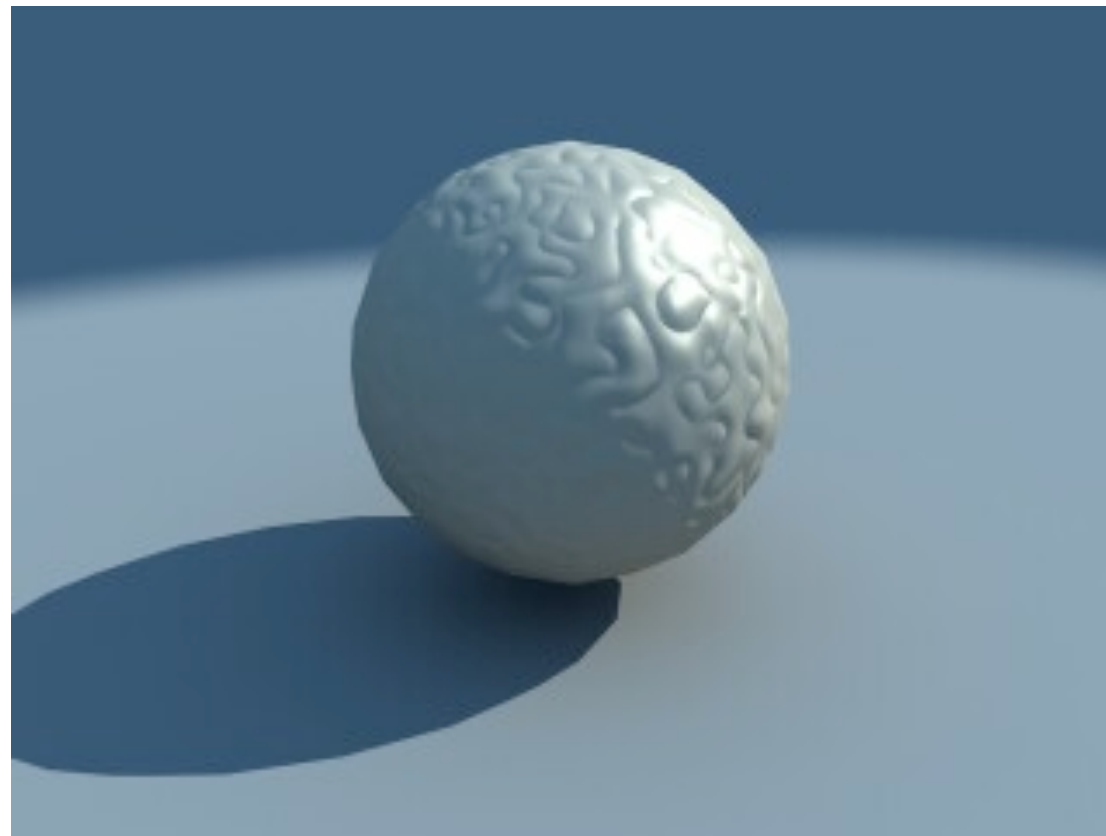
Displacement mapping

Bump Mapping

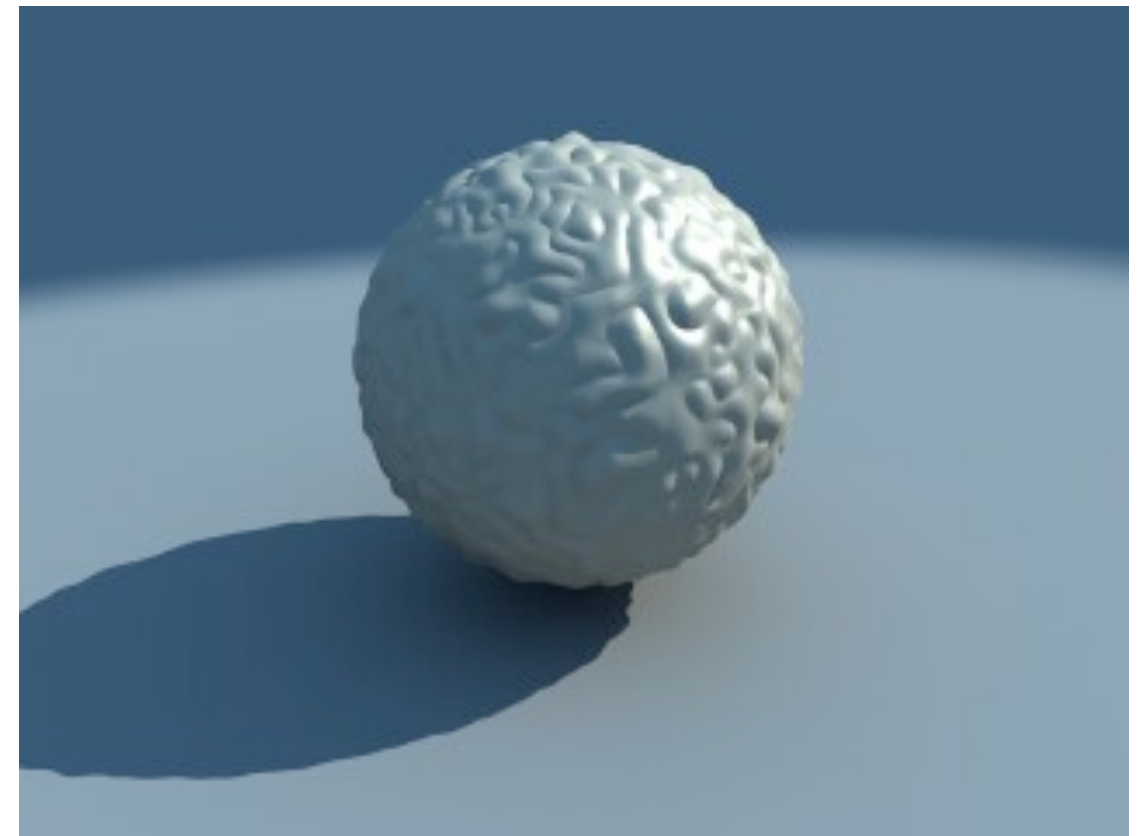
Where is the difference most noticeable?



Geometry

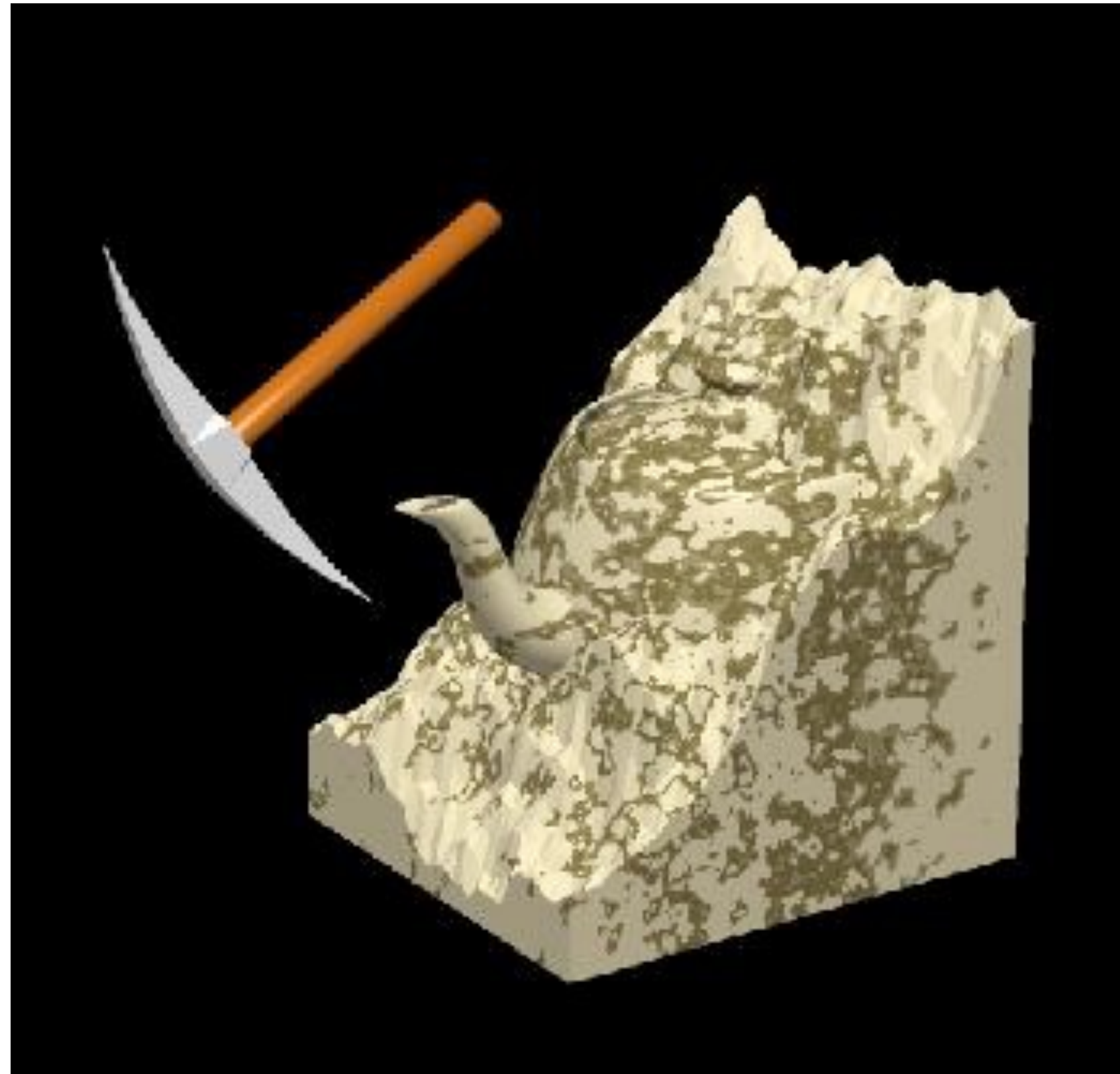


Bump mapping
Perturbs normals



Displacement mapping
Perturbs positions

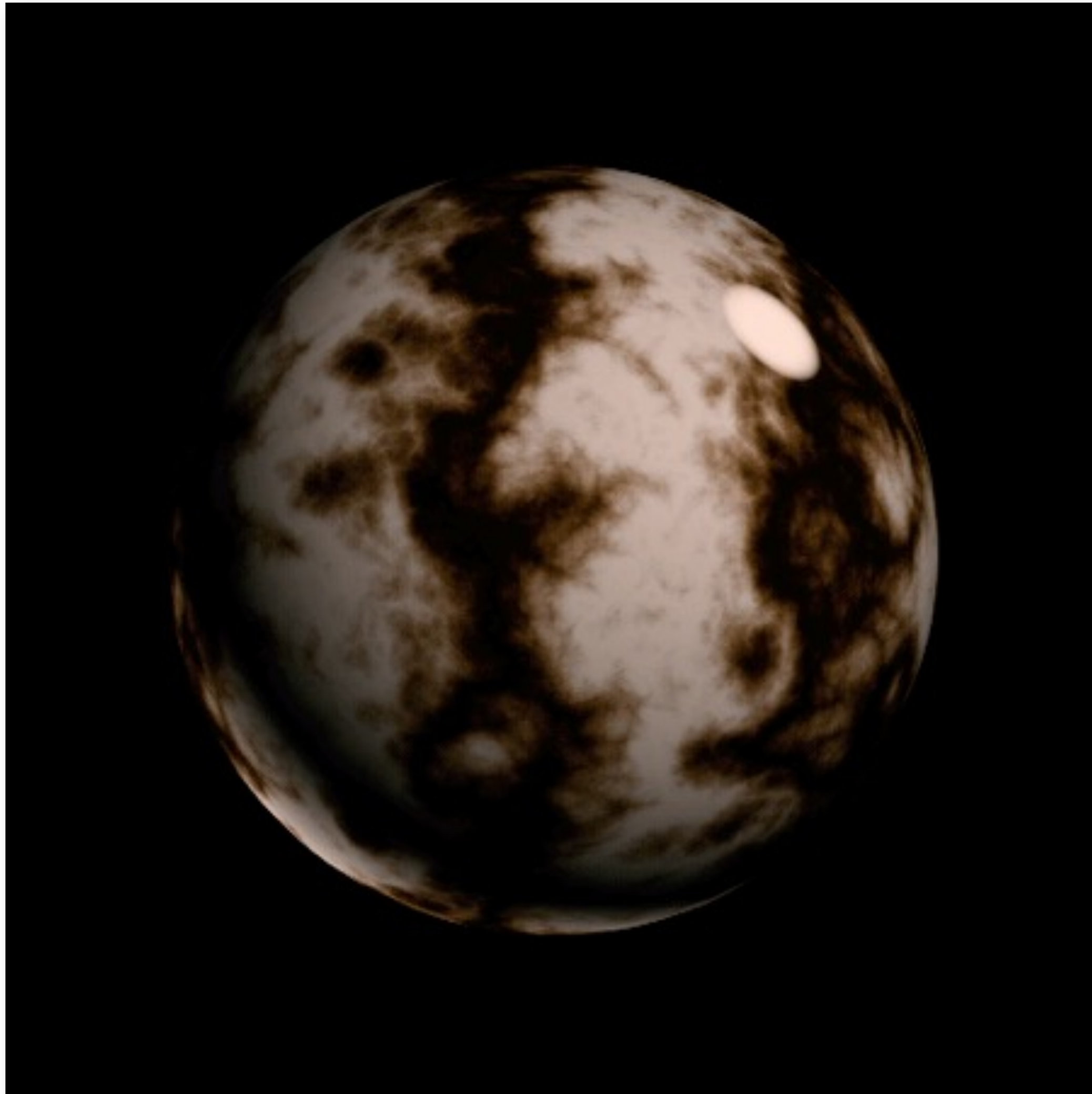
3D Textures



[Wolfe / SG97 Slide set]

Textures is a function of (u,v,w) . Solid modeling.

3D Procedural Noise + Solid Modeling



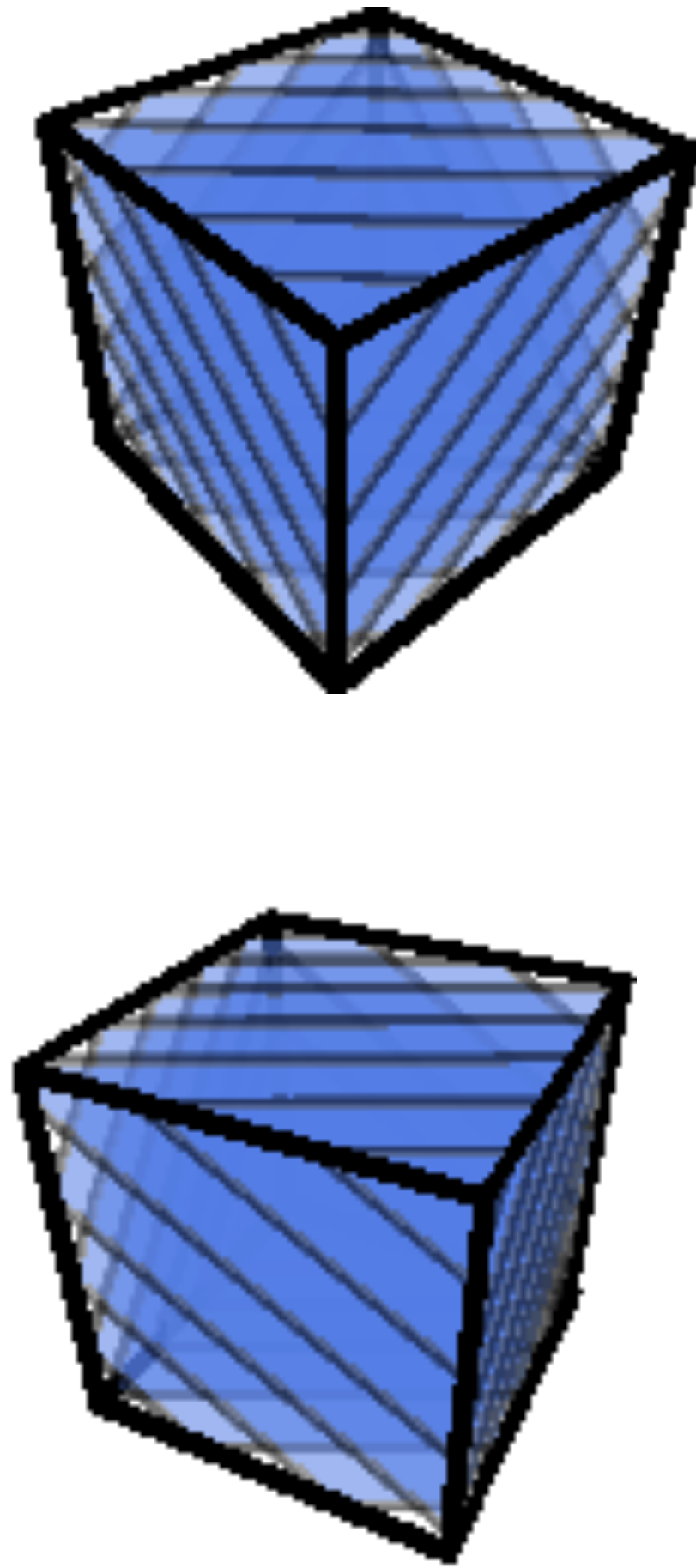
CS184/284A



Perlin noise, Ken Perlin

S26 - O'Brien

3D Textures and Volume Rendering



Marc Levoy

Provide Precomputed Shading



**Simple
shading**



**Ambient occlusion
texture map**



**With ambient
occlusion**

Autodesk

Things to Remember

Many uses of texturing

- Bring high-resolution data to fragment calculations
- Colors, normals, lighting on sphere, volumetric data, ...

How does texturing work?

- Texture coordinate parameterization
- Barycentric interpolation of coordinates
- Texture sampling pattern and frequency
- Mipmaps: texture filtering hierarchy, level calculation, trilinear interpolation
- Anisotropic sampling

Acknowledgments

The CS 184 slide set was developed by:

- Ren Ng
- James O'Brien

With additional contributions from:

- Kayvon Fatahalian
- David Forsyth
- Pat Hanrahan
- Angjoo Kanazawa
- Mark Pauly

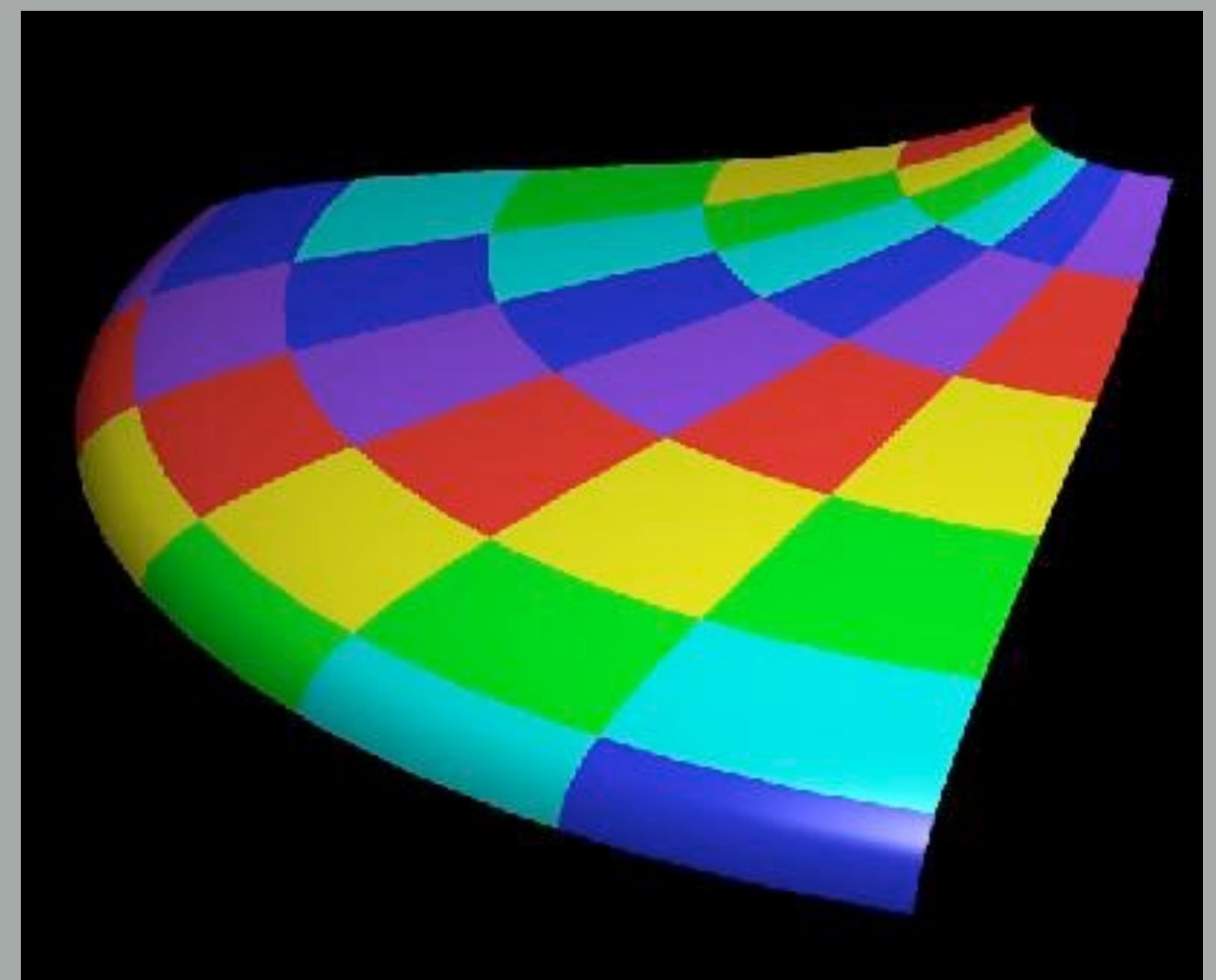
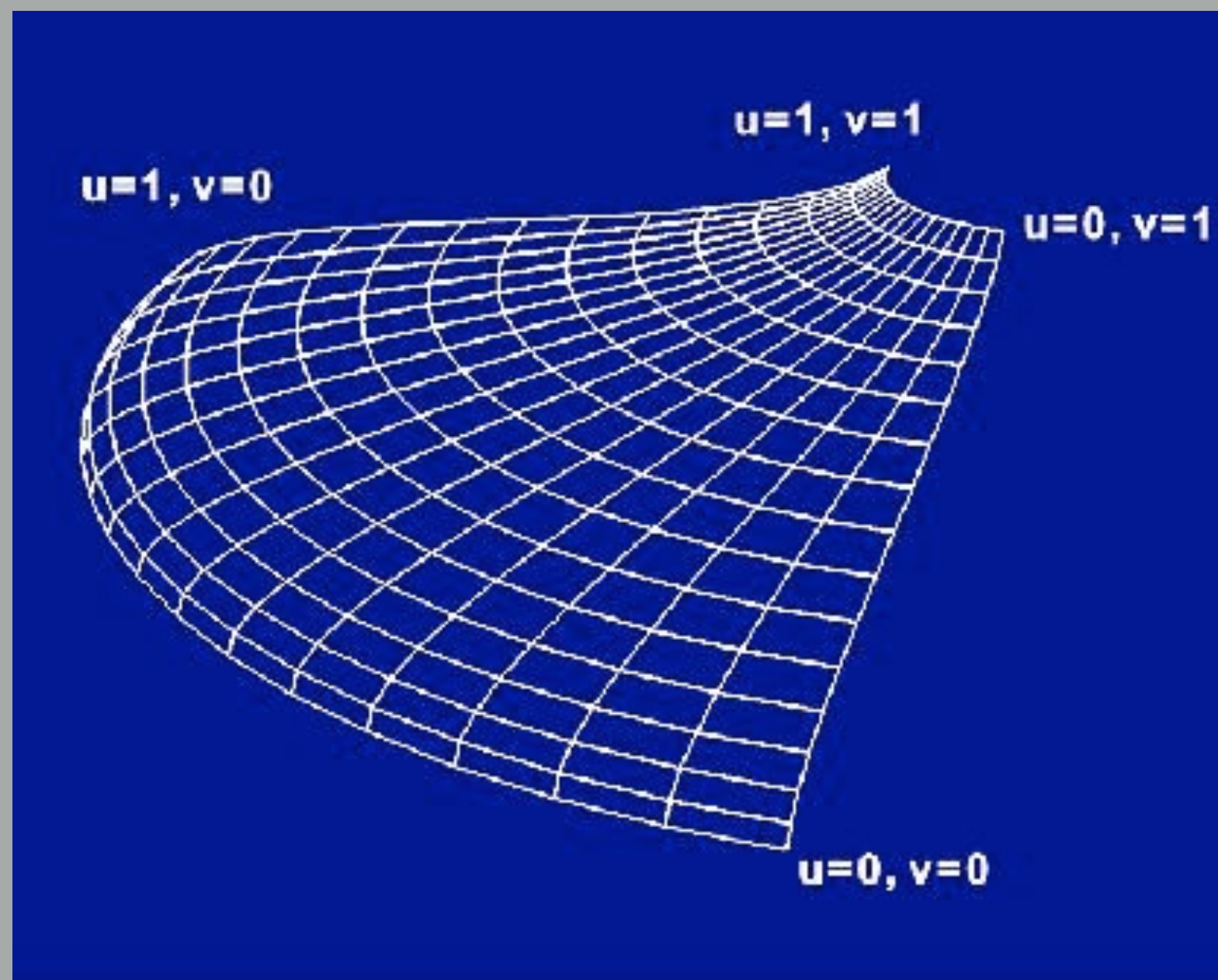
Bonus Slides

Examples of Texture Coordinate Functions

Examples of Texture Coordinate Functions

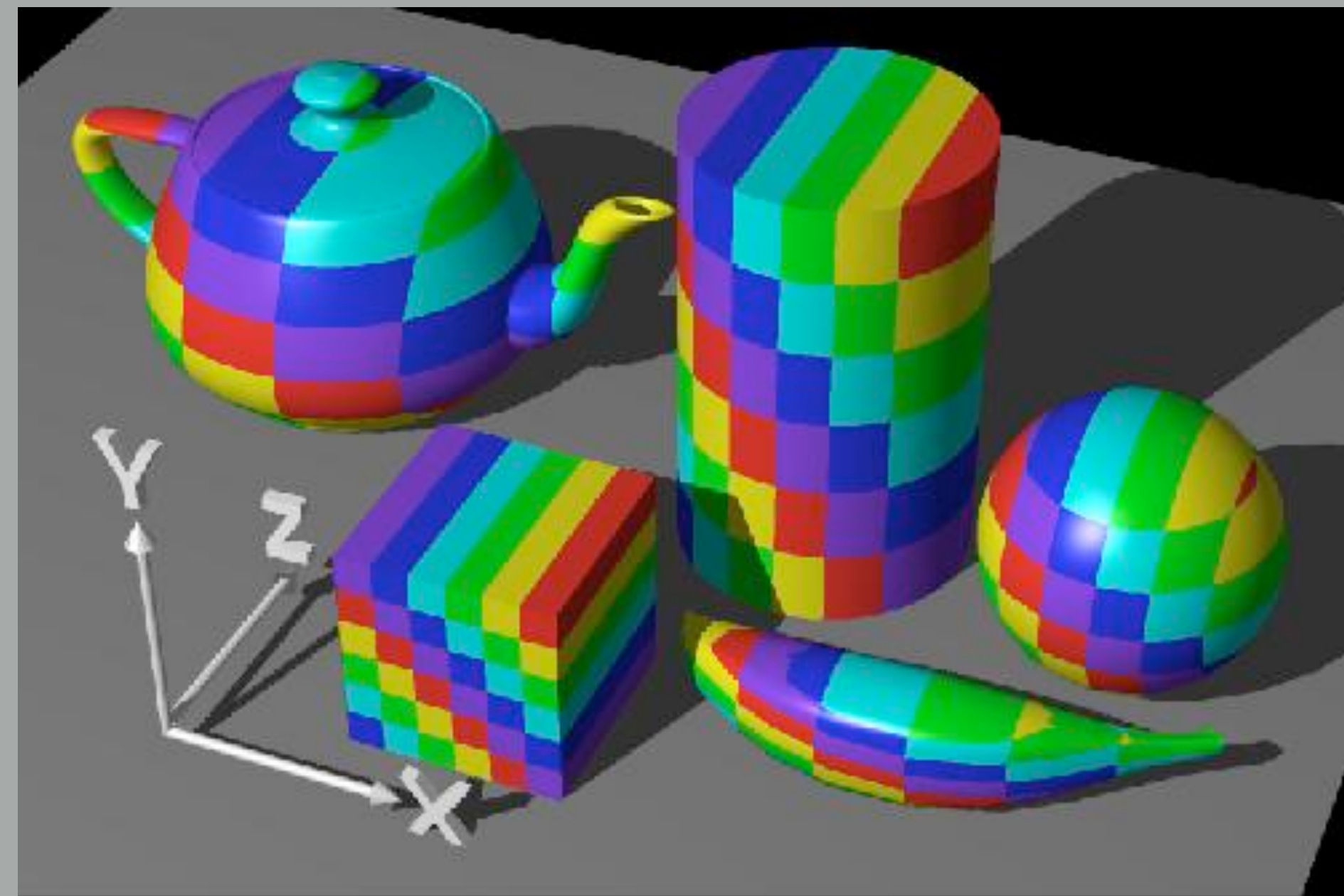
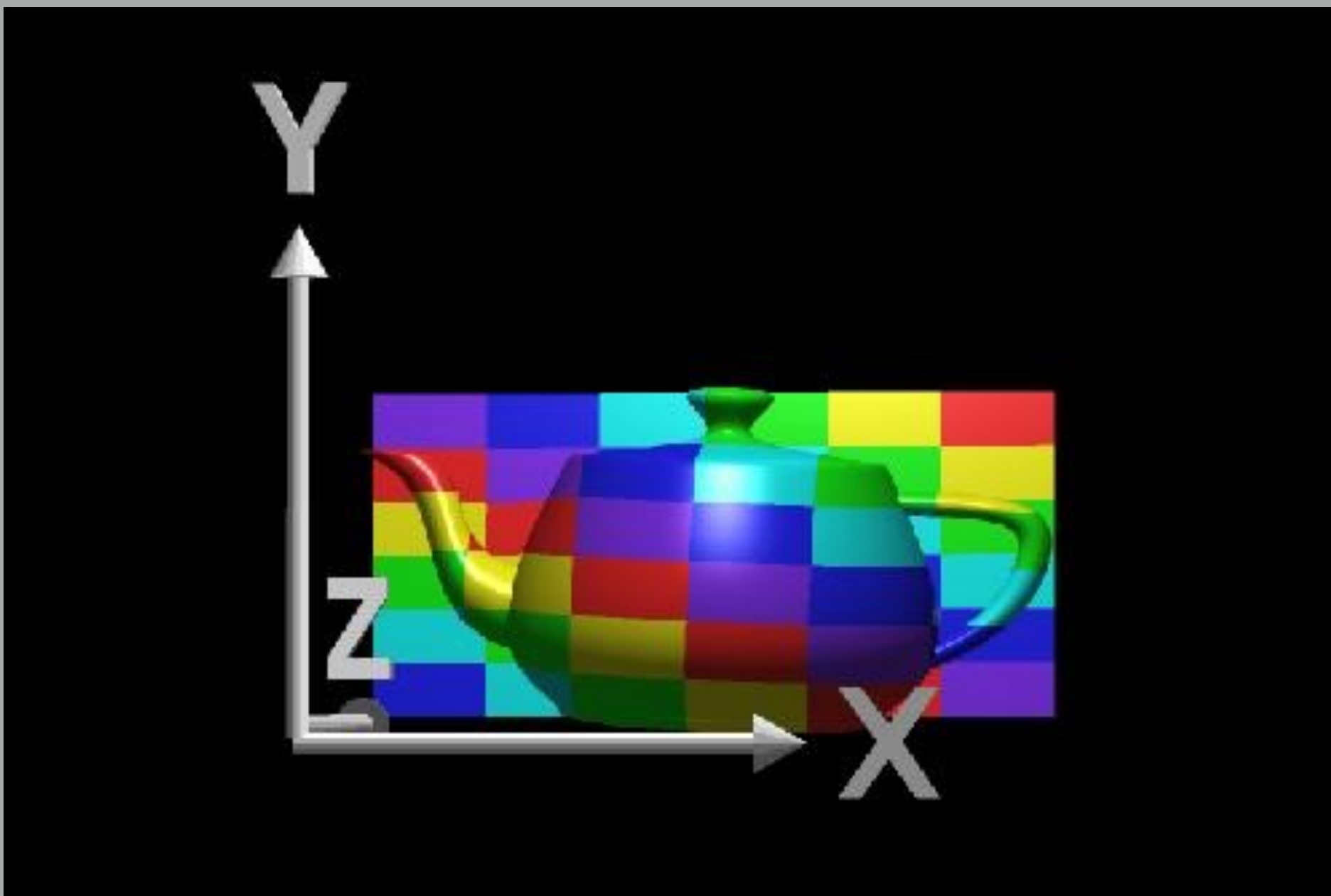
A parametric surface (e.g. spline patch)

- Use parameter space coordinates as texture coordinates directly



[Wolfe / SG97 Slide set]

Examples of Texture Coordinate Functions

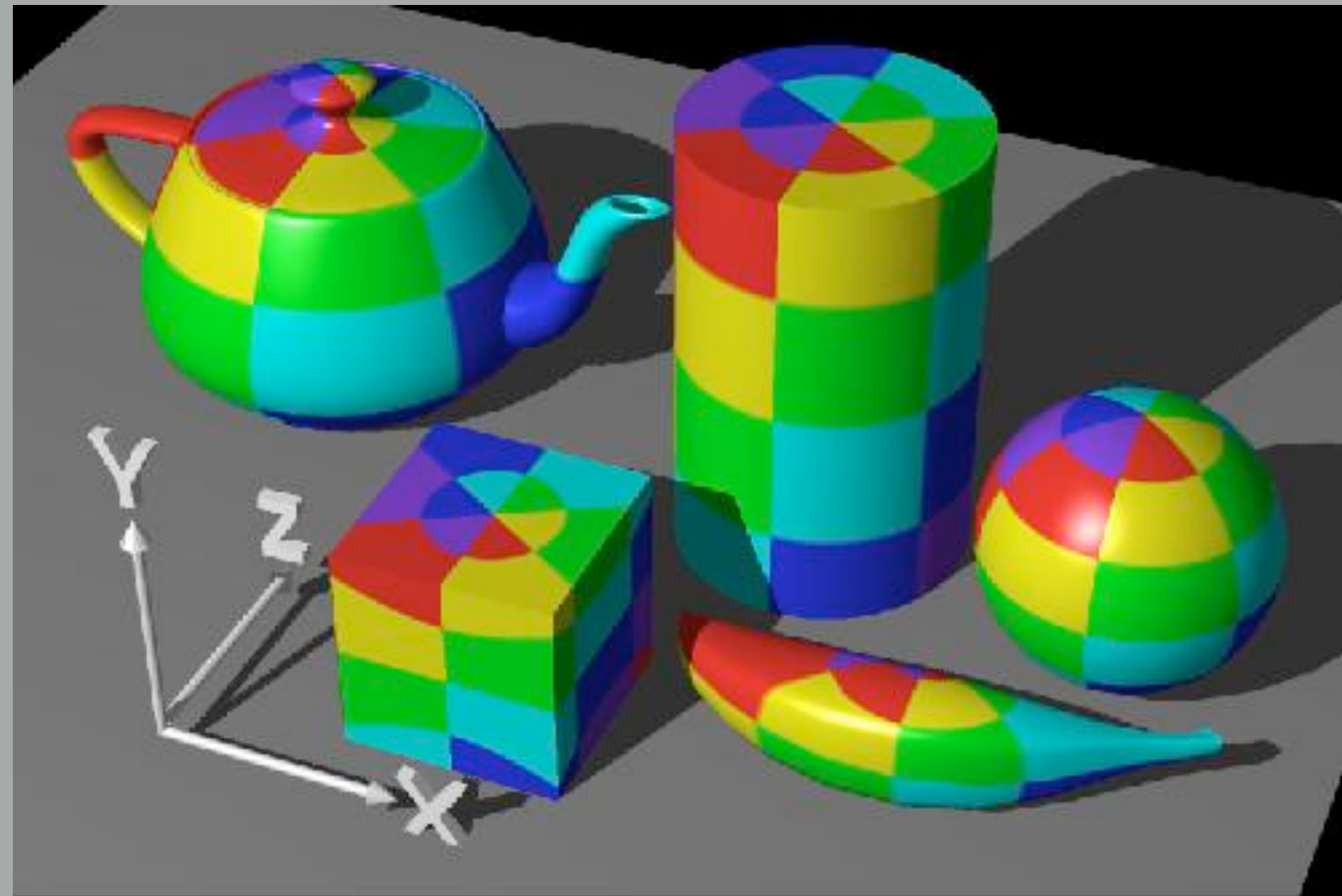
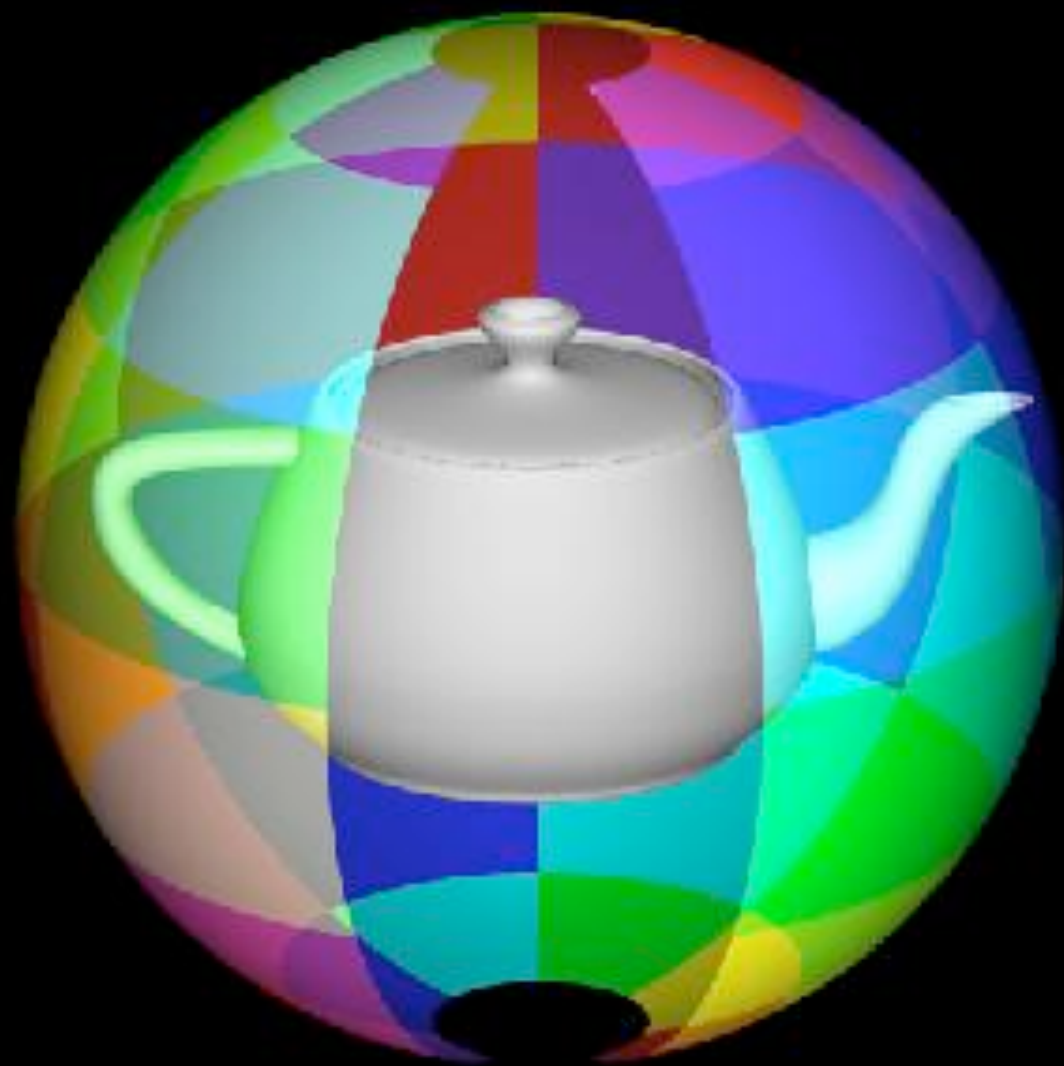


Rosalee Wolfe

http://www.siggraph.org/education/materials/HyperGraph/mapping/r_wolfe/r_wolfe_mapping_1.htm

Examples of Texture Coordinate Functions

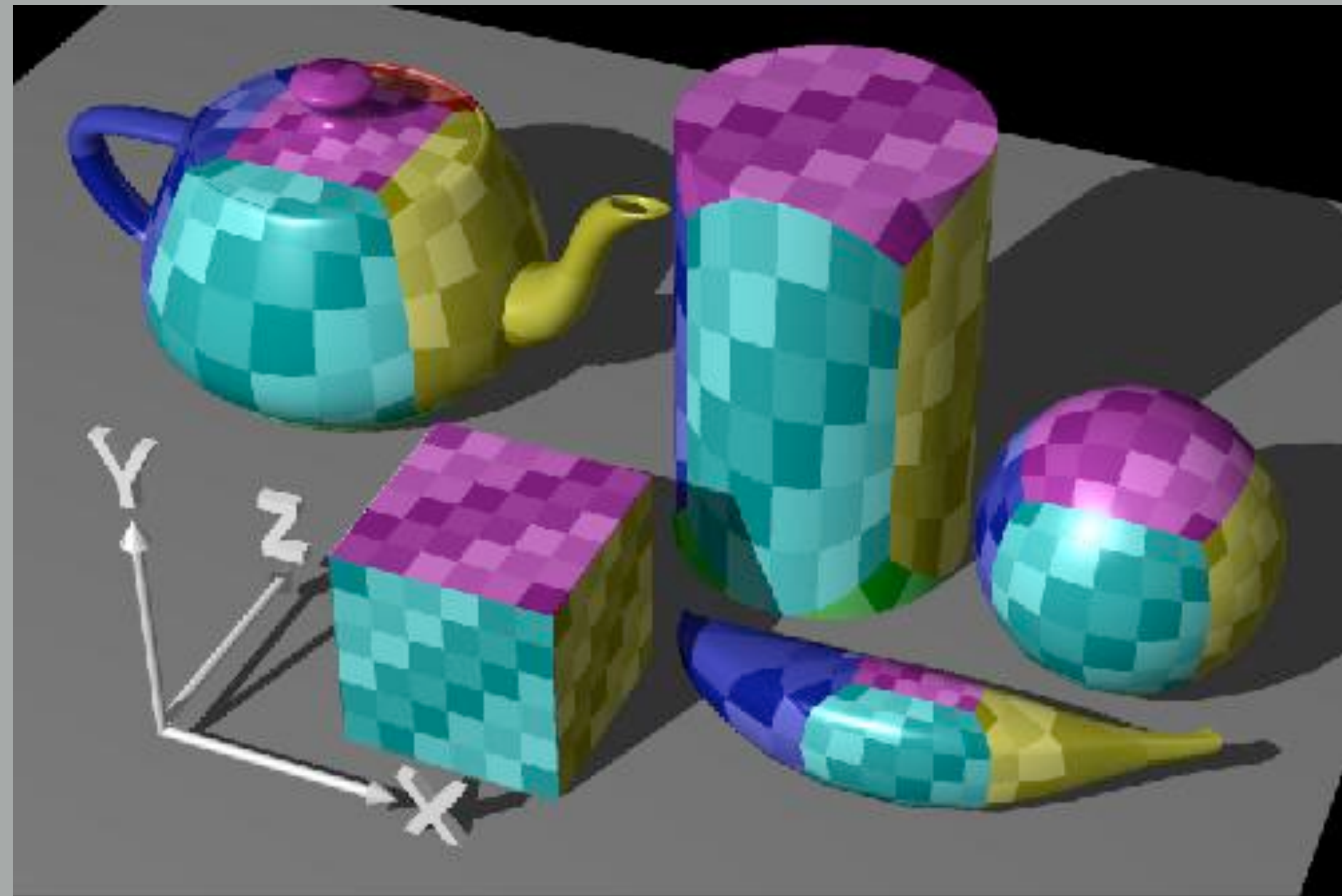
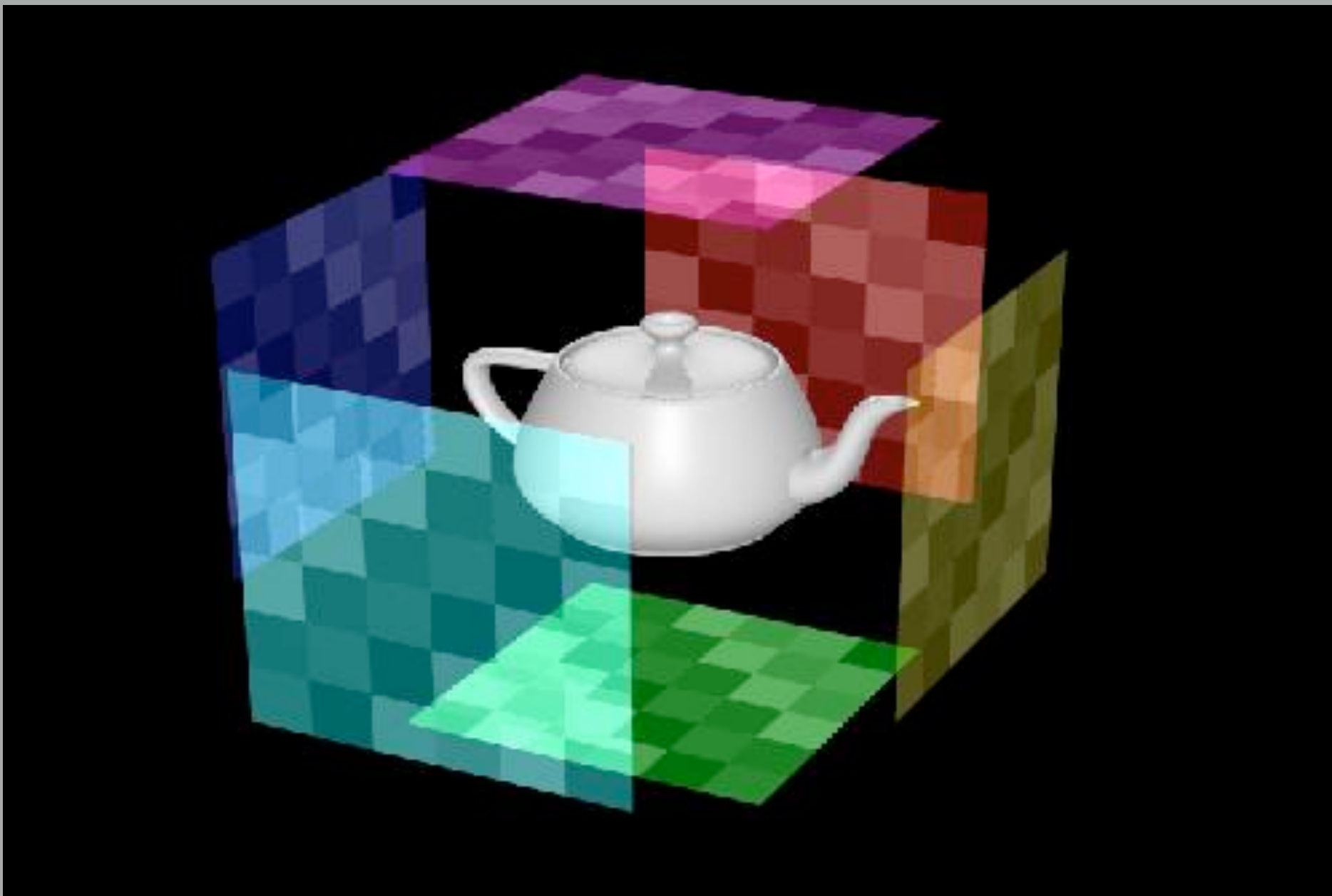
Spherical projection



Rosalee Wolfe

http://www.siggraph.org/education/materials/HyperGraph/mapping/r_wolfe/r_wolfe_mapping_1.htm

Examples of Texture Coordinate Functions

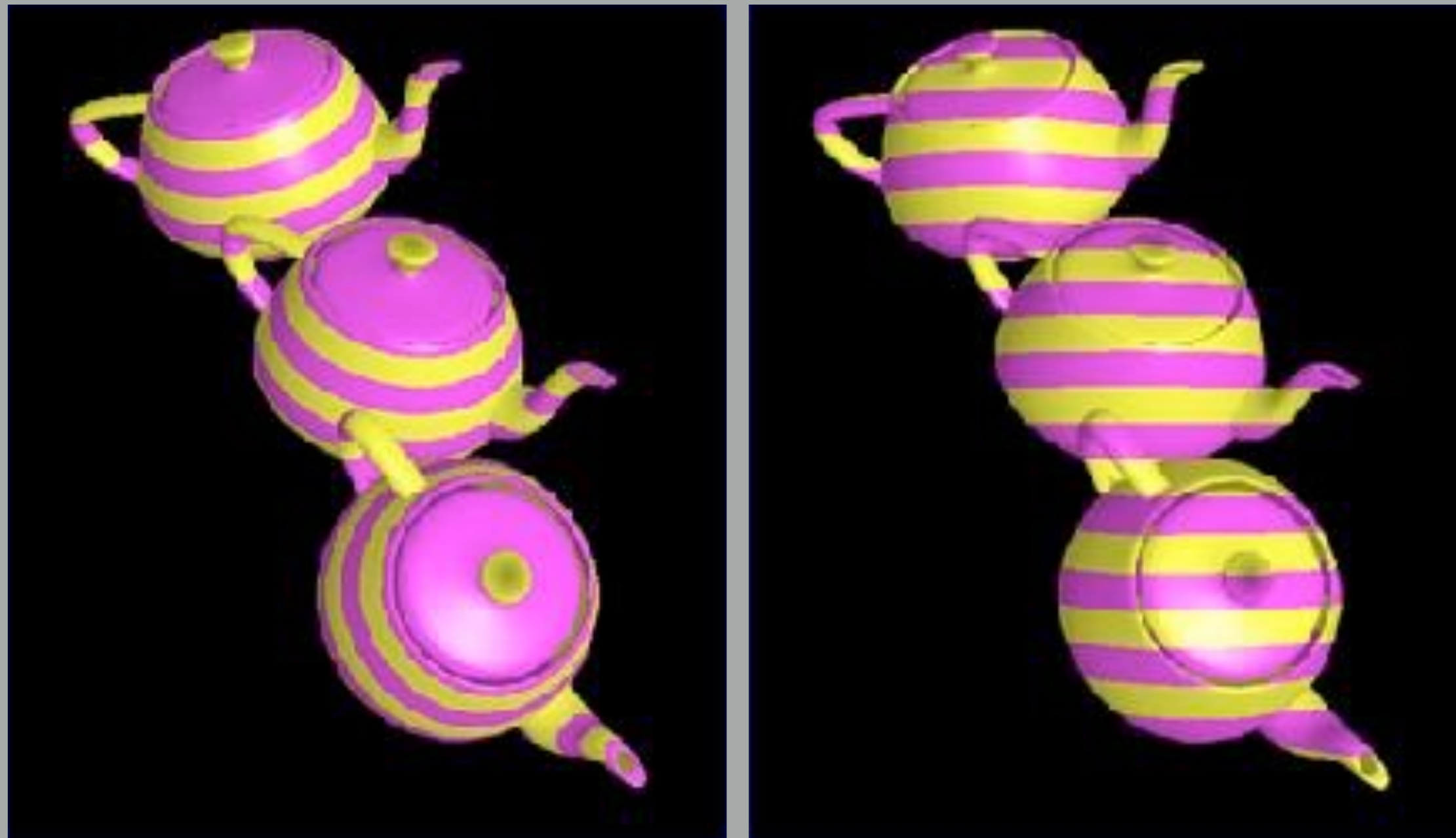


Rosalee Wolfe

http://www.siggraph.org/education/materials/HyperGraph/mapping/r_wolfe/r_wolfe_mapping_1.htm

Examples of Texture Coordinate Functions

Function of object or world coordinates?

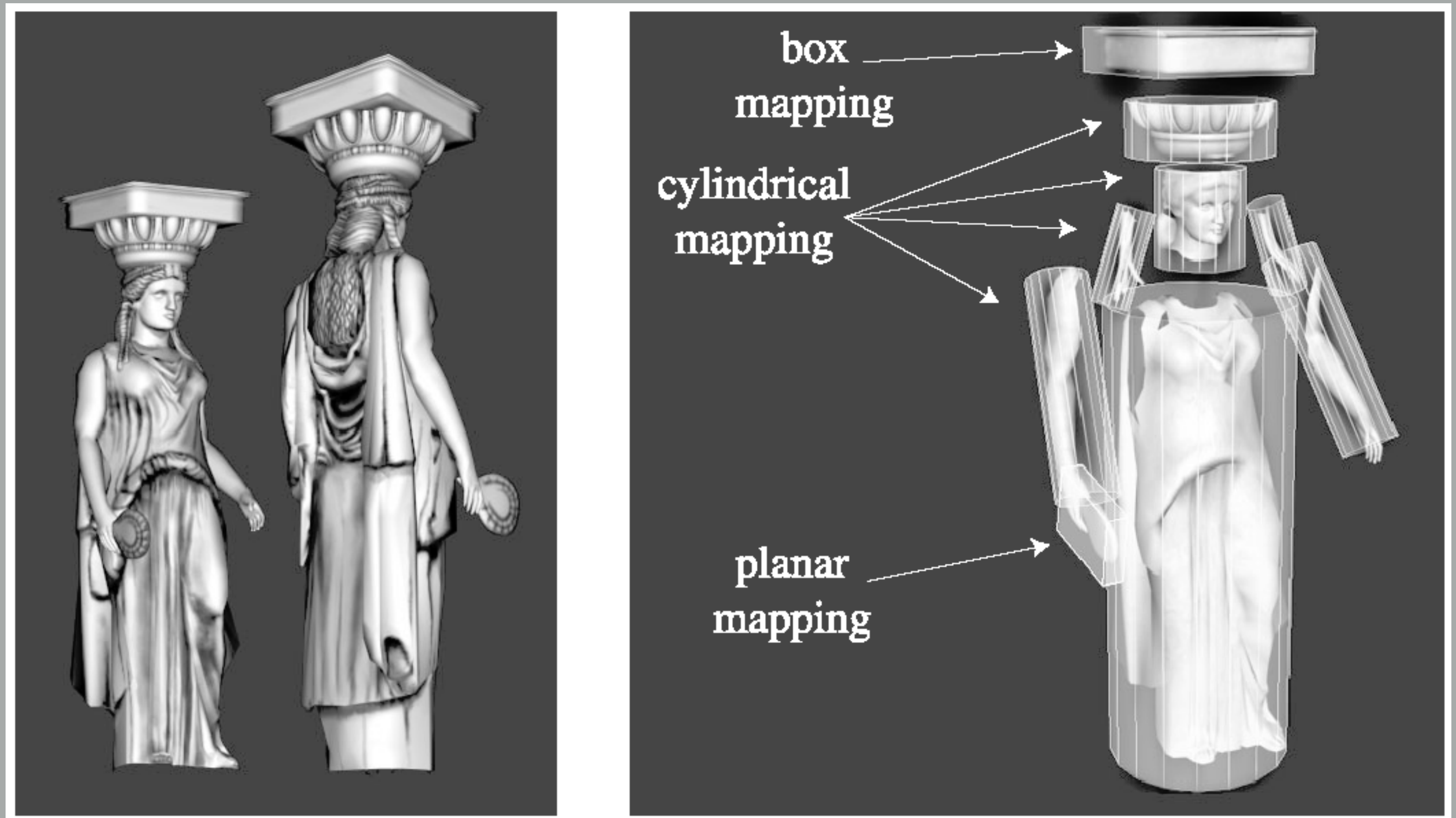


Rosalee Wolfe

http://www.siggraph.org/education/materials/HyperGraph/mapping/r_wolfe/r_wolfe_mapping_1.htm

Examples of Texture Coordinate Functions

Complex surfaces: project parts to parametric surfaces



[Tito Pagan]